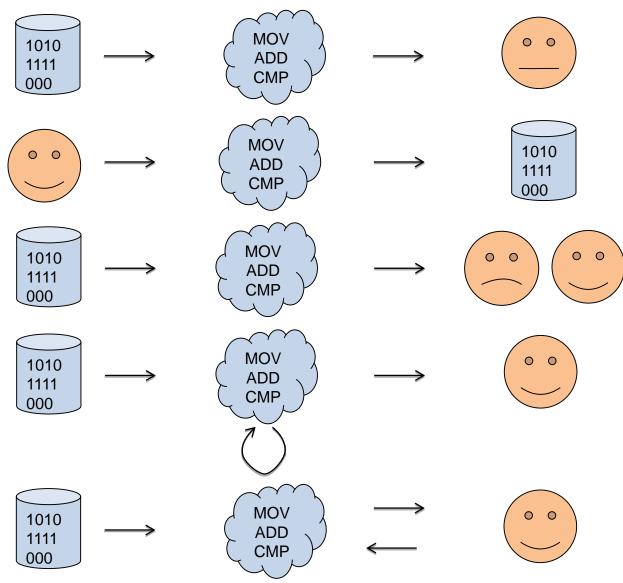
Declarative Visualization

Ivan Viola Vienna University of Technology Austria



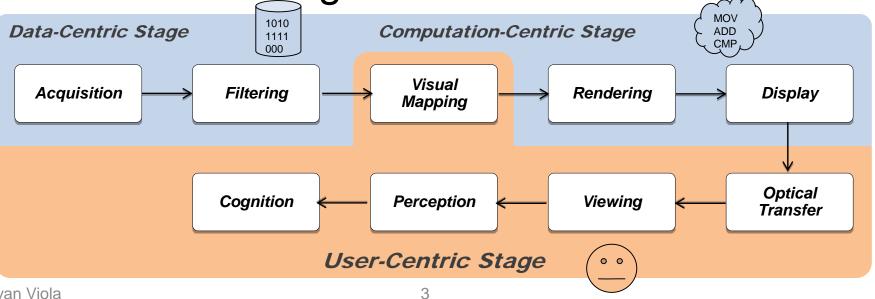
Pipeline Patterns



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Traditional Visualization Pipeline

- Aligned with the data-flow network
- Data is "thrown over fence" on visualizers
- Piped into visual representation
- Splatted on to the display
- Viewer is staring at it

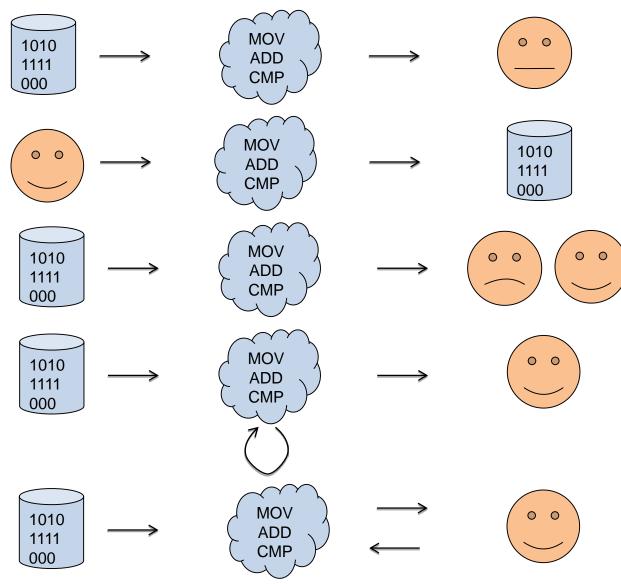


Direct Volume Rendering



- Imperative character
- Multitude of parameters to adjust (which could be automatized)
- Effect of parameter change is hard to predict

