### Wissenschaftliches Arbeiten Part 2 with CG Group 193.052, SS 2021, 2.0h (3 ECTS)

Philipp Erler

https://www.cg.tuwien.ac.at/staff/PhilippErler.html

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Institute of Visual Computing & Human-Centered Technology
TU Wien, Austria



#### Organization



- Organization via TUWELTODO
- General information on LVA site https://www.cg.tuwien.ac.at/courses/WissArbeiten/SE/2021S
- Topics and organization are presented today
- Topic selection in TUWEL -> fixed by end of the week

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#### Goals

3



- Practice selecting, reading and understanding
  - Search and select papers relevant to your topic
  - Summarize them as a state-of-the-art report
  - Prepare a talk about your topic in the seminar

■ This permits in-depth familiarization with the topic



#### Tasks



- Submit a literature list
  - Chosen with supervisor
- Attend 3 lectures
- Meetings with supervisor
  - paper selection
  - discussion of papers
  - preparing talk slides
- Alternative: evaluate and compare algorithms
- Final presentation in seminar



#### Literature List



- Analyze recent papers (select with supervisor)
- Study secondary literature to understand topic
- How to find relevant papers:
  - Google Scholar: key words and operators
  - Digital libraries: IEEE, ACM, ...
  - Survey papers, often-referenced papers
  - Skim the papers at least
- Submit a list of ca. 10 papers in TUWEL
   e.g. 8 technical papers + 2 survey papers or text books
  - → official registration (CG seminar)



#### State-of-the-Art Report (STAR)



- LaTeX template
  - Information on course website
  - Overleaf reference project available to copy
- Submit the paper in PDF format in TUWEL
- First submission must be complete
  - Min. 8 pages, preferably in English
  - All papers mentioned and complete structure
  - This version will be reviewed but not graded
- Start early! Plan at least 4 weeks for reading and writing.

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#### Scientific Review



- You will get the first submission of another student to review
- Typical conference review form (Eurographics)
- This helps author to improve the manuscript
- Guides on review writing on course website
- You will receive 2 reviews (student, supervisor)
- Improve final report (camera-ready submission) according to reviews
- Plagiates -> Fail! Institute Guidelines



#### **Seminar Presentations**



#### Duration:

- depending on number of students
- 10-15 minutes presentation +3-5 minutes discussion
- Presentation (preferably in English)
  - Prepare slides in advance, using template
  - Focus is on overview/comparison of methods
  - Present so that other students will understand it
  - Submitted slides are presented on seminar PC via Zoom
  - Recorded video + live Q&A
- Active discussion is mandatory and graded



#### Dates



- Rough overview, see LVA page for details
- 3 weeks for meeting supervisor and literature list
- 7 weeks for report
  - 3 lectures of 2h during this time
  - Start early!
- 1 week for reviews
- 2 weeks for presentation preparation and final paper



#### Grading



■ Grades: 1: >88%, 2: 75%, 3: 63%,

4: 50%, 5: <50%

Every submission must be 4 or better, otherwise 5 overall

- Late submission:
  - -1 point per started hour
    - -> fail course after 50h
  - You will delay the next task for everyone!

Task	Point
Lecture	
attendance	5
Review	20
Presentation	30
Participation in	
discussion	5
Final report	40

Sum



100

CG Seminar 10

#### **Topic Presentation**



- Now, topics will be presented
- Topic assignment:
  - Non-binding poll to find most-wanted topics
  - Short discussion (to resolve conflicts)
  - Activate group choice in TUWEL -> first come, first serve
  - Switching is possible until the end of the week
  - Double assignment or groups if more students than topics

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Topic is Detailed 3D Gity Models
Topic is Trom last semester

Visualizing cities based on available data

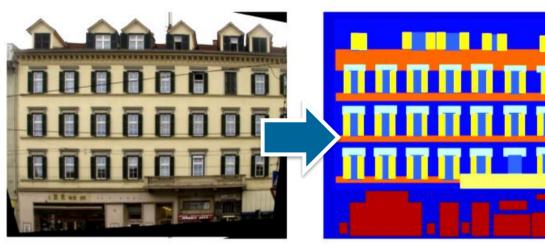
How is the geometry obtained?

- How does texturing work?
- Commonly used solutions (CityGML, etc.)?
- What are their strengths and weaknesses?

Special focus: using machine learning to augment data with additional

information from available images

- How many floors?
- How many windows/doors?
- Where are they?
- Color, style?

