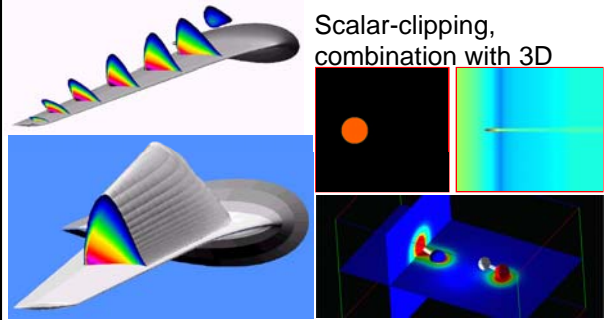


Volume Visualization

Part 2 (out of 3)

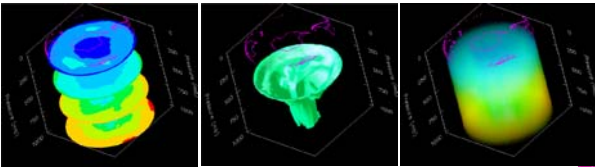
Review: Slices



Scalar-clipping,
combination with 3D

Slices vs. Iso-Surfaces. vs. Volume Rendering

- Comparison ozon-data over Antarctica:
 - Slices: selective (z), 2D, color coding
 - Iso-surface: selective (f_0), covers 3D
 - Vol. rendering: transfer function dependent, "too sparse – (too) dense"

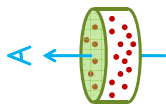


Optical Models for Volume Rendering

Display of
Semi-Transparent Media

Modelling of Natural Phenomena

- Various models (Examples):
 - Emission only (light particles)
 - Absorption only (dark fog)
 - Emission & absorption (clouds)
 - Single scattering, w/o shadows
 - Multiple scattering
- Two approaches:
 - Analytical model (via differentials)
 - Numerical approximation (via differences)



Emission, Differential Model

- Continuous emission model:
 - Question: how much light (\mathbf{I} like intensity) is added along an infinitely short ray segment in the volume
 - Differential $d\mathbf{I}/dt = g(t) \dots$
volume emits light (corresponding to thickness)
 - Glow factor $g(t)$
 - Integration results in: $\mathbf{I}(s) = \mathbf{I}_0 + \int_{t \in [0,s]} g(t) dt$
 - Overall emission contrib.: $G(0,s) = \int_{t \in [0,s]} g(t) dt$
 - Unrealistic, because no absorption

Emission, Numerical Approximation



- Discrete emission model:
 - ◆ **Question:** how much light (C like color) is added within a small, but finite volume extent
 - ◆ C_i ... contribution of vol. extent i (thickness 1)
 \Rightarrow adding emission of extent i results in
 $Out_i = In_i + C_i \Leftrightarrow Out_i = Out_{i-1} + C_i$
 - ◆ **Accumulation:**
 $Out_i = In_j + C_j + \dots + C_{i-1} + C_i$
 $Out_i = In_j + \sum_{j \leq k \leq i} C_k$
 - ◆ **Example:**
 pixel value = background + $\sum_{k \in N} C(\text{ray}(k))$

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Emission Only



- Differential model:
 - ◆ $I(s) = I_0 + \int_{t \in [0,s]} g(t) dt$
- Discrete approximation:
 - ◆ $Out_s = In_0 + \sum_{s \geq k \in N} C_k$
- Example:



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Absorption, Differential Model



- Continuous absorption model:
 - ◆ **Question:** how much light (in % of I_0) remains after traversal of ray segment through the volume
 - ◆ **Differential** $dI/dt = -\tau(t)I(t)$...
light (I) is partially absorbed (τ)
 - ◆ **Extinction coefficient** $\tau(t)$, e.g., 30%
 - ◆ **Integration** results in: $I(s) = I_0 \cdot \exp(-\int_{t \in [0,s]} \tau(t) dt)$
 - ◆ **Total transparency:** $T(0,s) = \exp(-\int_{t \in [0,s]} \tau(t) dt)$
 - ◆ **Total absorption:** $\alpha(0,s) = 1 - T(0,s)$

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Absorption, Numerical Approximation