Pipeline Patterns



5

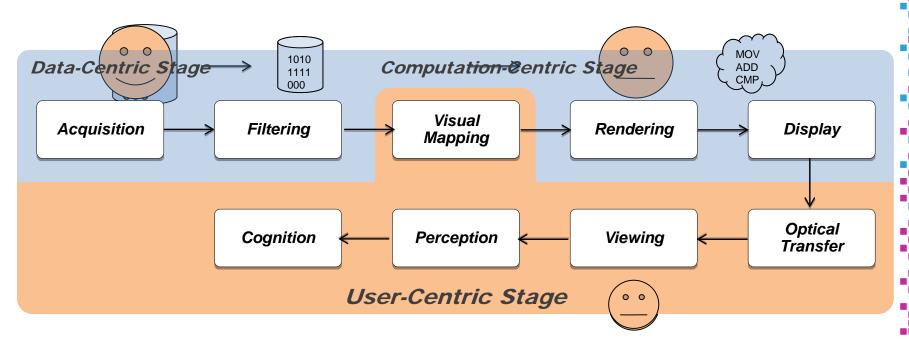
NIE N

Visualization Goal

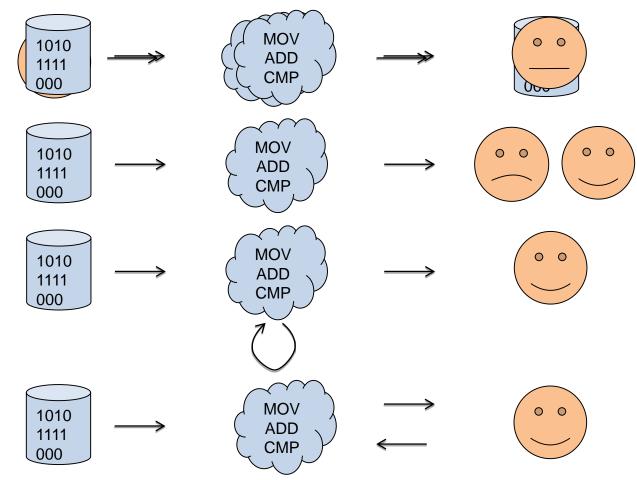
- Visualization is enabling technology
- Primary goal is to provide insight
- Exploiting perceptual / cognitive capabilities
- Specific tasks to reach the goal
- Strictly generic pipeline does not exist
- Common pattern: visual dialog: H⇔M⇔D
- Data: measurements, models, mental reps.
- Goal is the reason for visualization

Information Flow

- Imperative paradigm: Splat data on the user
- Declarative paradigm: User drives visualization of data

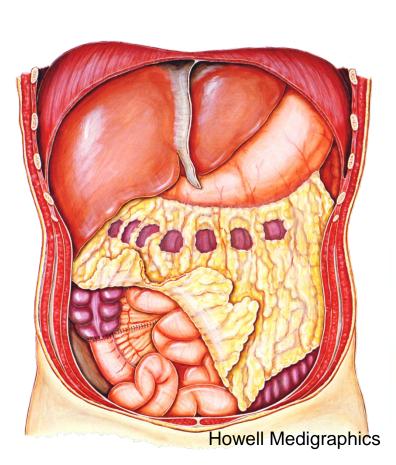


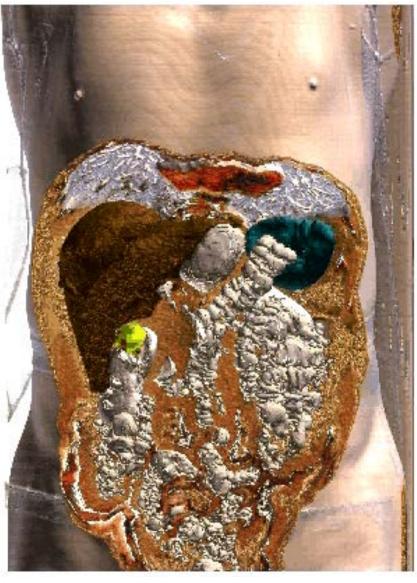
Pipeline Patterns





Importance-Driven Volume Rendering

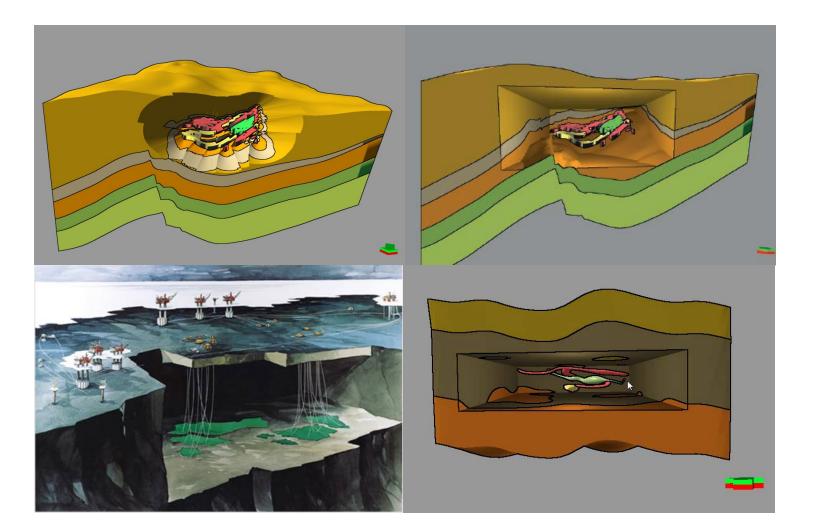




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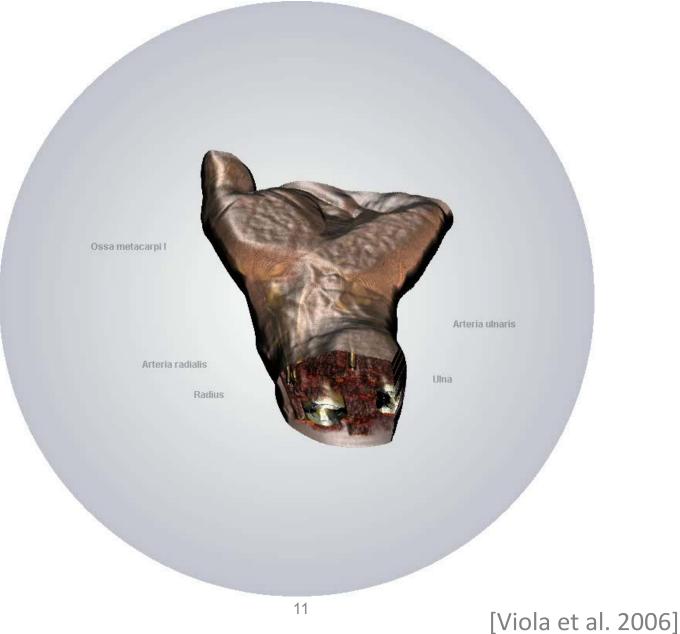
Design Guidelines for Geo-Cutaways