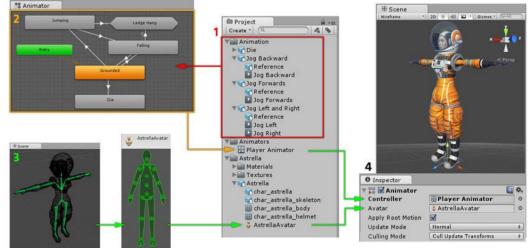




### Topic Modern Character Animation Systems 1001C IS FORMULAST Semieste

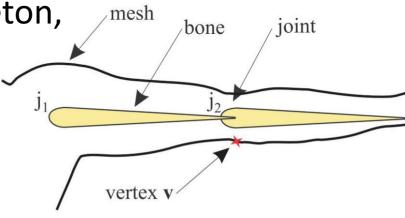
 A modern animation system must be able to consider multiple methods at runtime:

- Key-framed animations
- Inverse kinematics
- Animation blending
- Animation masks and partial updates



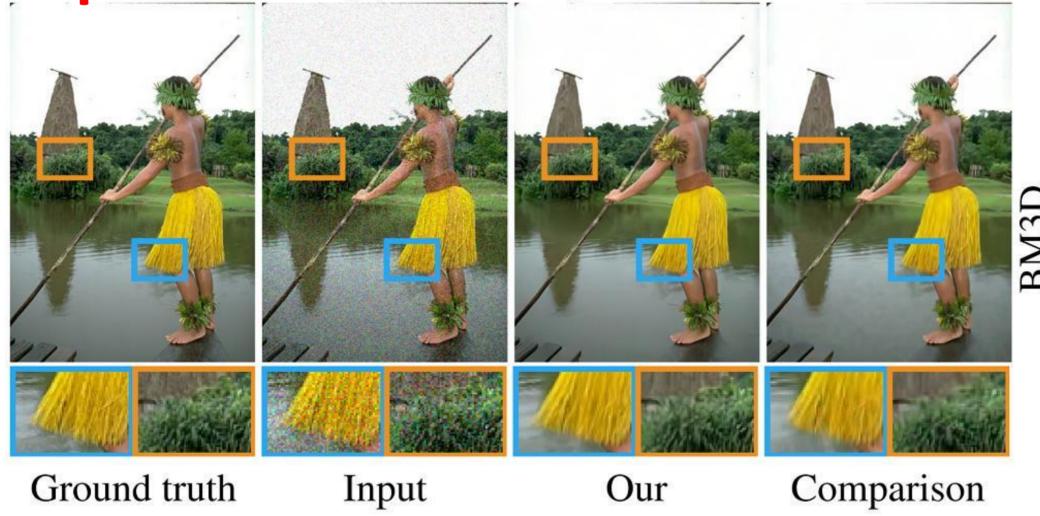
 Special focus: If we animate a character with a skeleton, mesh vertices should move with close-by bones

- Linear Blend Skinning
- Spherical Blend Skinning
- Dual Quaternion Skinning
- How do these work and which one works best?





## ToolCIS (a) Gaussian (SISS) Semestering (a) Gaussian (SISS) Semestering (a) Caussian (SISS) Semestering (BISS)



LEHTINEN, Jaakko, et al. Noise2noise: Learning image restoration without clean data.



Adam Celarek 14

### Convolutional Deep Learning Networks for 3d Data ODIC S HOME AST SEMESTE



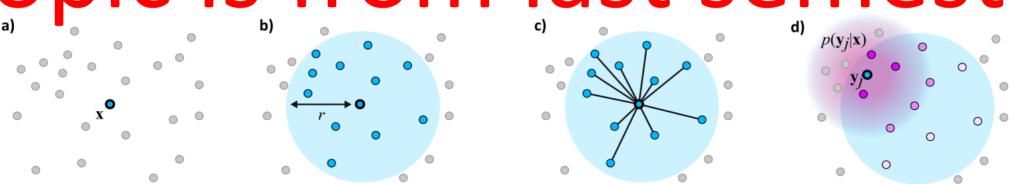


Fig. 4. Steps of our MC convolution. For a given point  $\mathbf{x}$  (a) the neighbors within the receptive field r are retrieved (b) to be used as Monte Carlo integration samples (c). For each neighboring point  $\mathbf{y}_j$ , its probability density function,  $p(\mathbf{y}_j | \mathbf{x})$ , is computed using *Kernel Density Estimation* [Parzen 1962; Rosenblatt 1956] (d). Based on the bandwidth used (pink disk), the neighboring points have different effects on the computation of  $p(\mathbf{y}_j | \mathbf{x})$  (pink gradient).



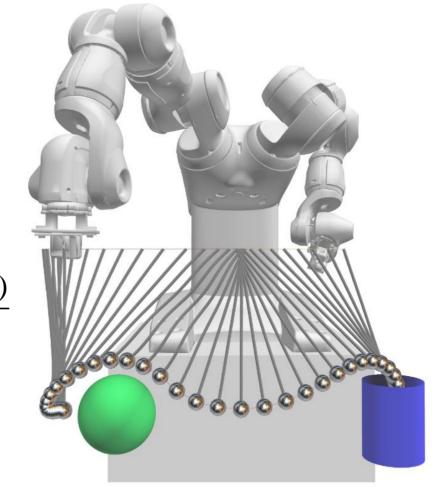
Fig. 9. Comparison of our segmentation result for uniform (second row) and non-uniform samplings (third row) to the ground truth (first row). Non-uniform sampling use the Gradient (first and second columns), LAMBERT (third and fourth columns), and SPLIT (fifth and sixth columns) protocols.

