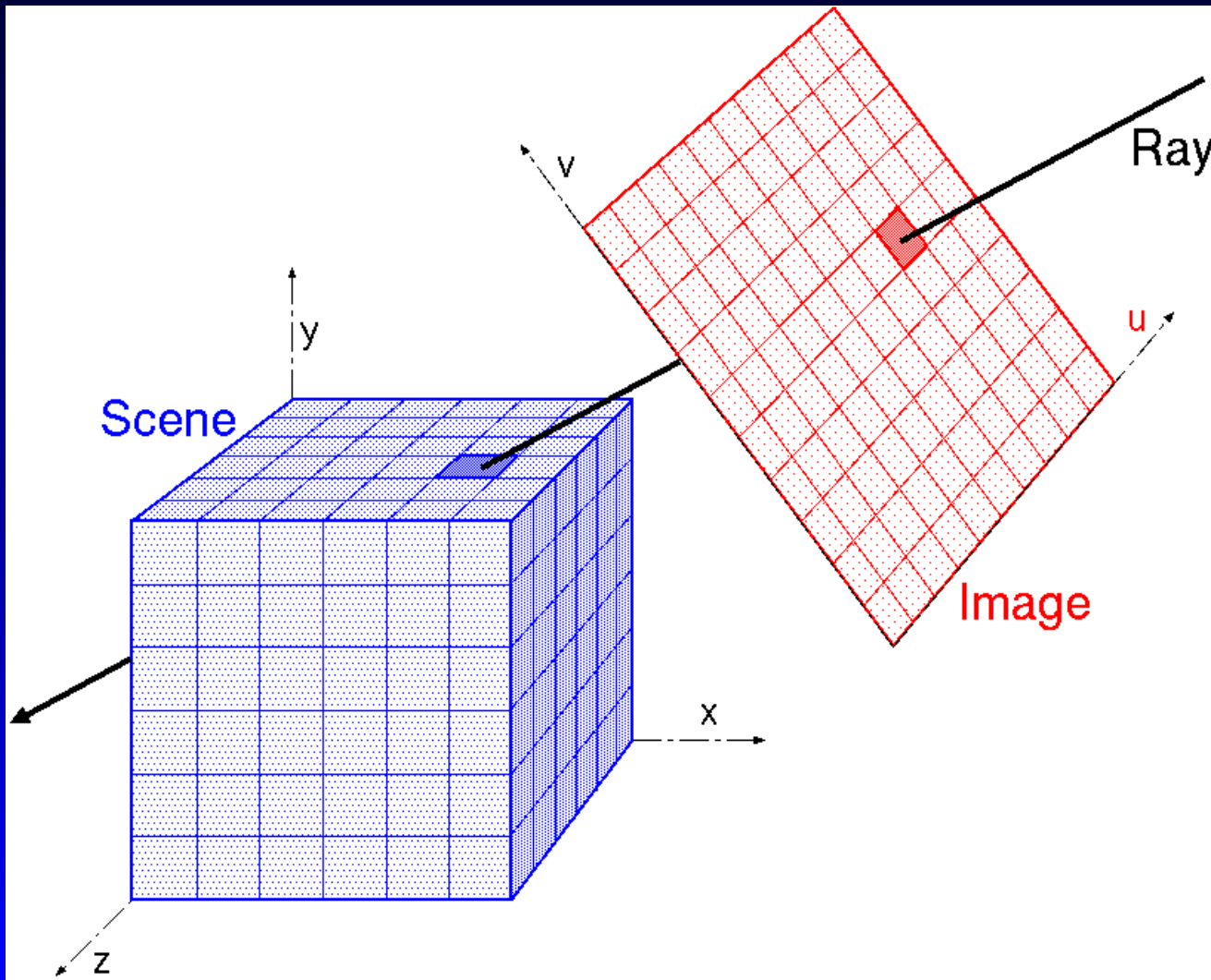


Sampling Aspects of Volume Rendering

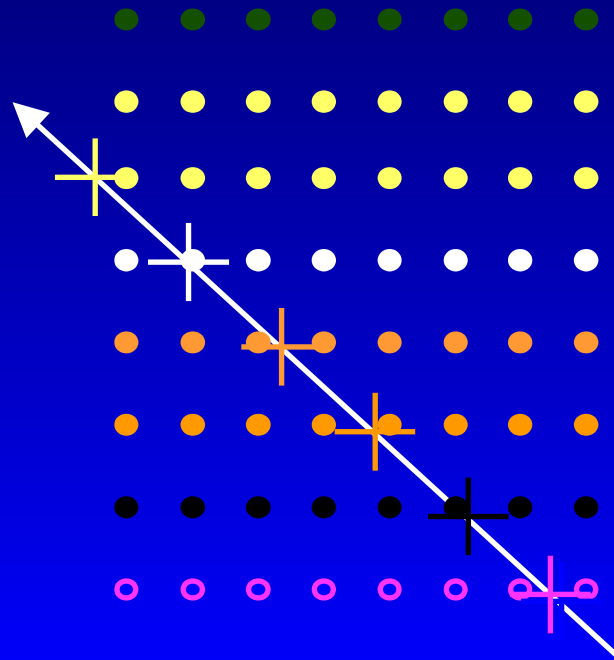
Miloš Šrámek and Leonid Dimitrov

Volume Rendering



Ray-Casting

- ◆ Shoot rays from each pixel
- ◆ Define a sequence of samples
- ◆ Accumulate color along each ray



Compositing

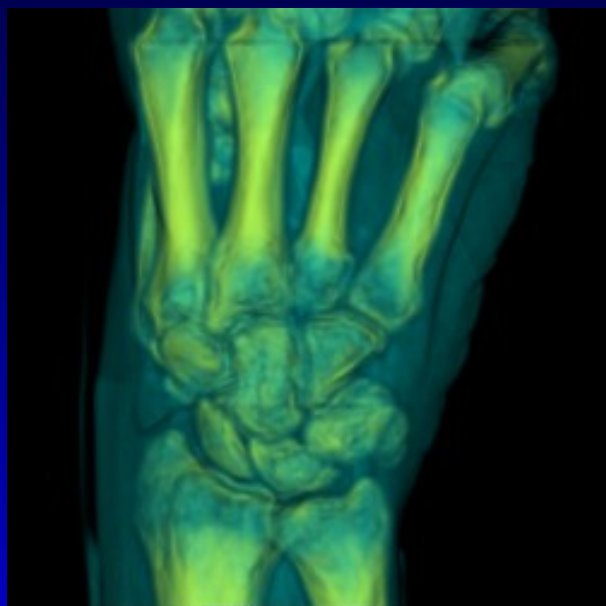
- ◆ Aproximate light attenuation
e.g. Front-to-Back compositing:

$$I_m = I_{m-1} + (1 - \beta_{m-1})C_m$$
$$\beta_m = \beta_{m-1} + (1 - \beta_{m-1})\alpha_m$$