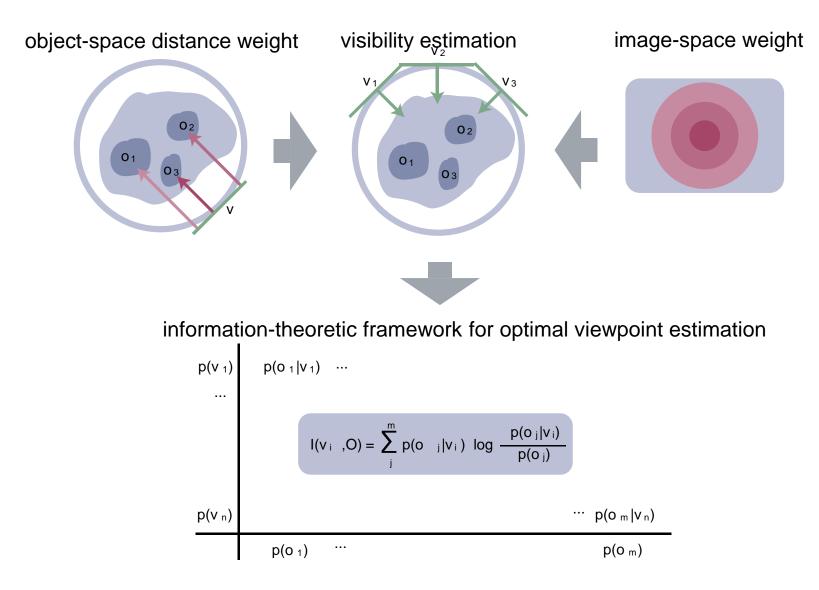
[Lidal et al. 2012]

Importance-Driven Focus of Attention



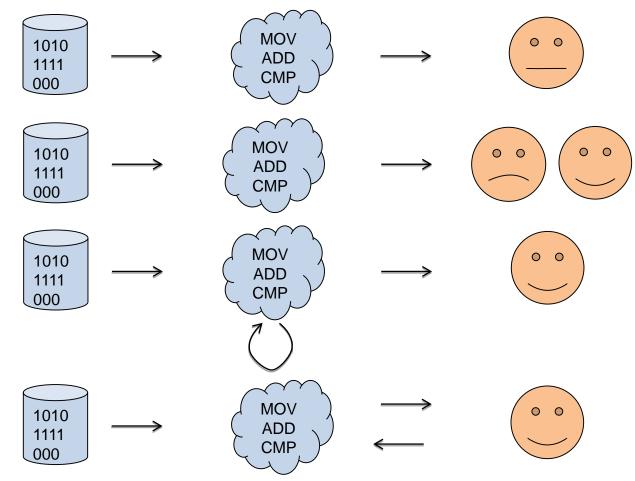
VIEN

Importance-Driven Focus of Attention



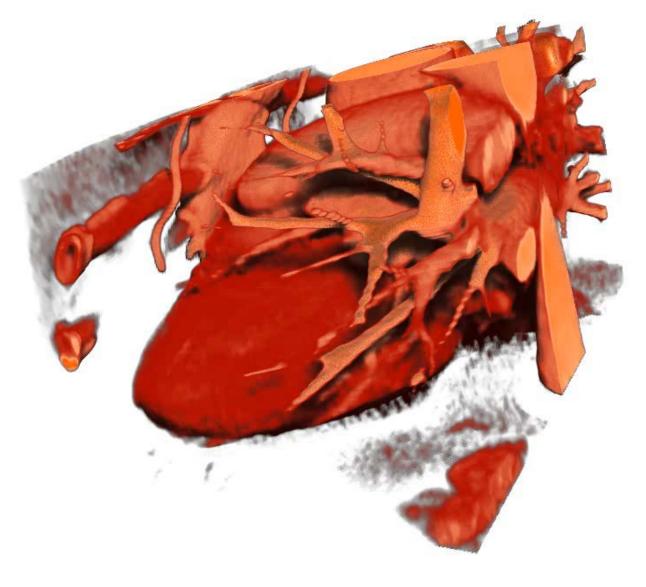
[Viola et al. 2006]