HERMOSILLA, Pedro, et al. Monte carlo convolution for learning on non-uniformly sampled point clouds

### Topic is Differentiable Simulation Topic is Trom last semester



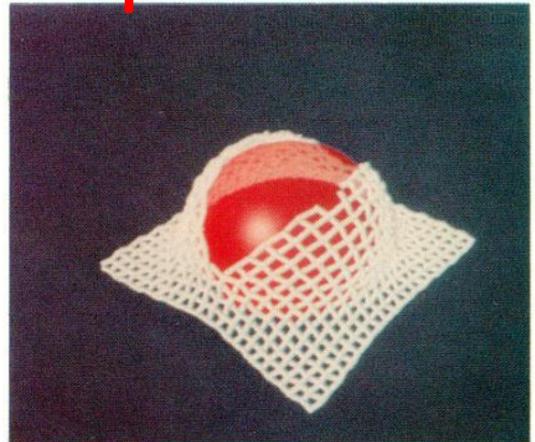
 $\frac{d\,\Phi(\boldsymbol{x}(\boldsymbol{q}))}{d\,\boldsymbol{q}}$ 



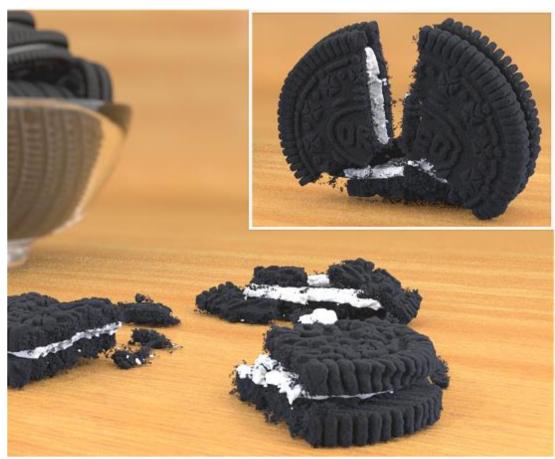
Liang et al., Differentiable Cloth Simulation for Inverse Problems. Advances in Neural Information Processing Systems 32 (2019) Zimmermann et al., PuppetMaster: Robotic Animation of Marionettes. ACM Trans. Graph. 38, 4 (2019)



### Topic is fracture simulation semester and the semester of the



Terzopoulos and Fleischer, Modeling inelastic deformation: viscolelasticity, plasticity, fracture. Proceedings of the 15th Annual Conference on Computer Graphics and Interactive Techniques (1988)



Wolper et al., CD-MPM: Continuum Damage Material Point Methods for Dynamic Fracture Animation. ACM Trans. Graph. 38, 4 (2019)



David Hahn 17

# TO DIC IS I TO THE SECOND TO SECOND TO THE CONDUCT A SURVEY OF RECENT

Conduct a survey of reconducts in real-time global illumination





Christian Freude 18

Topic is finverse Rendering Semester Sendering Conduct a survey on recent

advances in inverse rendering.





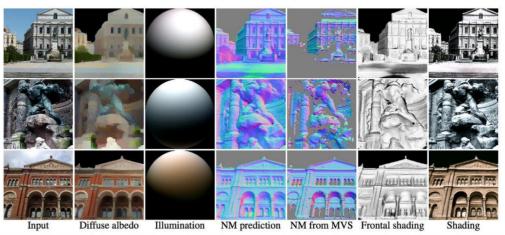


Figure 1: From a single image (col. 1), we estimate albedo and normal maps and illumination (col. 2-4); comparison multiview stereo result from several hundred images (col. 5); re-rendering of our shape with frontal/estimated lighting (col. 6-7).



Christian Freude 19

## Topic is from last semester Wind Direction







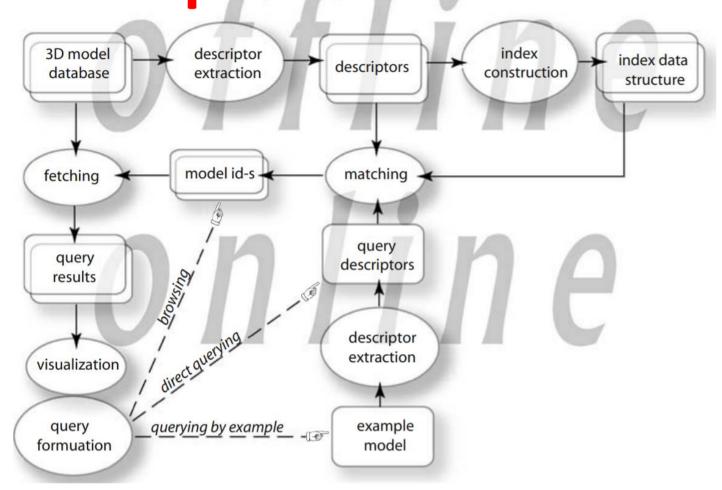
Pirk, Sören, et al. "Windy trees: computing stress response for developmental tree models." *ACM Transactions on Graphics (TOG)* 33.6 (2014): 1-11.



Chao Jia 20

### Topic is from last semester TU

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Tangelder JW, Veltkamp RC. A survey of content based 3D shape retrieval methods. Multimedia tools and applications. 2008 Sep;39(3):441-71.