- ◆ Segment opacity

$$\alpha_i = 1 - e^{-\int_{t_i}^{t_{i+1}} \rho(u) du}$$

VR: Different Techniques



Shaded
(gradients
evaluated)



Unshaded
(reprojection,
no gradient)



MIP

VR Questions

- ◆ Which is the correct sampling density along a ray
- ◆ Which is the influence of gradient on the correct sampling density
- ◆ Which is the correct sampling density in perspective rendering

Frequency Properties of Sampled Data

- ◆ Maximum representable frequency:

$$f_{max} = \frac{1}{2VU}$$

- ◆ Optimal sampling (ideal): 1 sample/voxel
- ◆ Optimal sampling (real): more than 1 sample/voxel. It depends on
 - ◆ spectral properties of data
 - ◆ used visualization technique (gradients!)
 - ◆ Used reconstruction filters

Low vs. High Sampling Density

- ◆ Rendered images at
 - ◆ 10 samples along a ray / voxel
 - ◆ Samples on voxel boundaries (0.7 / voxel)
- ◆ Results:

$$SNR(dB) = 10 \log \frac{\sum f_i^2}{\sum |t_i - f_i|^2}$$

Technique	Image SNR [dB]
Shaded	63
Unshaded	120
MIP	87

Rules of Thumb

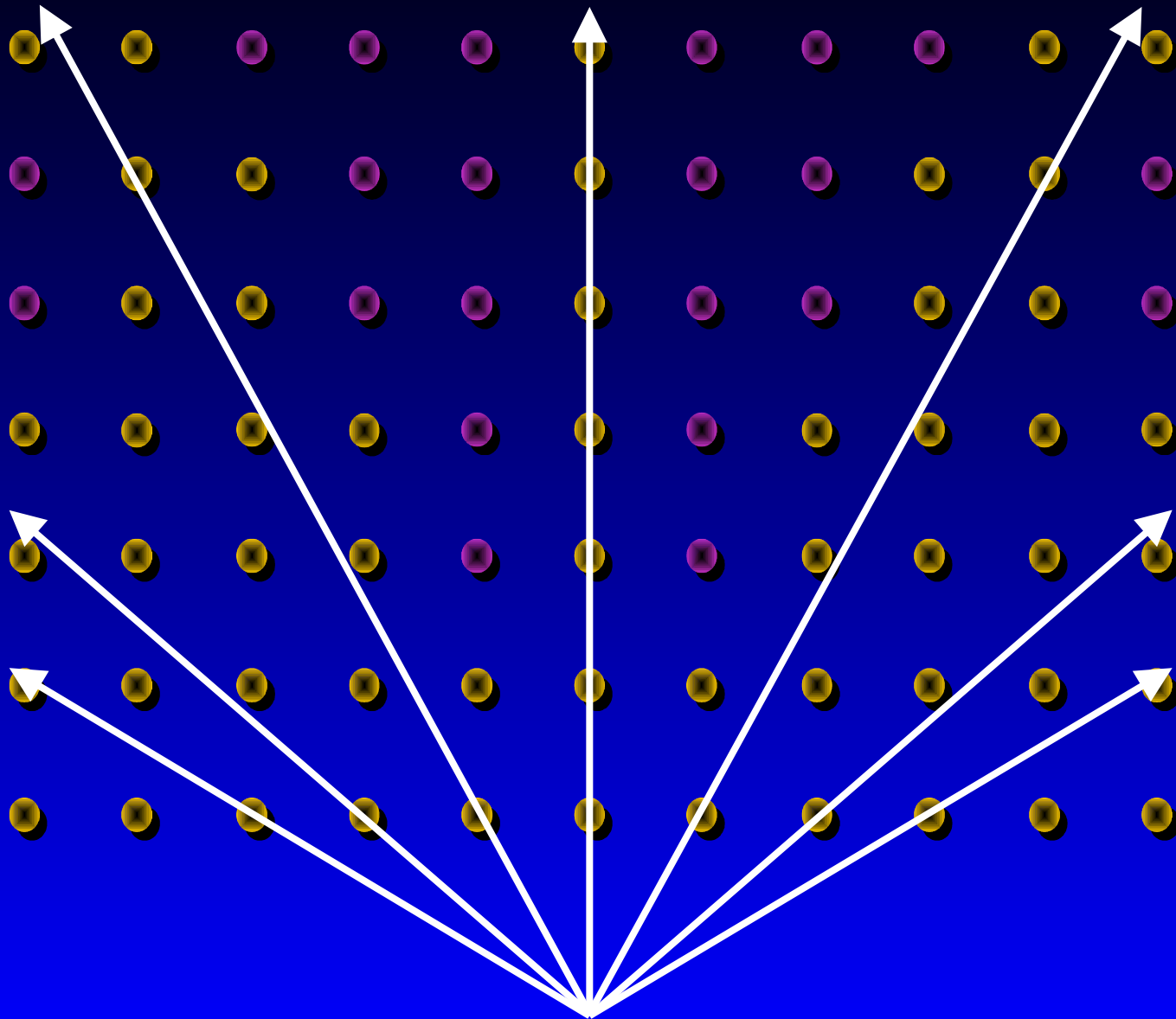
- ◆ **Unshaded** (reprojection)
 - ◆ 1 sample / voxel is OK
- ◆ **MIP**
 - ◆ 1 sample / voxel is not that bad
- ◆ **Shaded**
 - ◆ 1 sample / voxel is definitely bad
(2, 4, 8 samples?)