Pipeline Patterns





Occlusion Shading



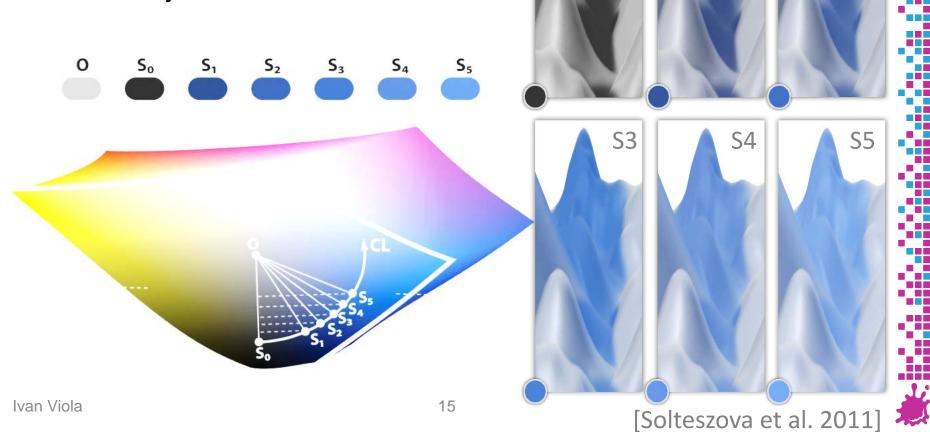
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Chromatic Shadows

 Constant perceptual distance between shadow color and object color



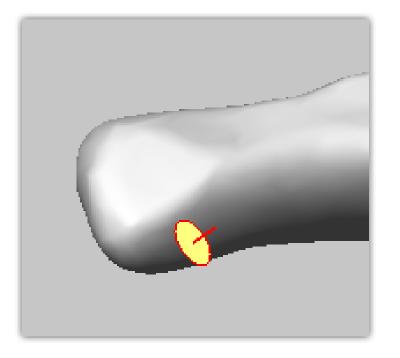
S0

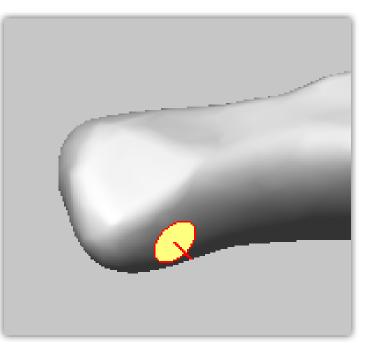
S1

S2

Assessment of Surface Perception

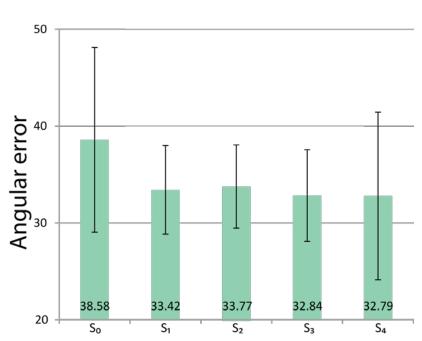
• Gauge figure task [Koenderink et al. '92]





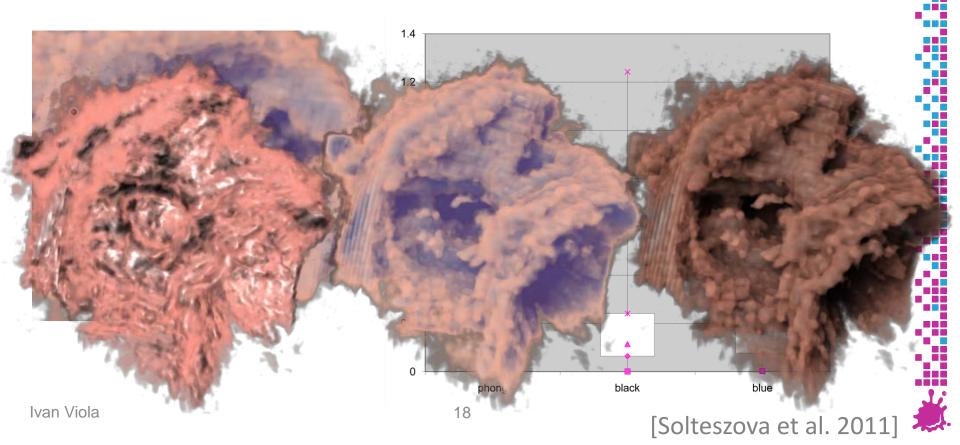
Experiment on Surface Perception

- Users rotated the gauge until it was perceived tangential to the surface
- Perceived and ground truth normal
- Tested shadow colors S0-S4 from the palette



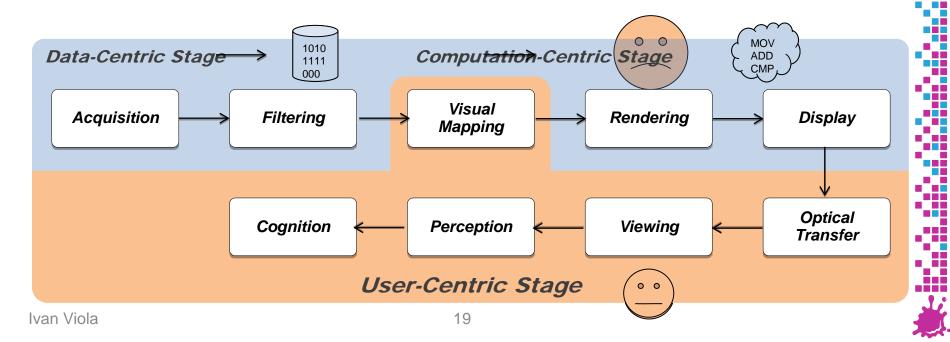
Experiment on Depth Perception

• Relative depth estimation of a yellow point with respect to the red and blue point