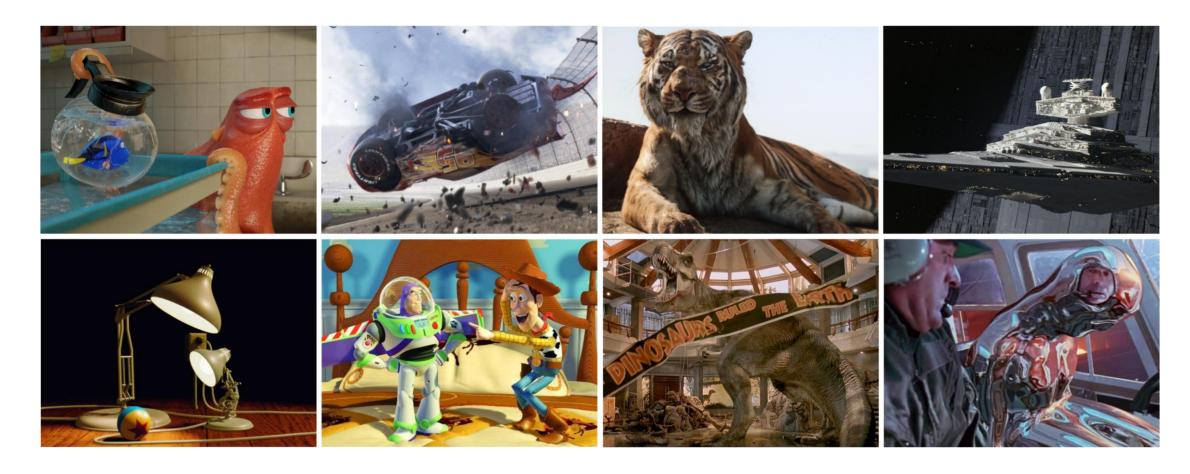
Bronstein, Alexander M., et al. "Shape google: Geometric words and expressions for invariant shape retrieval." *ACM Transactions on Graphics (TOG)* 30.1 (2011): 1-20.



Eitz, Mathias, et al. "Sketch-based shape retrieval." *ACM Trans. Graph.* 31.4 (2012): 31-1.

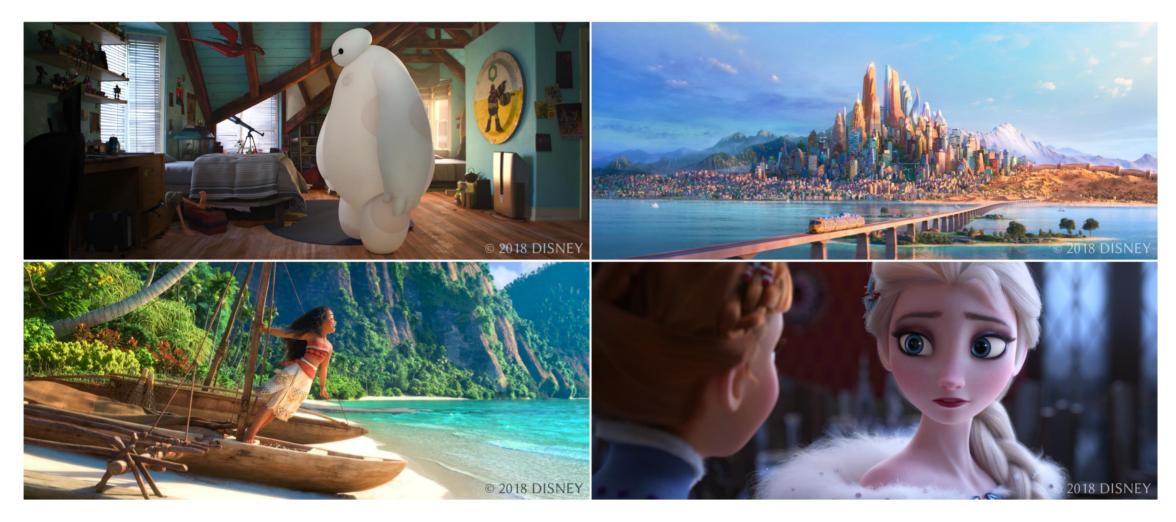


# The Technology Behind Pixar Films Provide an overview of the technology behind Pixar films



Hiroyuki Sakai 22

# The Technology behind Disney Films Provide an overview of the technology behind Disney films

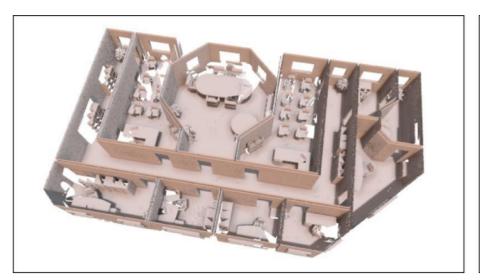


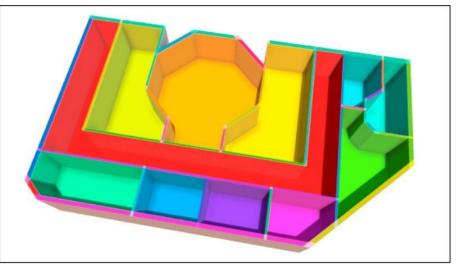
Hiroyuki Sakai 23



## TODIC S TO 1 a SUBSET of 3D reconstruction of Buildings Subset of 3D reconstruction from point clouds

- Obtain a polygonal model with sharp features





Sebastian Ochmann, Richard Vock, Reinhard Klein, "Automatic reconstruction of fully volumetric 3D building models from oriented point clouds", ISPRS Journal of Photogrammetry and Remote Sensing, 2019.

