

Flow Visualization

Part 1 (out of 3)



- Introduction, overview
 - ◆ Flow data
 - ◆ Simulation vs. measurement vs. modelling
 - ◆ 2D vs. surfaces vs. 3D
 - ◆ Steady vs time-dependent flow
 - ◆ Direct vs. indirect flow visualization
- Experimental flow visualization
 - ◆ Basic possibilities
 - ◆ PIV + Example



Flow Visualization

Introduction, Overview



- Introduction:
 - ◆ FlowVis = visualization of flows
 - Visualization of change information
 - Typically: more than 3 data dimensions
 - General overview: even more difficult
 - ◆ Flow data:
 - $nD \times nD$ data, $1D^2 / 2D^2 / nD^2$ (models), $2D^2 / 3D^2$ (simulations, measurements)
 - Vector data (nD) in nD data space
 - ◆ User goals:
 - Overview vs. details (with context)



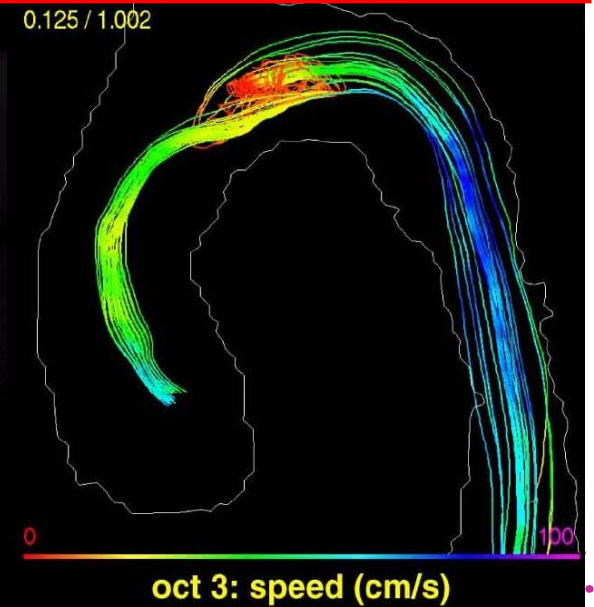
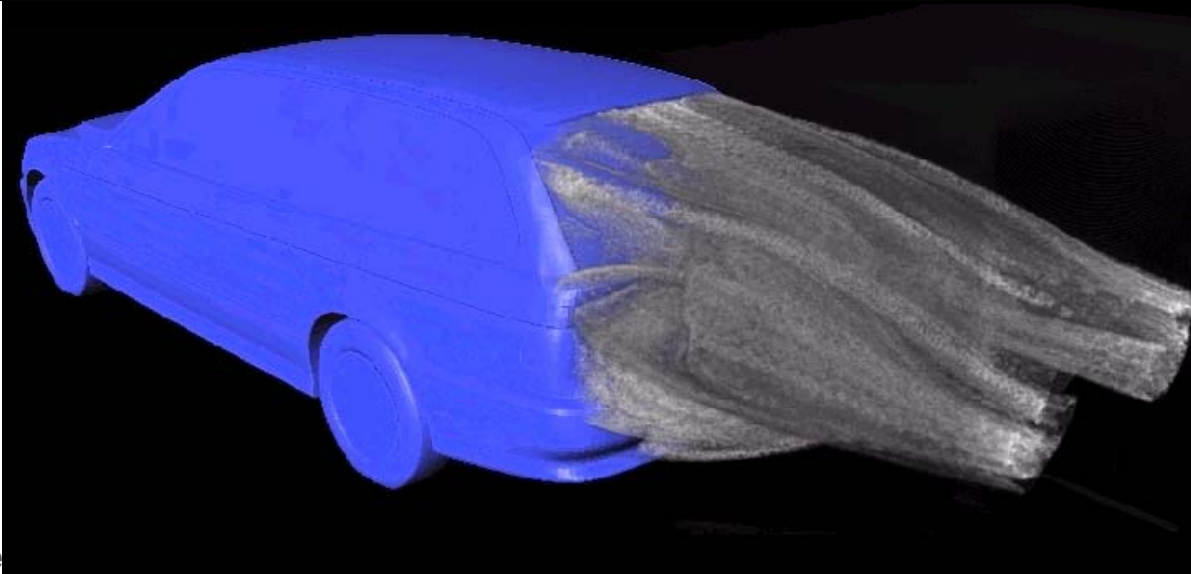
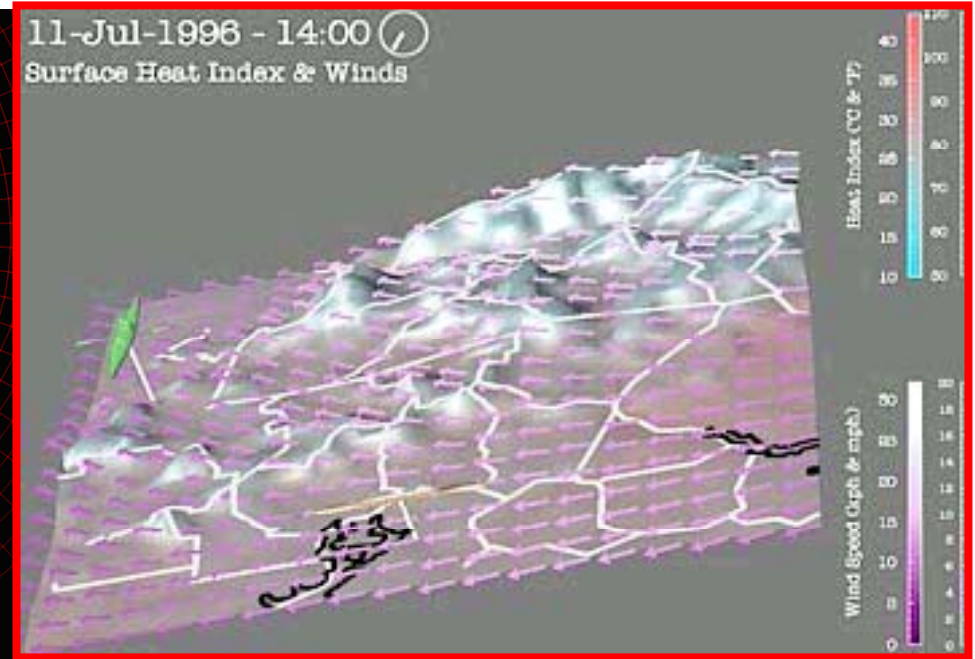
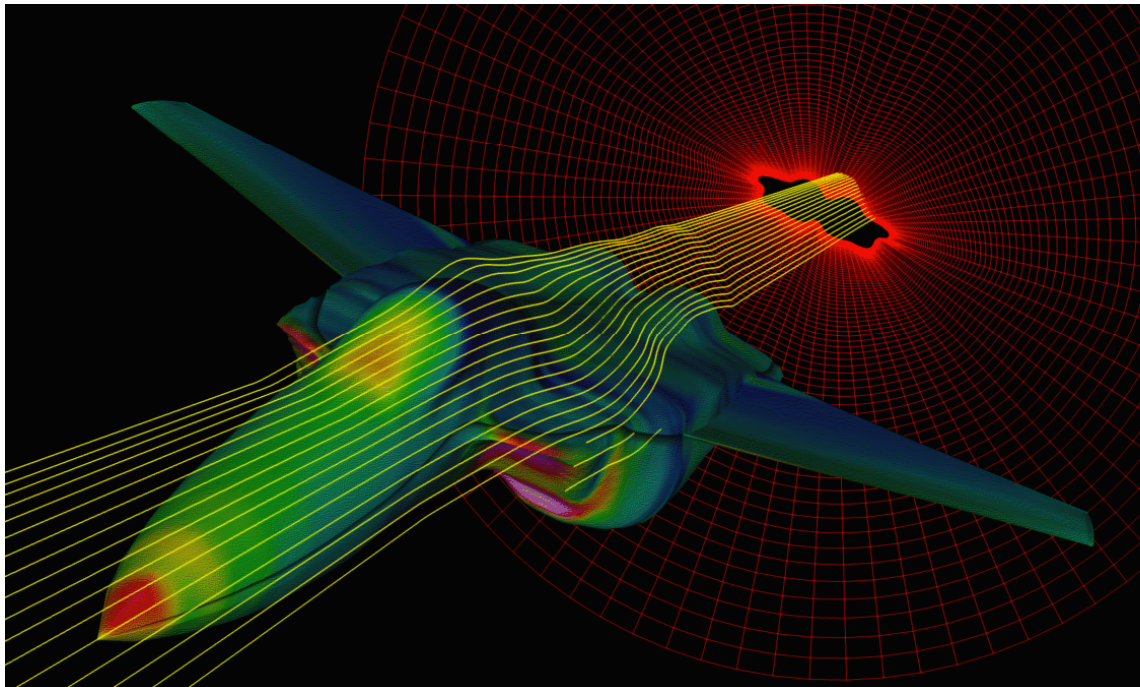
- Where do the data come from:
 - ◆ Flow simulation:
 - Airplane- / ship- / car-design
 - Weather simulation (air-, sea-flows)
 - Medicine (blood flows, etc.)
 - ◆ Flow measurements:
 - Wind tunnel, fluid tunnel
 - Schlieren-, shadow-technique
 - ◆ Flow models:
 - Differential equation systems (ODE)
(dynamical systems)