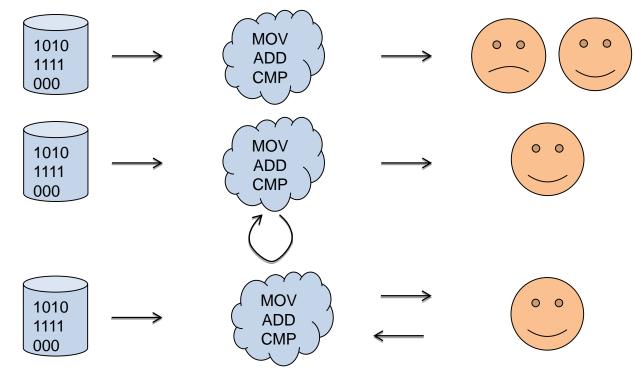


Traditional Role of Evaluation

- Final visual design is at the end evaluated
- The outcome can be...
 - positive or
 - negative...



Pipeline Patterns

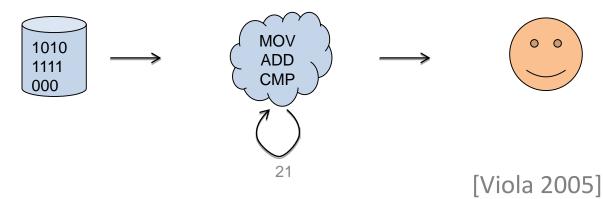




Importance-Driven Visibility

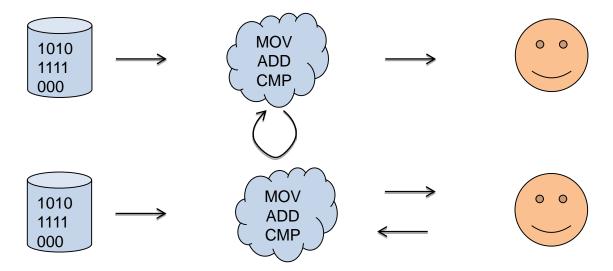


rind = iolit2ad; tpautps f=r0f.on, steereds = 0.15



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Pipeline Patterns



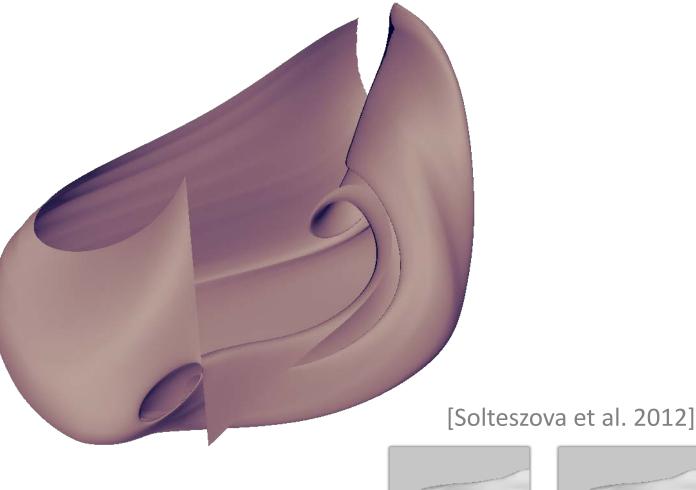


Iterative Visualization Redesign

- The goal is to provide most accurate match between information and its perceptual stimulus
- Iterative approach of visualization redesign

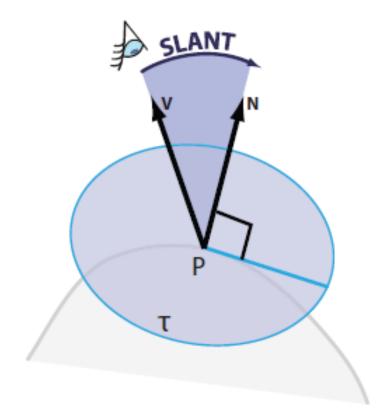
$$\begin{array}{c}
1010\\
1111\\
000
\end{array} \longrightarrow \qquad \left(\begin{array}{c}
MOV\\
ADD\\
CMP
\end{array} \right) \longleftrightarrow \qquad \left(\begin{array}{c}
\circ & \circ \\
\circ & \circ \\
\end{array} \right)$$