24 **Philipp Erler** 



### Topic Strom last semeste

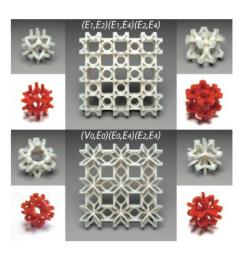
#### Generating mesoscale structures with target elastic properties



Panetta et al., 2017



Martínez et al., 2016



Panetta et al., 2015

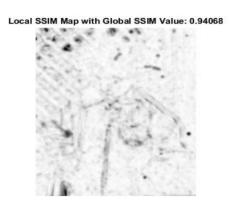


Ildar Gilmutdinov 25

### Topic Is Trom ast Semeste

Processing and compression of video or image files can result in a degradation of the original visual quality. The student will search for existing methods that, given a ground truth file and potentially degraded file, measure the amount of degradation on at a given pixel/point in time.





Suggested citation: Zhang X, Lin W, Xue P. Just-noticeable difference estimation with pixels in images. Journal of Visual Communication and Image Representation. 2008 Jan 1;19(1):30-41.

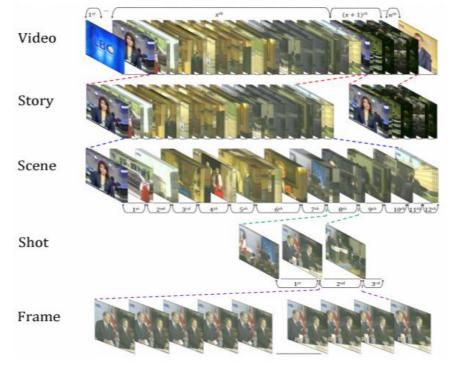
Joao Cardoso 26



### Automated Film Metadata Generation

A lot of information about a video, such as multiple shots or camera movement is immediately obvious to humans. For computers however, it is not explicitly stated in the pixel data.

The student will search for existing methods that process the video data and attempt to predict new abstract information about it.



Suggested citation: Abdulhussain SH, Ramli AR, Saripan MI, Mahmmod BM, Al-Haddad SA, Jassim WA. Methods and challenges in shot boundary detection: a review. Entropy. 2018 Apr;20(4):214.

27 Joao Cardoso



### GPU-Pased Neighborhood Search

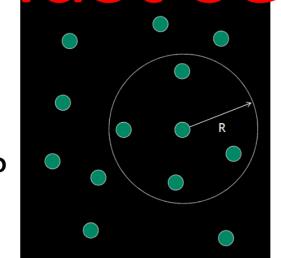
■ This is all about **GPU**-algorithms!

Given a large amount of particles,
 e.g. N >> 100k, how to efficiently
 find the neighbors of each particle?

Research different approaches

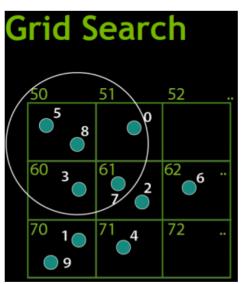
Start with the "oldie but goldie" by Simon Green: Particle Simulation using CUDA

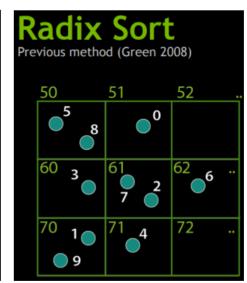
- Describe how Counting Sort works (by Rama C. Hoetzlein)
- Anything more advanced?

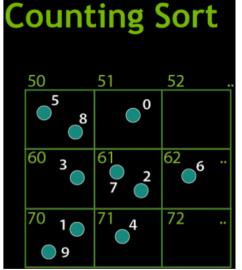


Here's your objective:

Find all neighboring particles in a fixed radius R!









## TODIC STOMAST Semeste This is all about algorithms,

This is all about algorithms, which are either severely RTX-accelerated or only possible with RTX-acc. at real-time frame rates (60Hz).

"RTX" here means: GPU-accelerated Real-Time Ray Tracing using new hardware-features such as the RT-cores introduced with NVIDIA Turing.

- Two examples of suitable publications on the right →
- None of your references can be older than 2018 「\\_(ッ)\_/ NVIDIA Turing was introduced in 2018.
- Find great RTX algorithms!



Adaptive Temporal Anti-Aliasing by Marrs et al.