- Discrete approximation model:
 - ◆ **Question:** how much light (in % of I_0) remains after traversal of small, but finite volume extent
 - ◆ α_i ... opacity of volume extent i (per unit)
 \Rightarrow result after traversal of extent i
 $Out_i = In_i \cdot (1 - \alpha_i) \Leftrightarrow Out_i = Out_{i-1} \cdot (1 - \alpha_i)$
 - ◆ **Akkumulation:** $Out_i = In_j \cdot (1 - \alpha_j) \cdot \dots \cdot (1 - \alpha_i)$
 $Out_i = In_j \cdot \prod_{j \leq k \leq i} (1 - \alpha_k)$
 - ◆ **Unit sampling:** unit distance between α_i samples!!

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Absorption Only



- Differential model:
 - ◆ $I(s) = I_0 \cdot \exp(-\int_{t \in [0,s]} \tau(t) dt)$
- Discrete approximation:
 - ◆ $Out_s = In_0 \cdot \prod_{s \geq k \in N} (1 - \alpha_k)$
- Example:



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Emission and Absorption



- Continuous model (no scattering):
 - ◆ **At each position** is given:
 - Emission $g(t)$
 - Extinction coefficient $\tau(t)$
 - ◆ **Differential** $dI/dt = g(t) - \tau(t)I(t)$
 - ◆ Emission $g(t)$ **attenuated** by $T(t,s)$
 - ◆ **Only Emission:** $I_0 + \int_{t \in [0,s]} g(t) dt$
 - ◆ **With Absorption:** $I_0 \cdot T(0,s) + \int_{t \in [0,s]} g(t) \cdot T(t,s) dt$
 - ◆ **Emission und Absorption:**
 $I_0 \cdot \exp(-\int_{u \in [0,s]} \tau(u) du) + \int_{t \in [0,s]} g(t) \cdot \exp(-\int_{u \in [t,s]} \tau(u) du) dt$

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Numerical Approximation



- Discrete model (compositing):
 - ◆ For each **volume extent** i :
 - Contribution C_i
 - Opacity α_i , transparency $1-\alpha_i$
 - ◆ $Out_i = In_i \cdot (1-\alpha_i) + C_i \cdot \alpha_i$ (Std.-**compositing**)
 - ◆ **Convex combination** from background and own contribution
 - ◆ $Out_s = In_0 \cdot \prod_{s \geq k \in N} (1-\alpha_k) + \sum_{s \geq k \in N} C_k \cdot \alpha_k \cdot \prod_{s \geq l > k} (1-\alpha_l)$
 - ◆ **Opacity-weighted colors**: $C_i \cdot \alpha_i$ instead of C_i



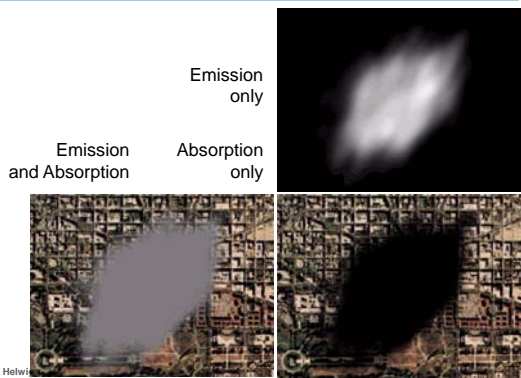
Emission and Absorption



- Differential model:
 - ◆ $I(s) = I_0 \cdot T(0,s) + \int_{t \in [0,s]} g(t) \cdot T(t,s) dt$
 - ◆ $I(s) = I_0 \cdot \exp(-\int_{u \in [0,s]} \tau(u) du) + \int_{t \in [0,s]} g(t) \cdot \exp(-\int_{u \in [t,s]} \tau(u) du) dt$
- Discrete Approximation:
 - ◆ $Out_i = In_i \cdot (1-\alpha_i) + C_i \cdot \alpha_i$ (Compositing)
 - ◆ $Out_s = In_0 \cdot \prod_{s \geq k \in N} (1-\alpha_k) + \sum_{s \geq k \in N} C_k \cdot \alpha_k \cdot \prod_{s \geq l > k} (1-\alpha_l)$