Perspective Rendering

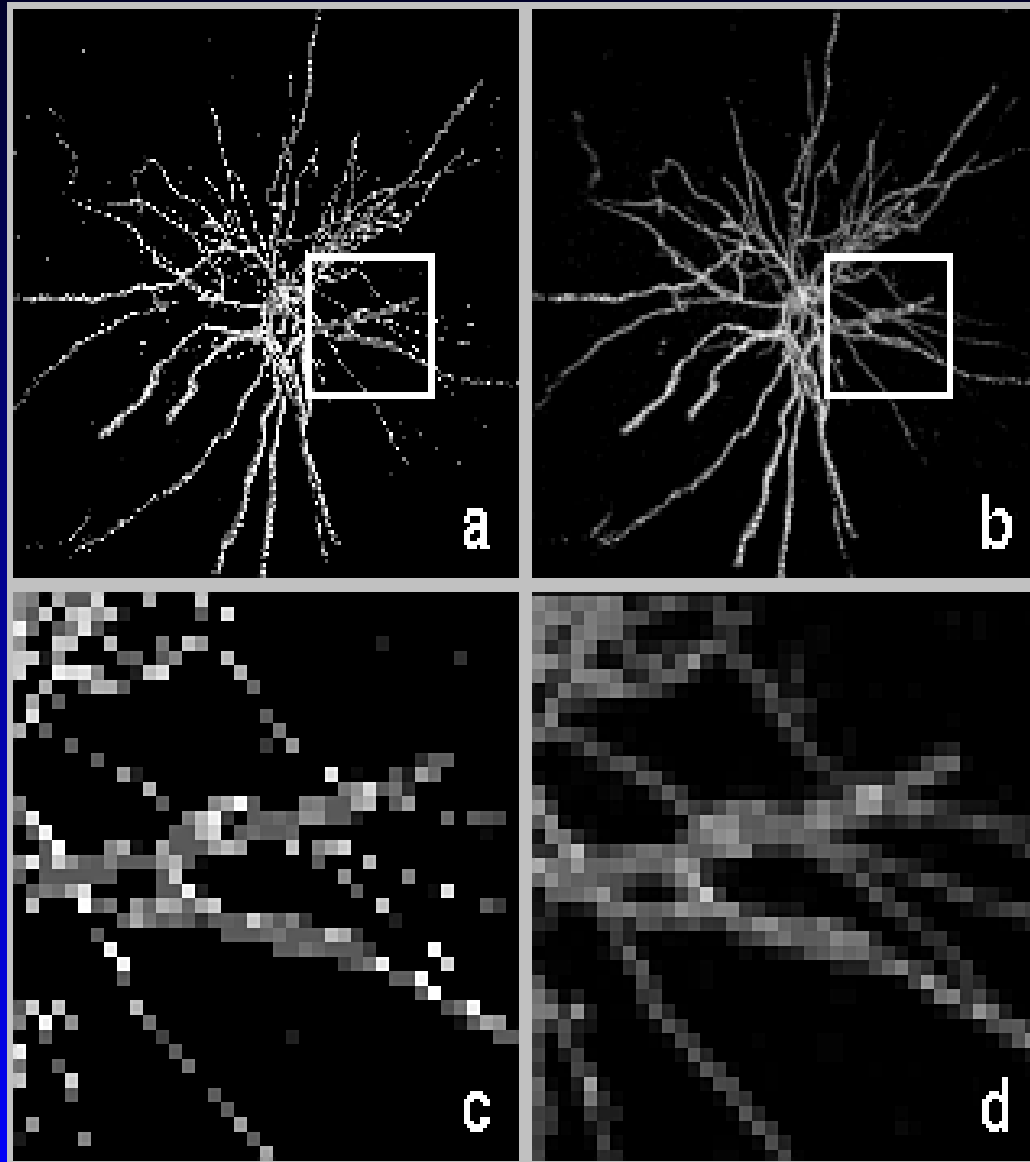
Problems in perspective rendering

- ◆ **Incorrect spatially variable sampling:**
 - ◆ **Oversampling (long time)**
 - ◆ **Undersampling (low image quality)**

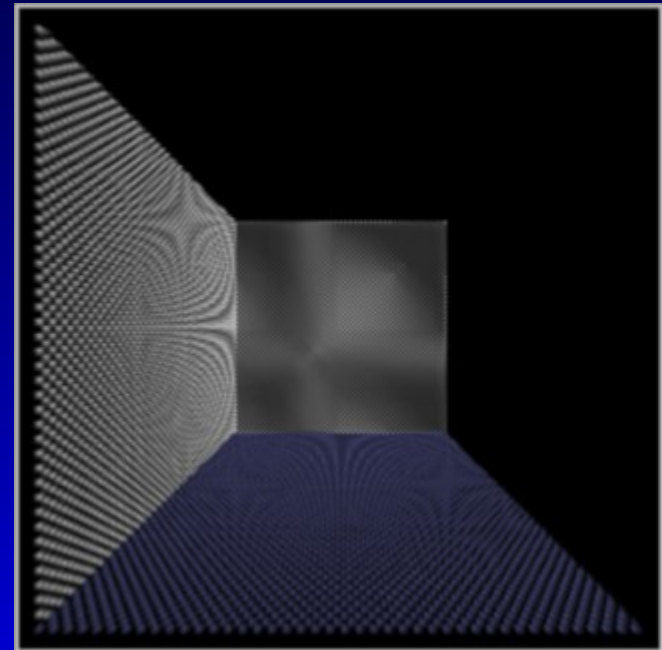
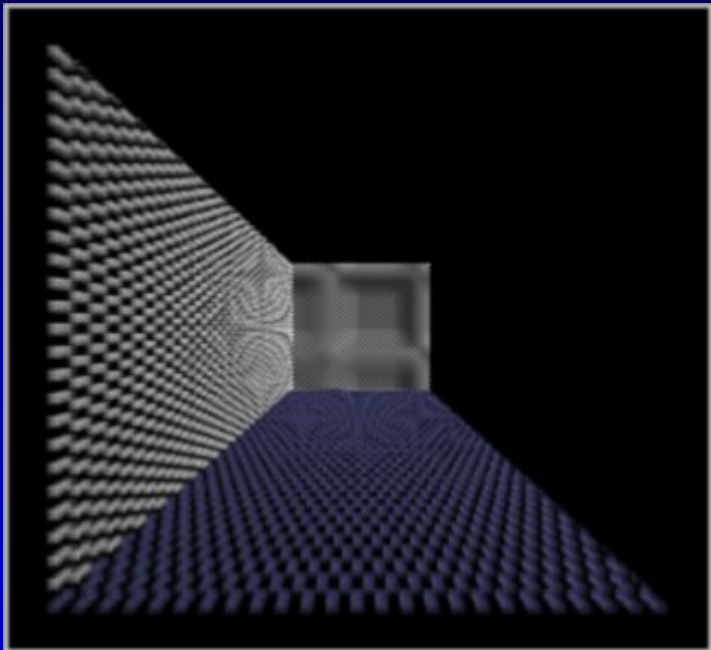
Motivation (Image Quality)