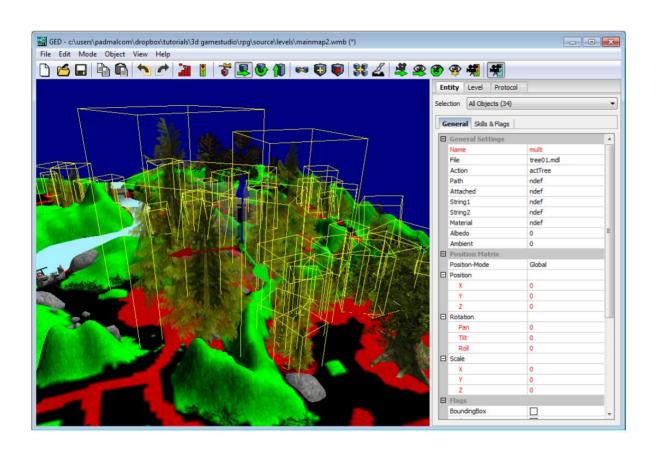
Ray-Guided
Volumetric Water
Caustics in Single
Scattering Media
with DXR
by Holger Gruen

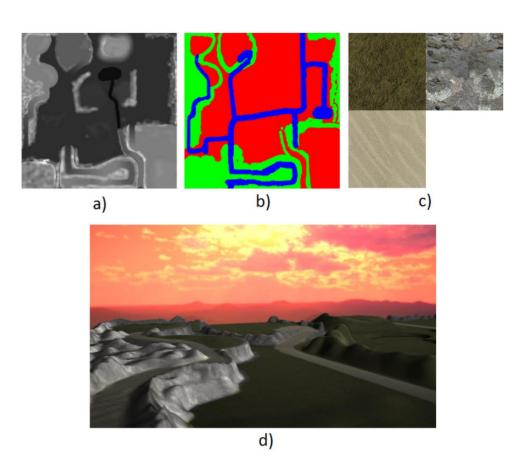




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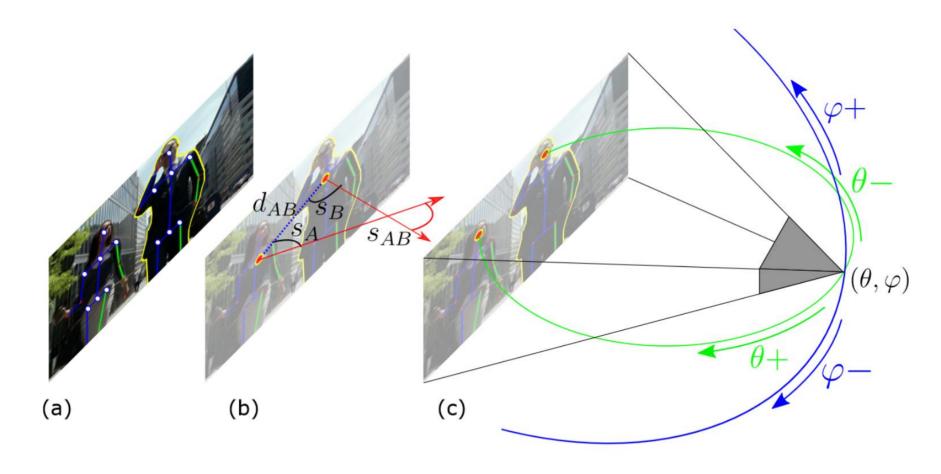
Freiknecht J, Effelsberg W. A Survey on the Procedural Generation of Virtual Worlds. Multimodal Technologies and Interaction. 2017; 1(4):27.

Manfred Klaffenböck 30



### Topic is 35 Pose Reconstruction Topic is 170 m last semeste

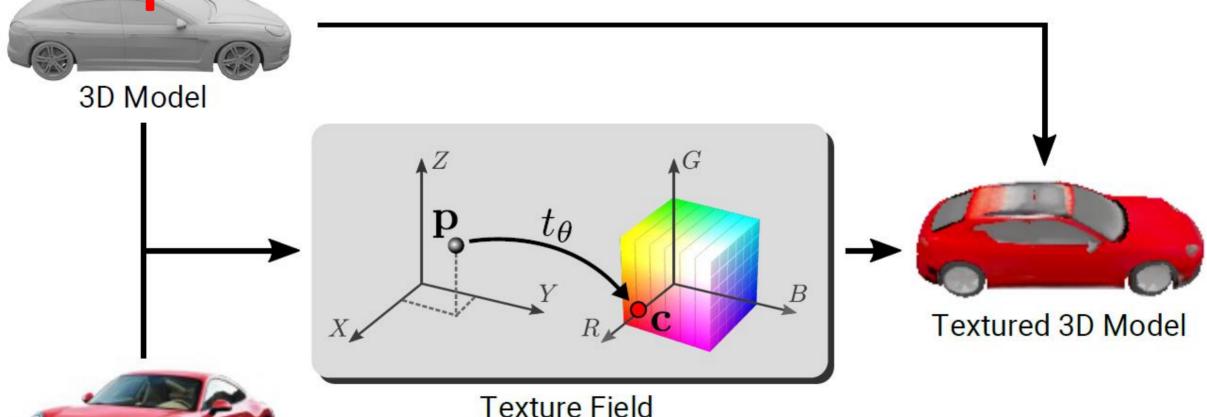




Hongda Jiang, Bin Wang, Xi Wang, Marc Christie, and Baoguan Chen. 2020. Example-driven virtual cinematography by learning camera behaviors. ACM Trans. Graph. 39, 4, Article 45 (July 2020), 14 pages.