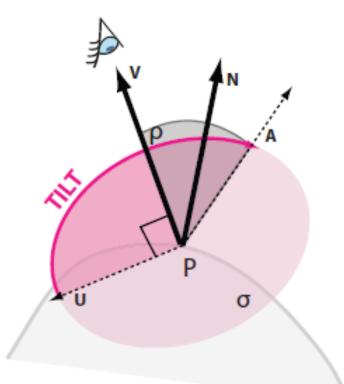
Perceptual-Statistics Shading Model



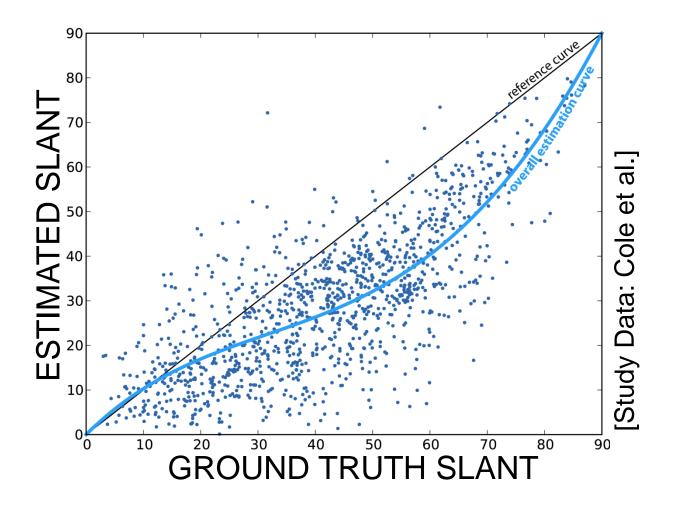
24

Surface Slant and Tilt



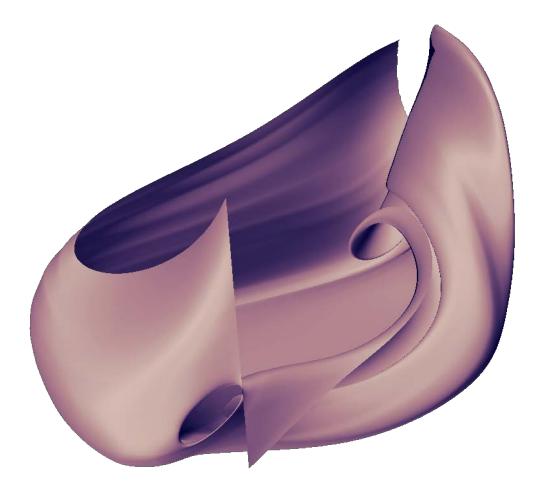


Underestimation of Slant





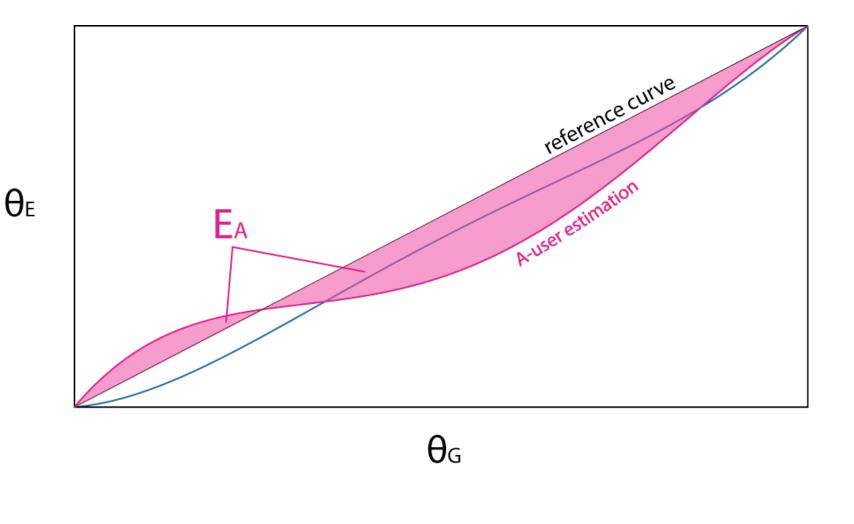
Optimized Normal-Based Shading



[Solteszova et al. 2012]