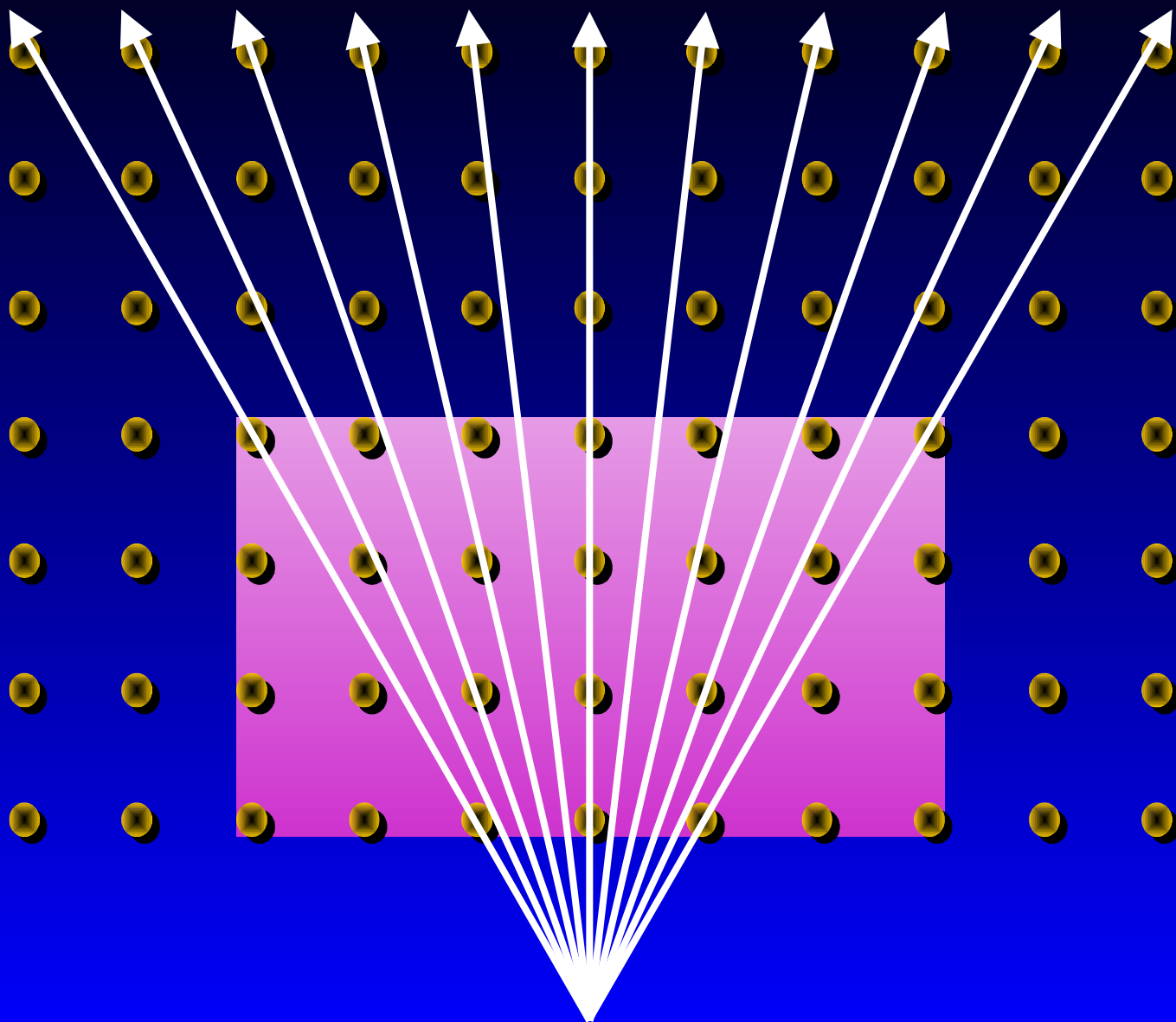
Motivation (Image Quality)



Motivation (Image Quality)



Motivation (Rendering Speed)