### Topic is from last semester



2D Image

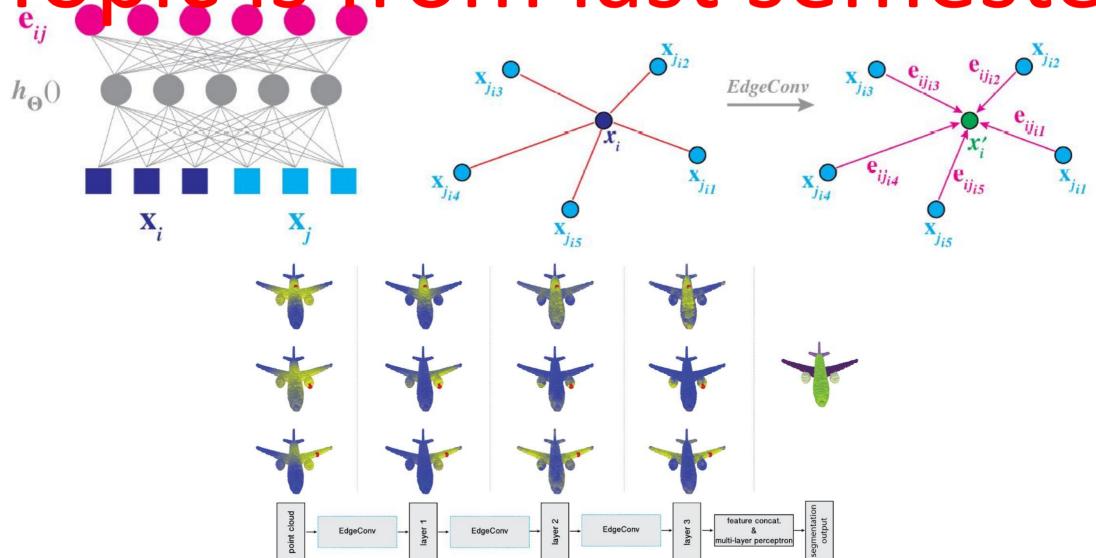
Oechsle, Michael, et al. "Texture fields: Learning texture representations in function space." *Proceedings of the IEEE International Conference on Computer Vision*. 2019.

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Philipp Erler 32

#### TU

### Topic is from last semester





## Classify Objects in Point Clouds ODIC S HOH LAST SEMESTE Machine learning algorithms for 3D scanned data

- Detect partial objects and their pose (location+orientation in 3D)

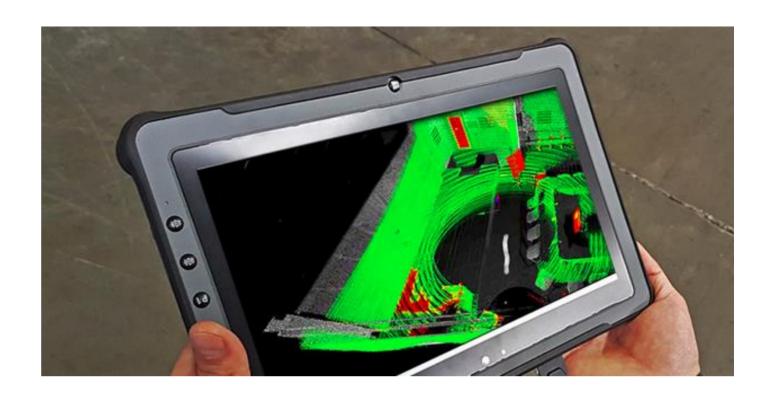




Stefan Ohrhallinger

## Real-time Change Detection O D C S TO TO TO S S E Mester Mobile App shows AR changes to scanned 3D model in real-time

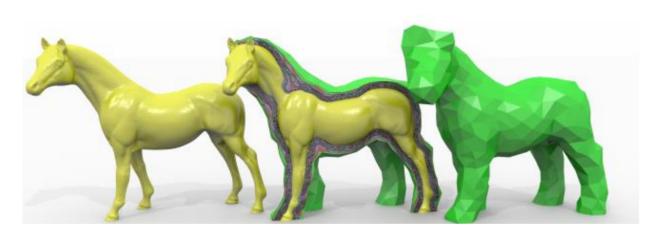
- Requirements:
- 3D Occupancy Maps
- Sensor noise tolerance
- Clustering segments
- Real-time performance



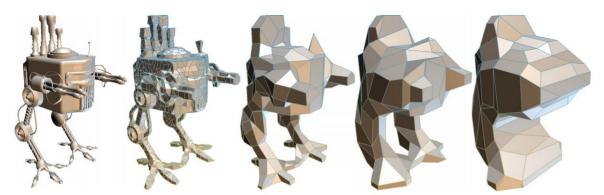


35 Stefan Ohrhallinger

## TODIC STOM ast Semester Review different approaches

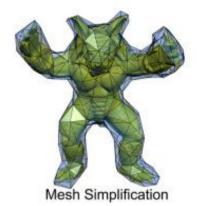


Sacht et al. "Nested Cages." ACM Trans. (TOG). ACM, 2015.



Calderon et al. "Bounding Proxies for Shape Approximation." ACM Transactions on Graphics (TOG). ACM, 2017.







