# WIEN Informatics



## Interactive Visualization of Vector Data on Heightfields

Silvana Zechmeister Visual Computing

**TU Wien Informatics** 

Institute of Visual Computing & Human Centered Technology Research Unit of Computer Graphics Supervisor: Ao.Univ.Prof. Dipl.-Ing. Dr.techn. Eduard Gröller Assistance: Dipl.-Ing. Dr.techn. Daniel Cornel

### **Problem & Motivation**

The accurate visualization of huge amounts of georeferenced vector data on heightfields in real-time is a common problem in the field of geographic information systems (GIS). Vector data usually consist of lines and polygons, which represent objects such as roads and parks. The interactive exploration of these vector entities in large-scale virtual 3D environments and the resulting large

#### Contributions

- A new screen-based vector data visualization method, which...
  - ... is able to render large vector data sets
  - ... delivers interactive frame rates
  - ... is well suited for large-scale environments

zoom range pose an additional performance challenge for their visualization. Ensuring clear visibility of all objects of interest in overview and of their details in close-up views is difficult in such large-scale environments.

#### ... dynamically adapts lines to interactively changing views

... supports different polygon and line styles

#### **Visualization Process**

and

heightfield.



The input vector Different acceleration data structures are generated during data are lines preprocessing for the static and dynamic approach. For static lines polygons and polygons, the spatial domain is subdivided by a regular grid. Line defined by open segments and polygon quad-trees are assigned to grid cells and and closed 2D organized in bounding volume hierarchies (BVH). Dynamic lines are polylines and a matched to the terrain by subdividing and sampling the line segments on the heightfield to prepare them for dynamic updates.

The line segments from preprocessing are used to create approximate boxes to limit the area a line can cover. Accurate point-in-line tests determine all lines affecting a pixel, which are stored in linked lists.

A grid cell, corresponding BVH, and polygon quad-tree leaf node is detected by a pixel position to determine the pixel color for the static approach. For dynamic lines, the **per-pixel line list** has to be traversed for the pixel color.