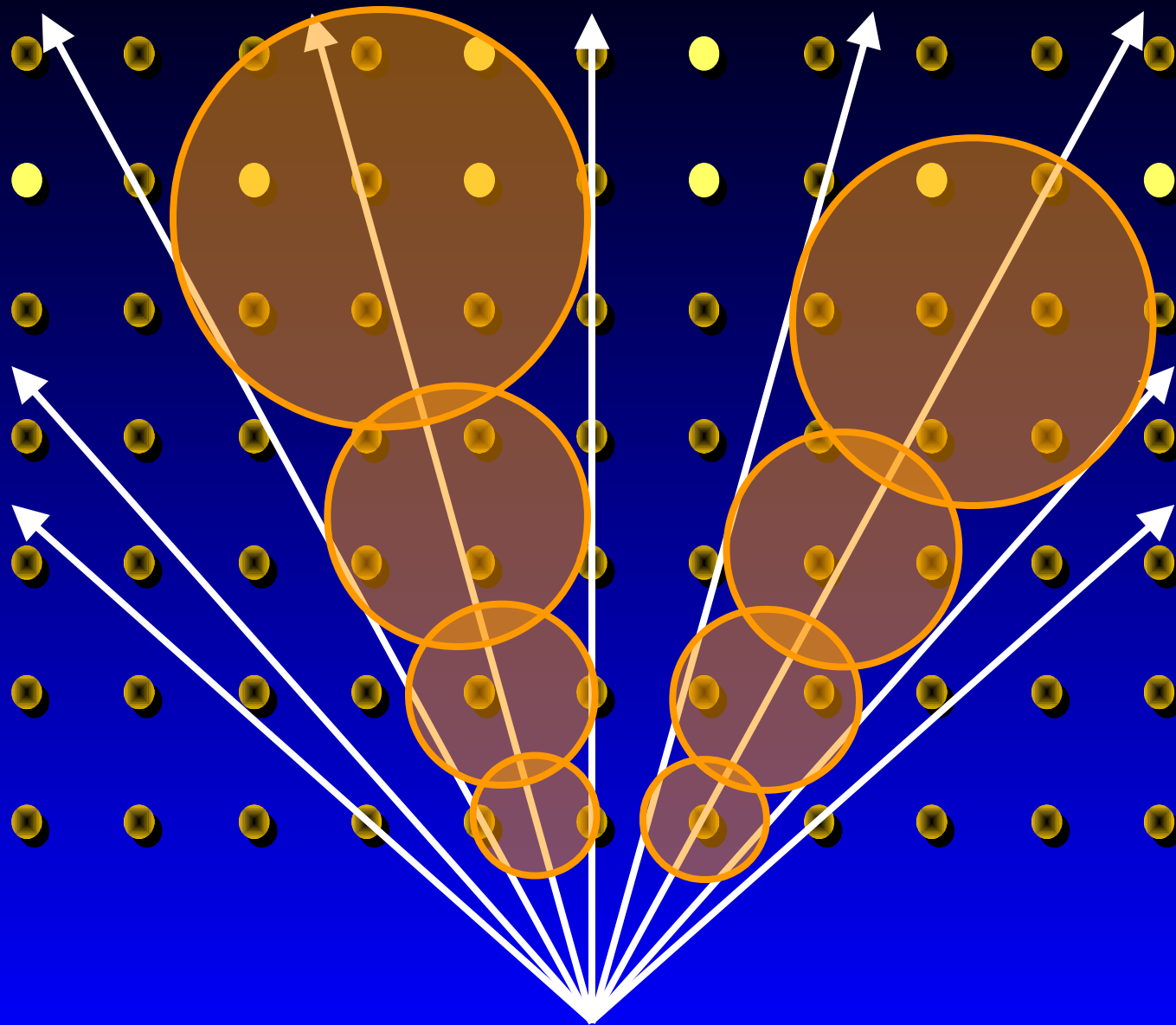
A Correct Solution

- ◆ VR is a resampling process:
 - ◆ Reconstruction of a continuous field
 - ◆ **Antialiasing by low-pass filtering**
 - ◆ Sampling
 - ◆ Compositing

Can be combined in one filter:

**Size and sampling density depend
on distance between rays**

A Correct Solution



Practical Solutions

- ◆ 3D-mip map

- ◆ *multum in parvo*, much in a small space

- [Levoy & Whitaker `90]

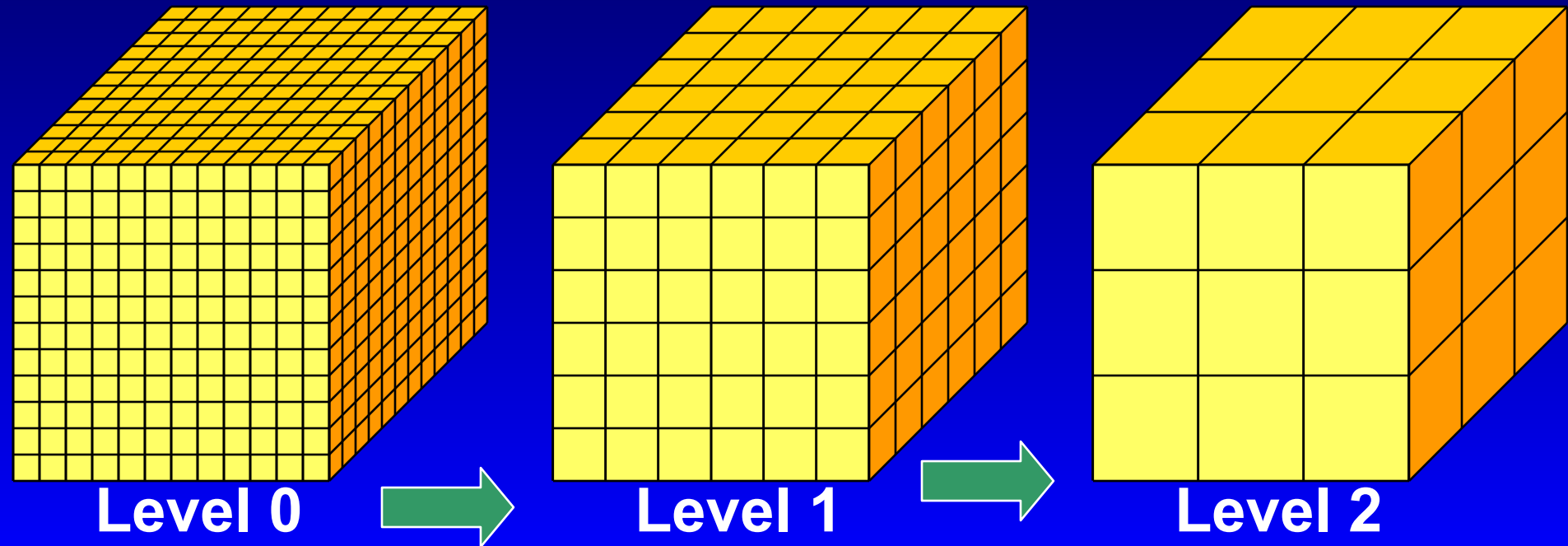
- ◆ Adaptive sampling [Novins et al. `90]

- ◆ Splitting a ray in 4 rays when necessary

- ◆ Exponential Regions Perspective [Kreeger et al. `98]