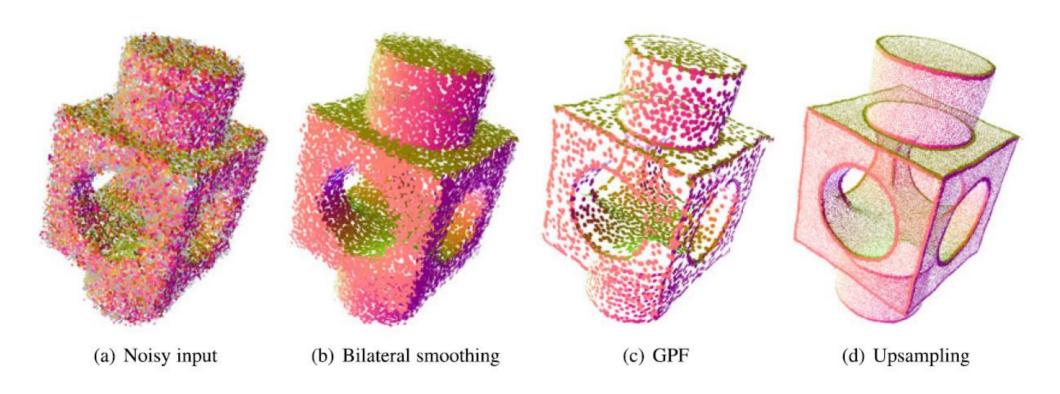


Le and Deng. "Interactive Cage Generation for Mesh Deformation." ACM SIGRAPH SI3D, 2017.

**Mohamed Radwan** 36

## Resampling Noisy Point Sets TODIC IS TOTAL AST SEMESTE Challenges: noise, missing data, sharp features

- Review recent approaches



Lu et al. "GMM-Inspired Feature-Preserving Point Set Filtering." IEEE Trans. on Visualization and and Computer Graphics. 2018.



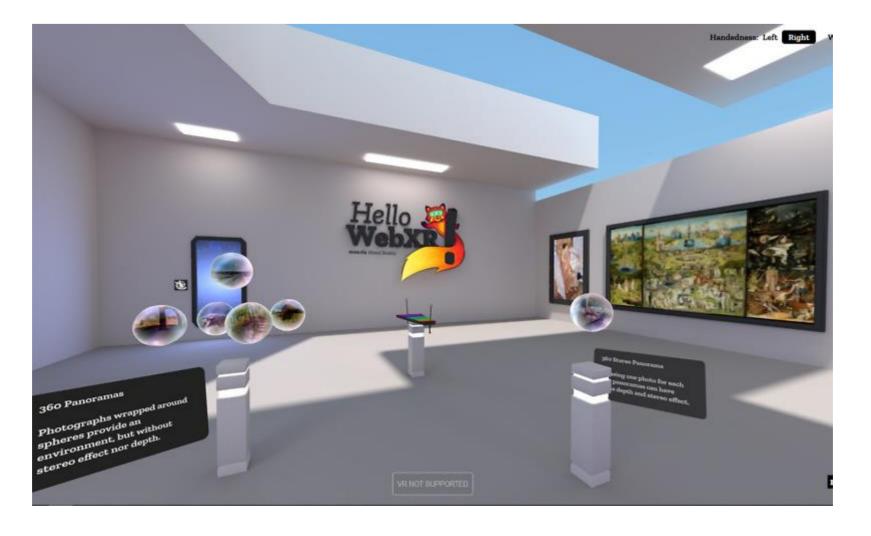
# TODIC IS TOMINAST SEMESTE Research publications implemented in WebGL / WebGPU





Markus Schütz 38

# TODIC IS TO MebVR / WebXR Research publications implemented in WebVR / WebXR





39 Markus Schütz

#### **Topic Assignment**



- Deep Learning Based Noise Reduction in Rendering
- Convolutional Deep Learning Networks for 3d Data
- 3. Detailed 3D City Models
- Modern Character Animation Systems
- 5. Differentiable Simulation
- 6. Fracture simulation
- 7. Global Illumination in Real Time 20.
- 8. Inverse Rendering
- Tree Animation
- 10. Shape Retrieval
- 11. The Technology Behind Pixar Films
- The Technology behind Disney Films
- 3D Reconstruction of Buildings

- 14. Computational Metamaterials
- 15. Video and Image Quality Metrics
- 16. Automated Film MetadataGeneration
- 17. GPU-Based Neighborhood Search
- 18. RTX-Accelerated Algorithms
- 19. Procedural Generation of Cities and Landscapes
- 20. 3D Pose Reconstruction
- 21. Colored Reconstruction
- 22. Graph-CNN
- 23. Classify Objects in Point Clouds
- 24. Real-time Change Detection
- 25. Multi Scale Bounding Cages
- 26. Resampling Noisy Point Sets
- 27. WebGL / WebGPU
- 28. WebVR / WebXR

- Non-binding poll to show most-wanted topics
- Short discussion
- Activate group choice in TUWEL -> first come, first serve



#### **Next Steps**



- Contact your supervisor ASAP
- Find mail addresses here: <a href="https://www.cg.tuwien.ac.at/staff/">https://www.cg.tuwien.ac.at/staff/</a>
- Discuss literature list with your supervisor
- Submit the literature list in TUWEL

Questions?



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