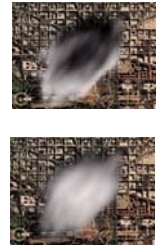
Emission or/and Absorption



Scattering



- **Scattering**: particles deviate light at a position
 - ◆ BRDF (bidirectional reflectance distribution function)
 - ◆ Single scattering
 - Too little light in the interior
 - ◆ Single scattering with shadows
 - ◆ Multiple Scattering
 - Radiosity techniques
 - Very realistic, very costly



Literature



- Paper (more details):
 - ◆ **Nelson Max**: "**Optical Models for Direct Volume Rendering**" in *IEEE Transactions on Visualization and Computer Graphics*, Vol. 1, No. 2, June 1995



Ray Casting / Compositing

Classical
Image-Order Methods



Ray Tracing vs. Ray Casting



- **Ray Tracing**: method from image generation
- In volume rendering: **only viewing rays**
⇒ therefore Ray Casting
- Classical **image-order** method
- **Ray Tracing**: ray – object intersection
Ray Casting: no objects, density values in 3D
- In **theory**: take all density values into account!
In **practice**: traverse volume step by step
- **Interpolation** necessary for each step!

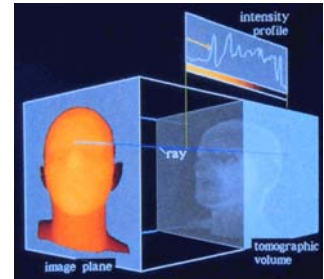


Ray Traversal through Volume Data



Context:

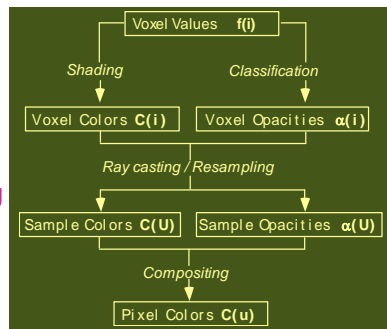
- ◆ **Volume data**: 1D value defined in 3D –
 $f(\mathbf{x}) \in \mathbb{R}^1, \mathbf{x} \in \mathbb{R}^3$
- ◆ **Ray** defined as half-line:
 $\mathbf{r}(t) \in \mathbb{R}^3, t \in \mathbb{R}^1 > 0$
- ◆ **Values along Ray**:
 $f(\mathbf{r}(t)) \in \mathbb{R}^1, t \in \mathbb{R}^1 > 0$
(intensity profile)



Standard Ray Casting



- **Levoy '88**:
- 1. **$C(i), \alpha(i)$**
(from TF)
- 2. **Ray casting, interpolation**
- 3. **Compositing**

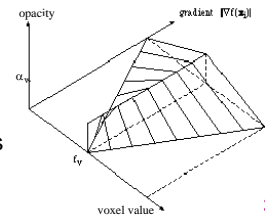


1. Shading, Classification

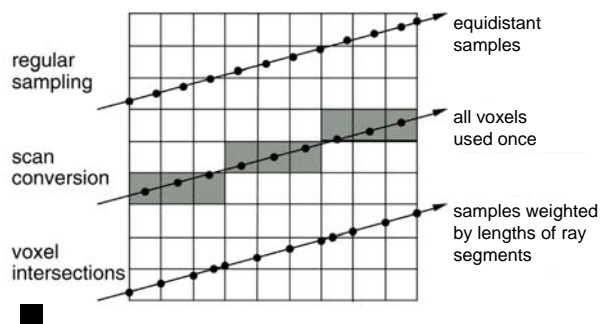


1. Step:

- ◆ **Shading, $f(i) \rightarrow C(i)$** :
 - Apply transfer function
 - diffuse illumination (Phong),
gradient \approx normal
- ◆ **Classification, $f(i) \rightarrow \alpha(i)$** :
 - **Levoy '88**,
gradient enhanced
 - **Emphasizes transitions**



2. Ray Traversal – Three Approaches



2. Ray Traversal, Interpolation



- **Voxel-based vs. cell-based traversal**
- **Tri-linear** (interpolation within a cell) vs. **bi-linear** (interpolation within a cell face)
- **Tri-linear**:
 - ◆ first 4* in z-direction (interpolated square),
 - ◆ then 2* in y-direction (interpolated line),
 - ◆ then 1* in x-direction (interpolated value)
- **Unit sampling vs. variable sample distances – compositing different!!**