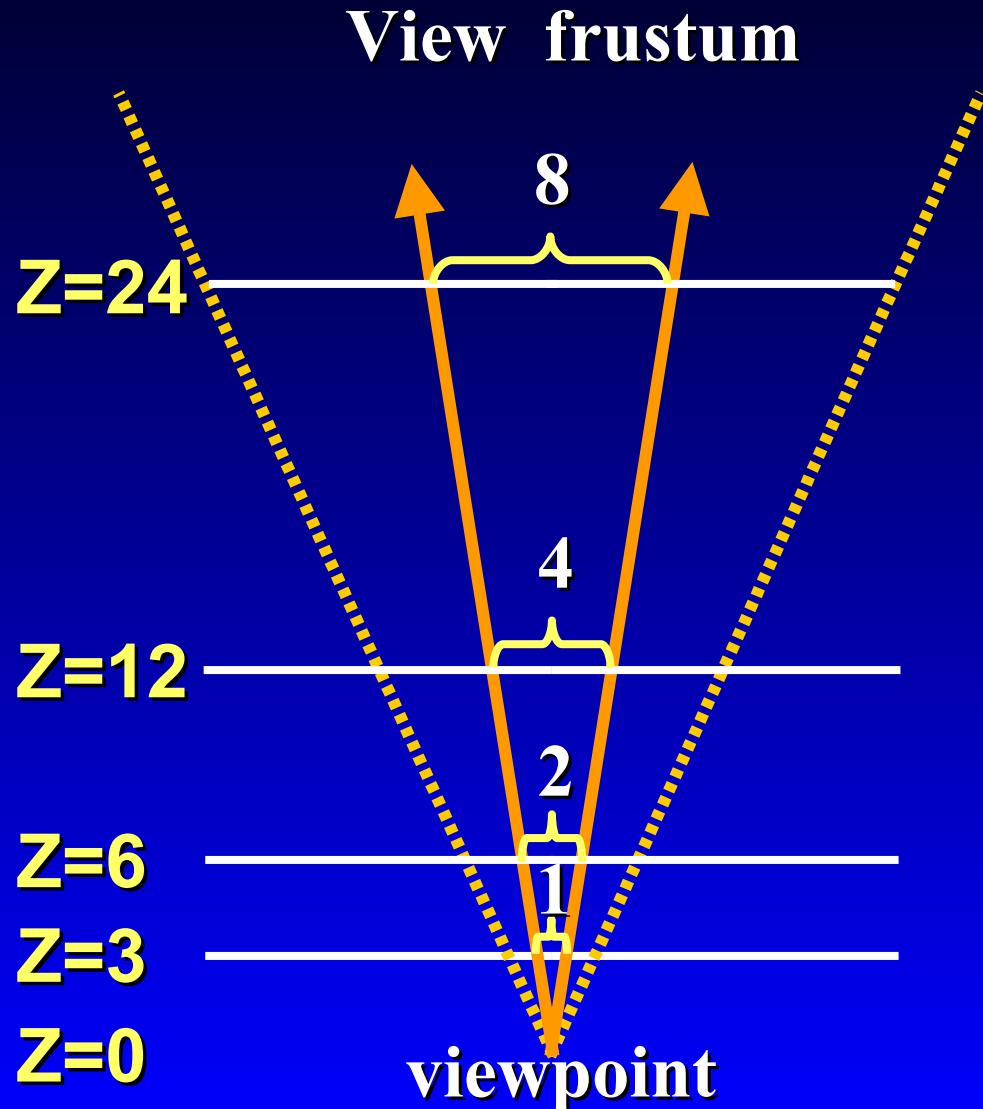
3D Mip Maps

- ◆ Build a hierarchy of volumes by downsampling:
 - ◆ Low pass filtering
 - ◆ Take every second sample
- ◆ Sample a pair of volumes simultaneously:
 - ◆ 2 x trilinear + linear interpolation