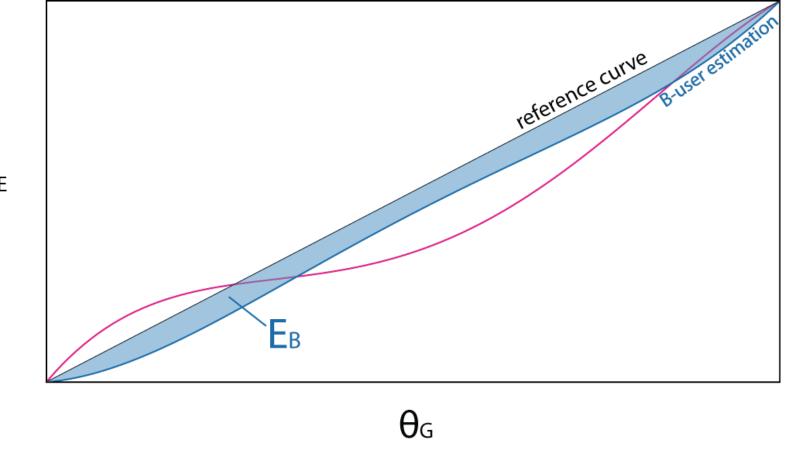
IEN

Quantifying the Error



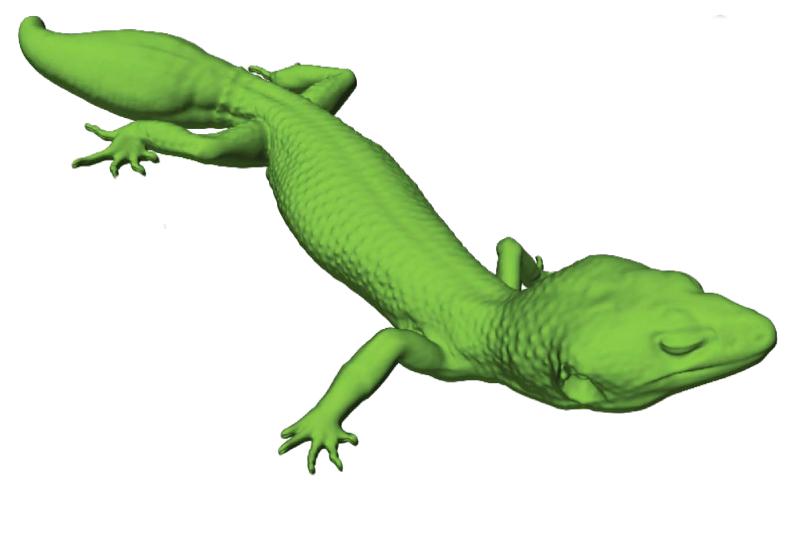
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Quantifying the Error



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Iterative Evaluation and Redesign



Perceptually Uniform Motion

• How is motion perceived in relation of one to another?

Parameter

Range

Pilot Study

Ivan Viola

- Can we linearize perception of motion?
- Estimation from a motion legend

Initial Study

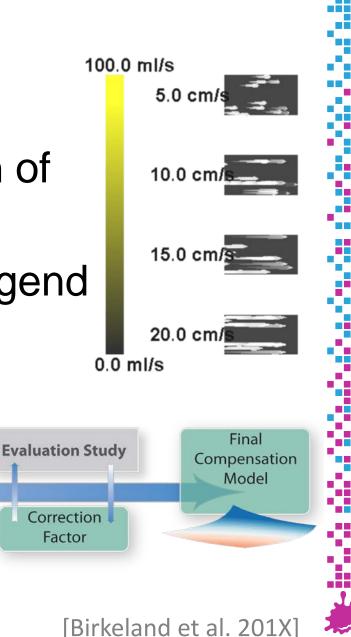
Color Speed

Scale Direction Initial

Compensation

Model

31



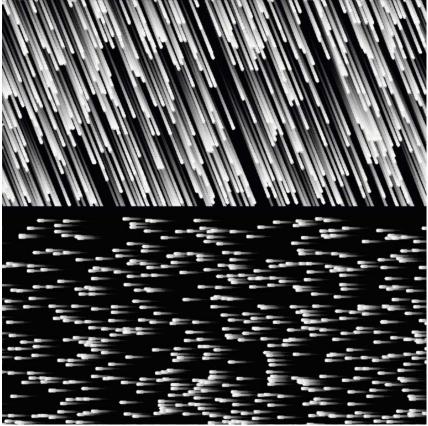
Studied Characteristics

- Task: Estimate relative speed-up factor
- Global scale of velocities
- Direction
- Contrast-type
- Representation



Studied Characteristics

- Task: Estimate relative speed-up factor
- Global scale of velocities
- Direction
- Contrast-type
- Representation

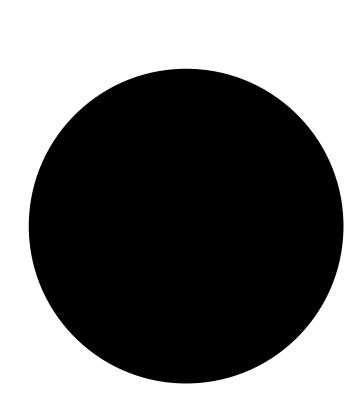


Studied Characteristics

- Task: Estimate relative speed-up factor
- Global scale of velocities
- Direction
- Contrast-type
- Representation



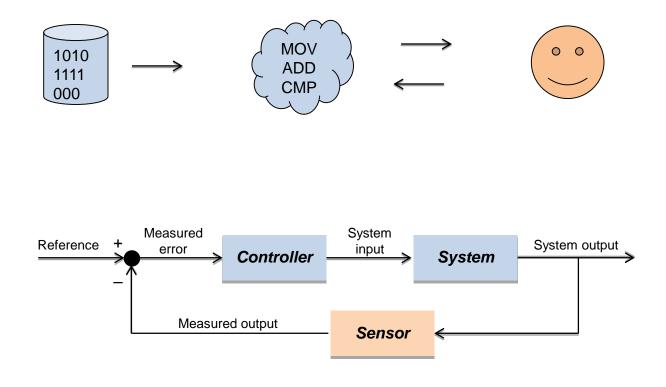
Information Visualization: Circle Size



I E N

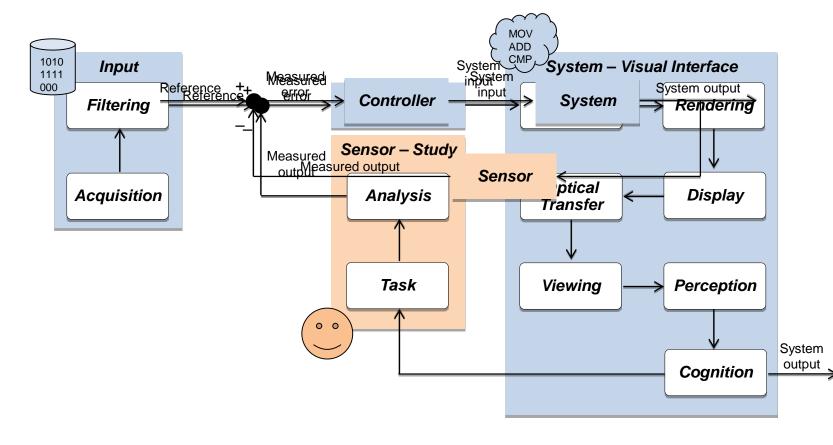
Declarative Visualization Workflow

 Automation and regulation systems are based on a feedback loop mechanism



Declarative Visualization Workflow

- Can we learn from process automation?
- What would the PID controller look like?