Compositing: F2B vs. B2F



Back-to-Front (B2F):

- ◆ $Out_i = In_i \cdot (1 - \alpha_i) + C_i \cdot \alpha_i$, $In_{i+1} = Out_i \dots$
- ◆ Depending on local transparency $(1 - \alpha_i) \Rightarrow$ convex combination of old In_i & new C_i
- ◆ Example:
 - Voxel i : $C_i = \text{red}$, $\alpha_i = 30\%$; so far: $In_i = \text{white}$
 - Result of compositing: 70% white + 30% red

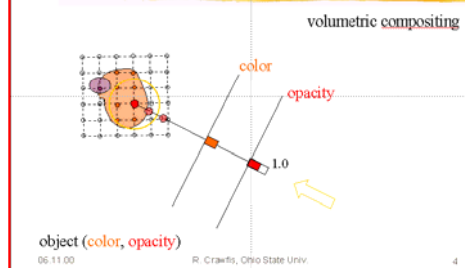
Front-to-Back (F2B):

- ◆ $Col = Col + (1 - \alpha_{akk}) \cdot C_i \cdot \alpha_i \dots$ accumulated color
- ◆ $\alpha_{akk} = \alpha_{akk} + (1 - \alpha_{akk}) \cdot \alpha_i \dots$ accumulated opacity

Front-to-Back Compositing



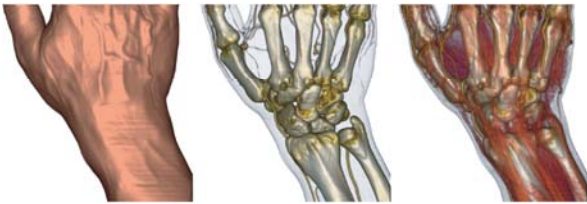
Interpolation Kernels



Ray Casting – Examples



- CT scan of human hand (244x124x257, 16 bit)



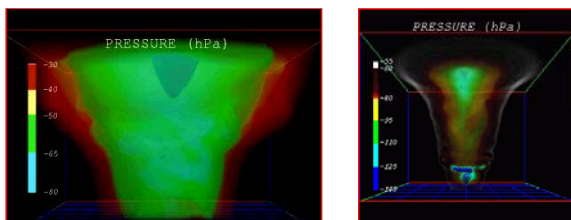
Ray Casting – Examples



Ray Casting – Further Examples



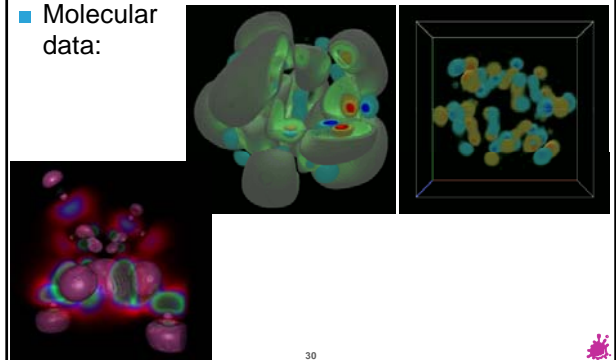
- Tornado Visualization:



Ray Casting – Further Examples



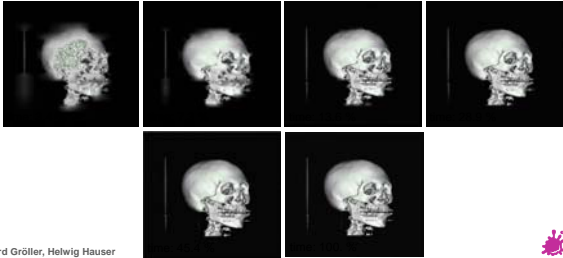
- Molecular data:



Acceleration - Progressive Refinement



- First render every $2^n \times 2^n$ -th pixel, then render the $2^{n-1} \times 2^{n-1}$ -th pixel inbetween, aso. (until interruption or completion)



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Literature



- Paper (more details):
 - ◆ Marc Levoy: "Display of Surfaces from Volume Data" in *IEEE Computer Graphics & Applications*, Vol. 8, No. 3, June 1988

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