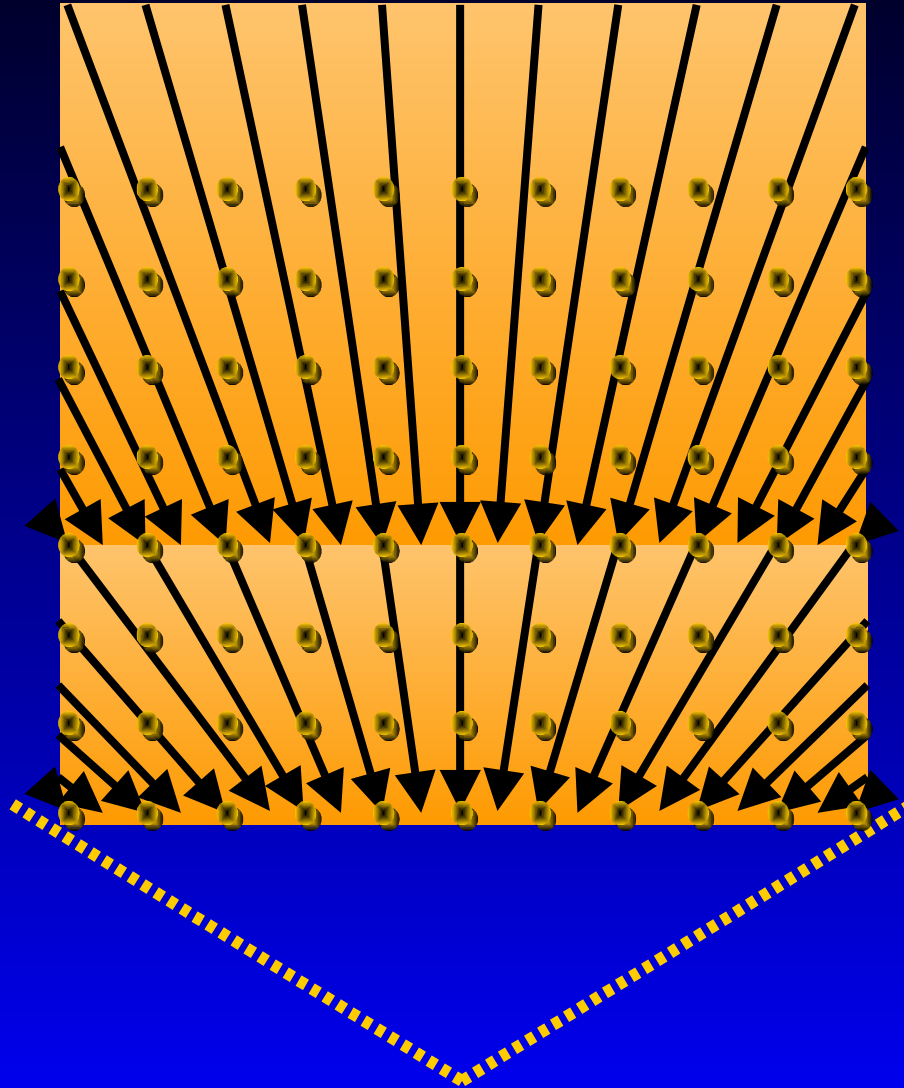


ER Perspective

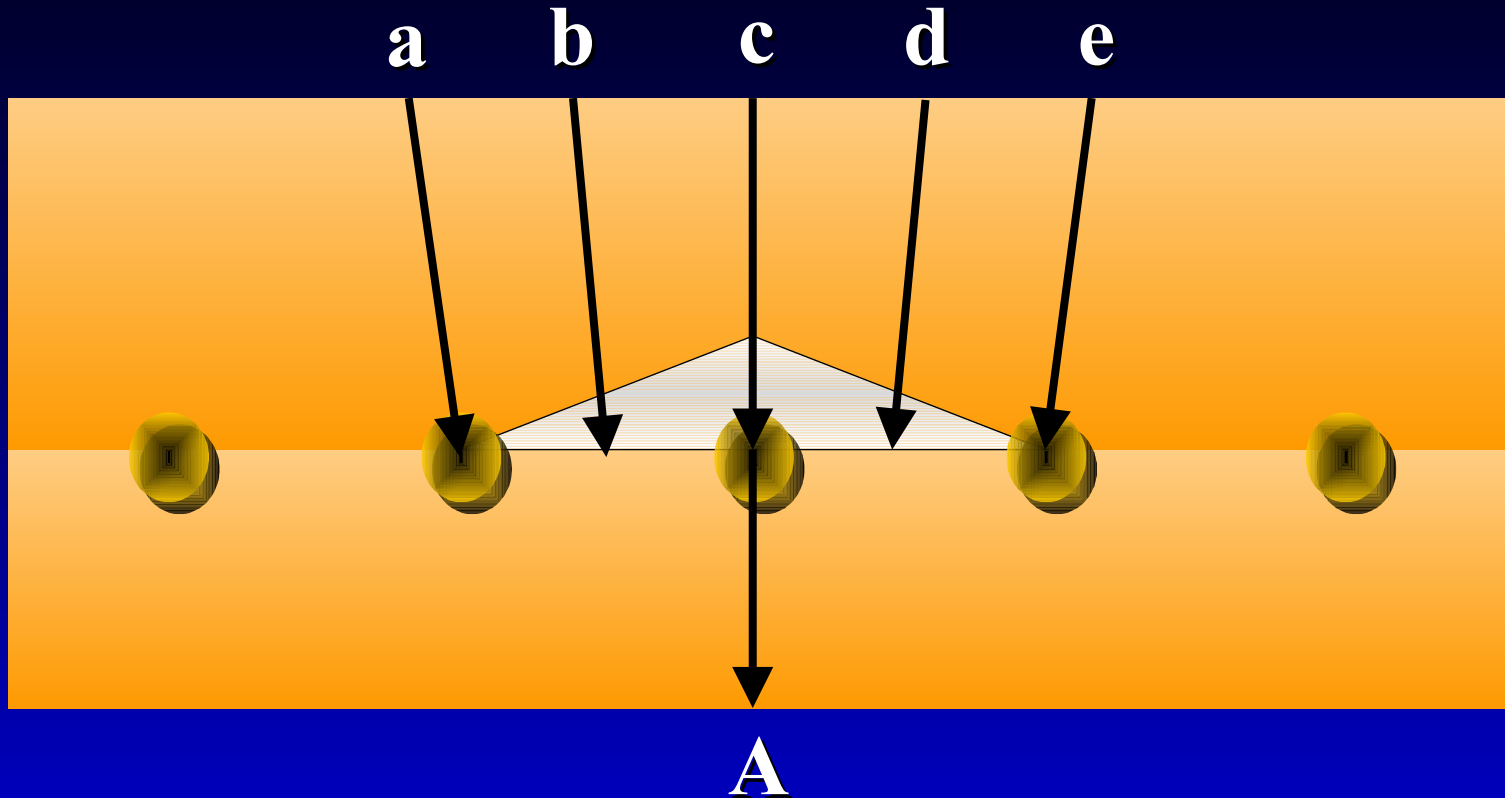
- ◆ One sample per voxel
- ◆ Regular pattern of merge/split
- ◆ Exponentially growing regions \Rightarrow uniform divergence