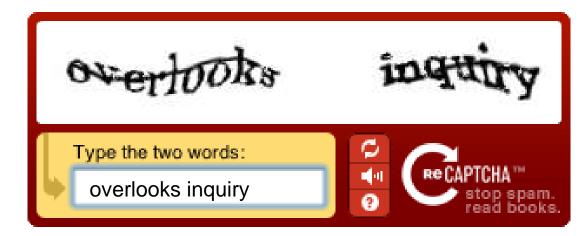
Sensor

- Psychophysics
- Controlled Study
- Surveillance
 - Eye Tracking (Tobii)
 - Digital Pen (Lifetrons)
 - EEG (Emotiv)
- Crowdsourcing
- Statistical Analysis
- Individuality is reality

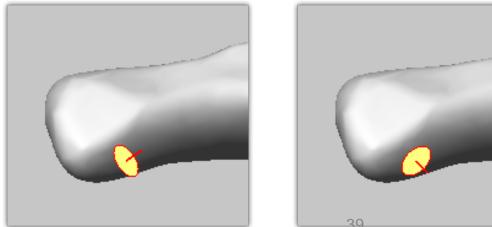


Invisible Perceptual Study

• ReCaptcha idea

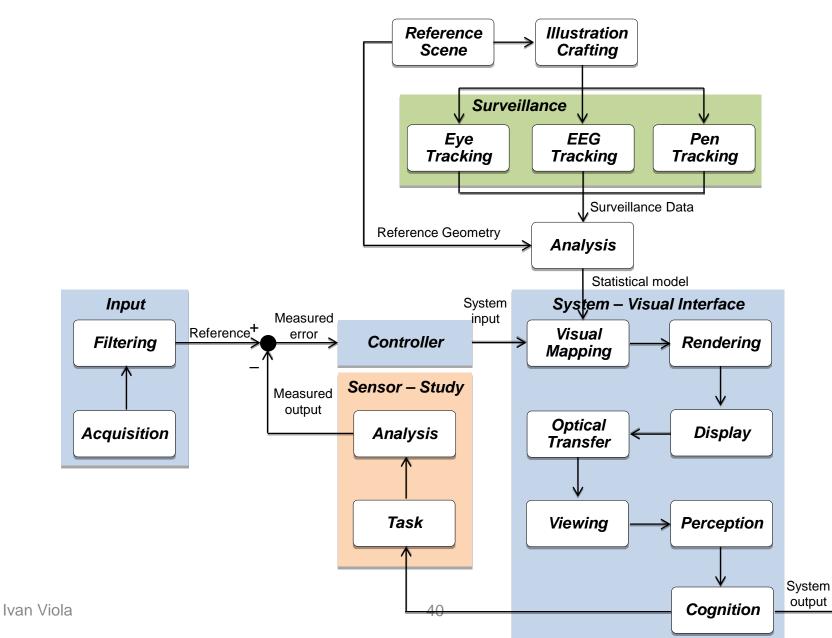


• ReGauge-figure task?



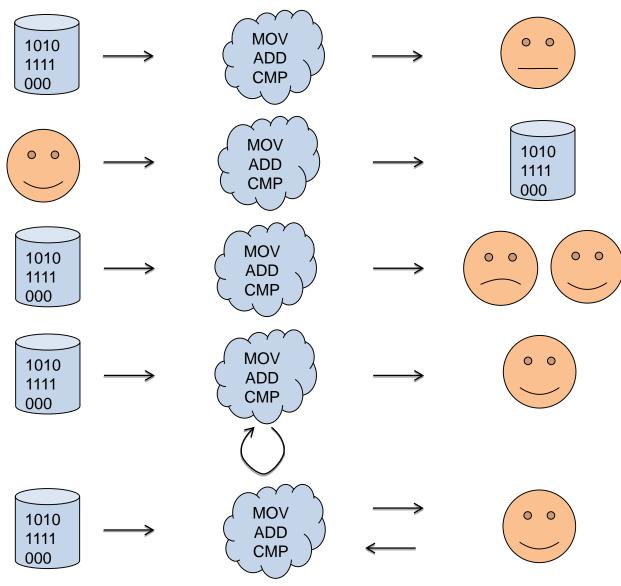


Statistical Model of Illustration



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Pipeline Patterns



WIEN

Thanks

- Veronika Šoltészová
- Åsmund Birkeland
- Endre Lidal
- Manu Waldner
- many others!