ER Perspective

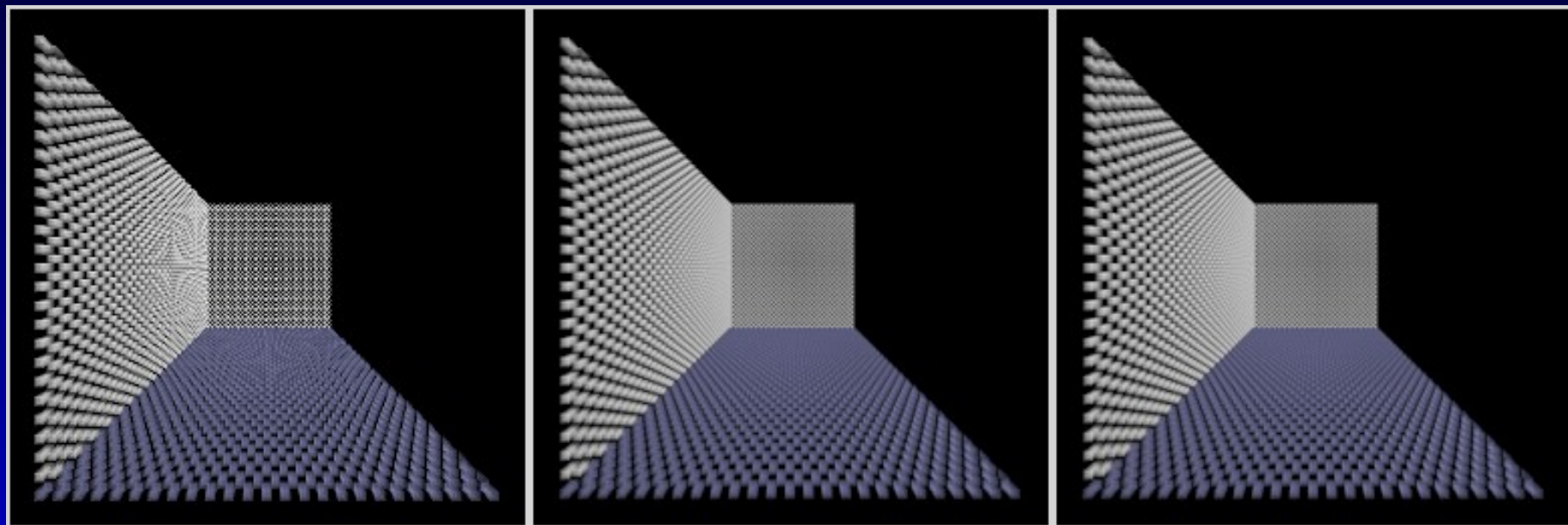


Ray Density Resampling



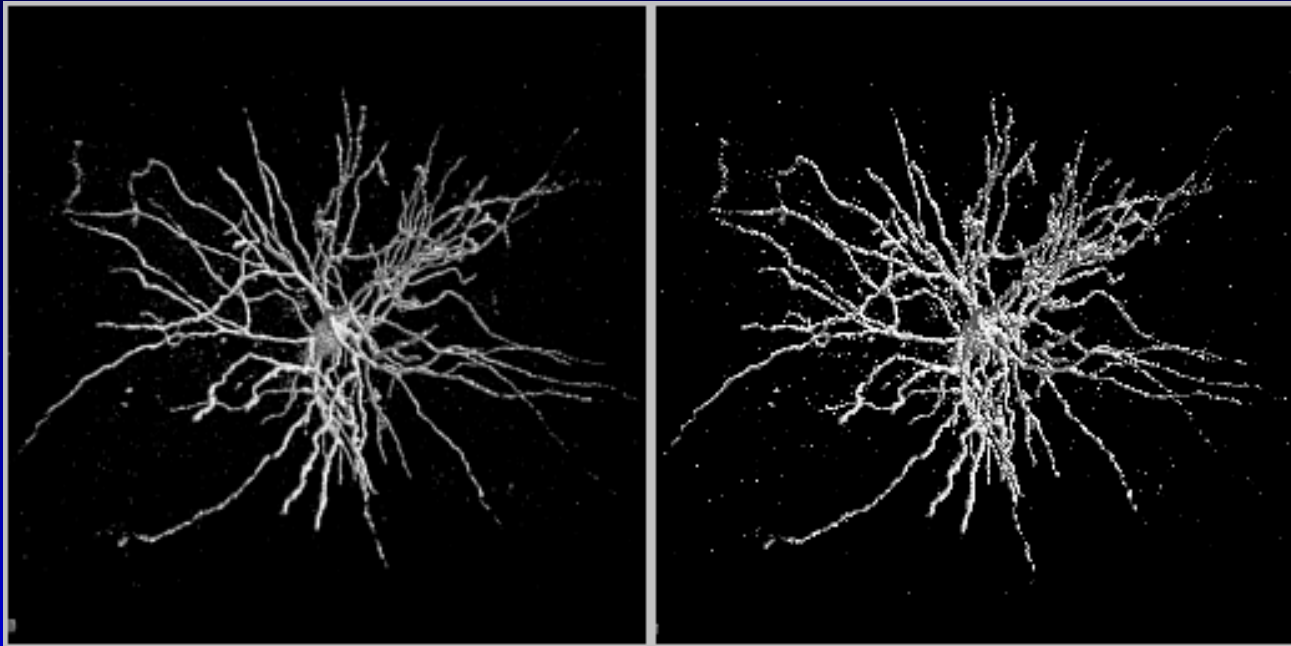
$$A = \frac{0}{4} a + \frac{1}{4} b + \frac{2}{4} c + \frac{1}{4} d + \frac{0}{4} e$$

ER Perspective - Results

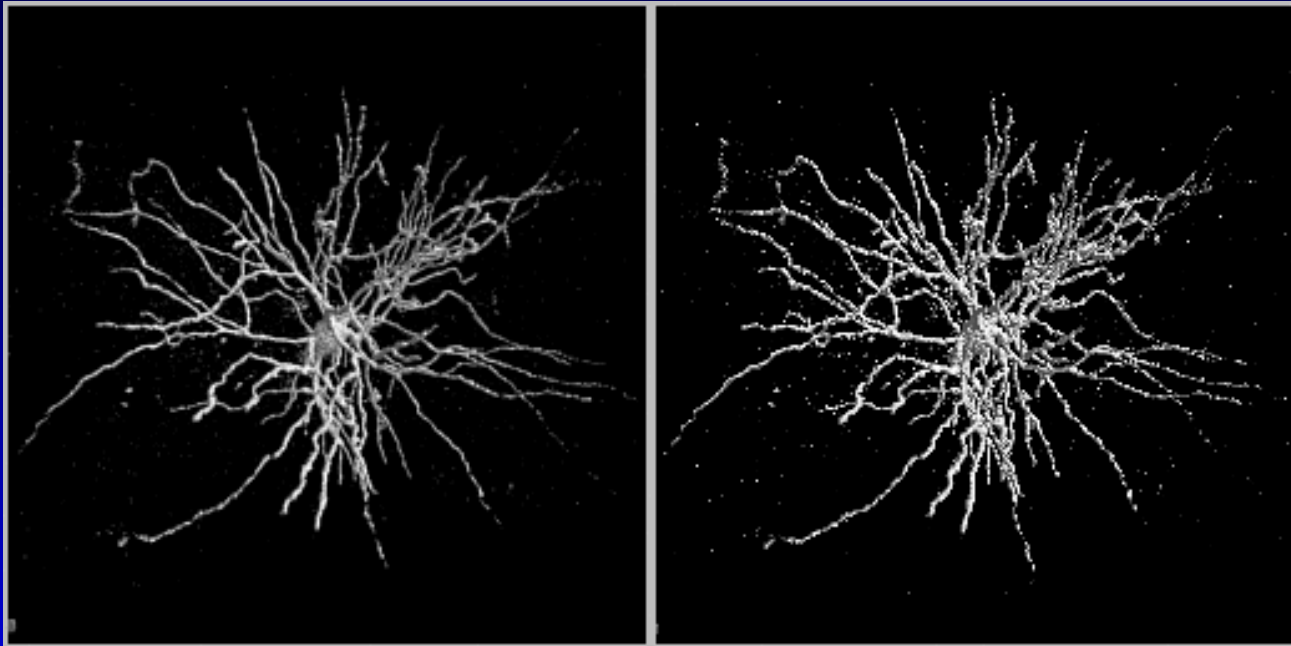


Undersampling ER - Perspective Oversampling

ER Perspective – Results



ER Perspective - Results



The End