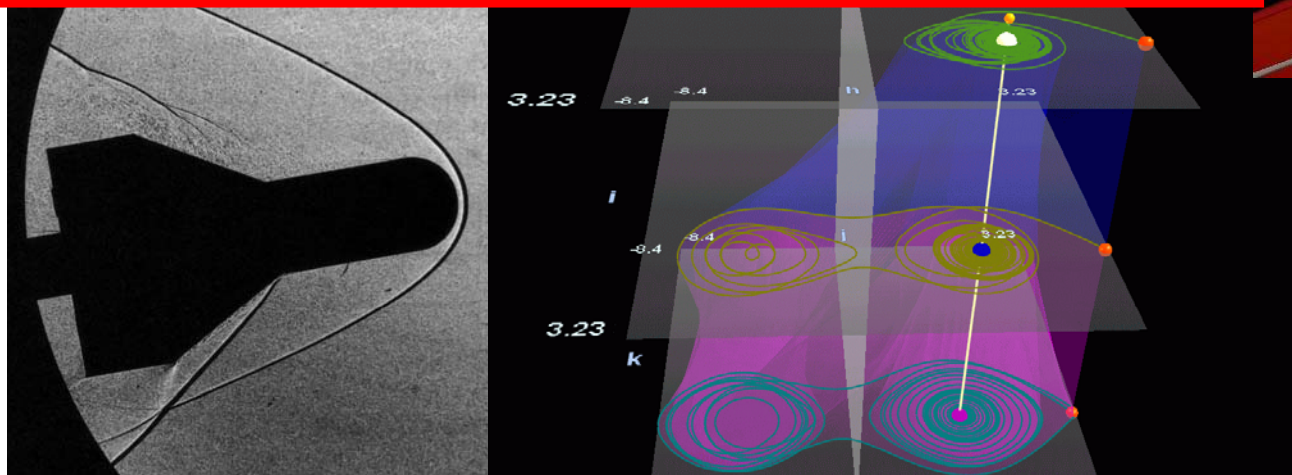
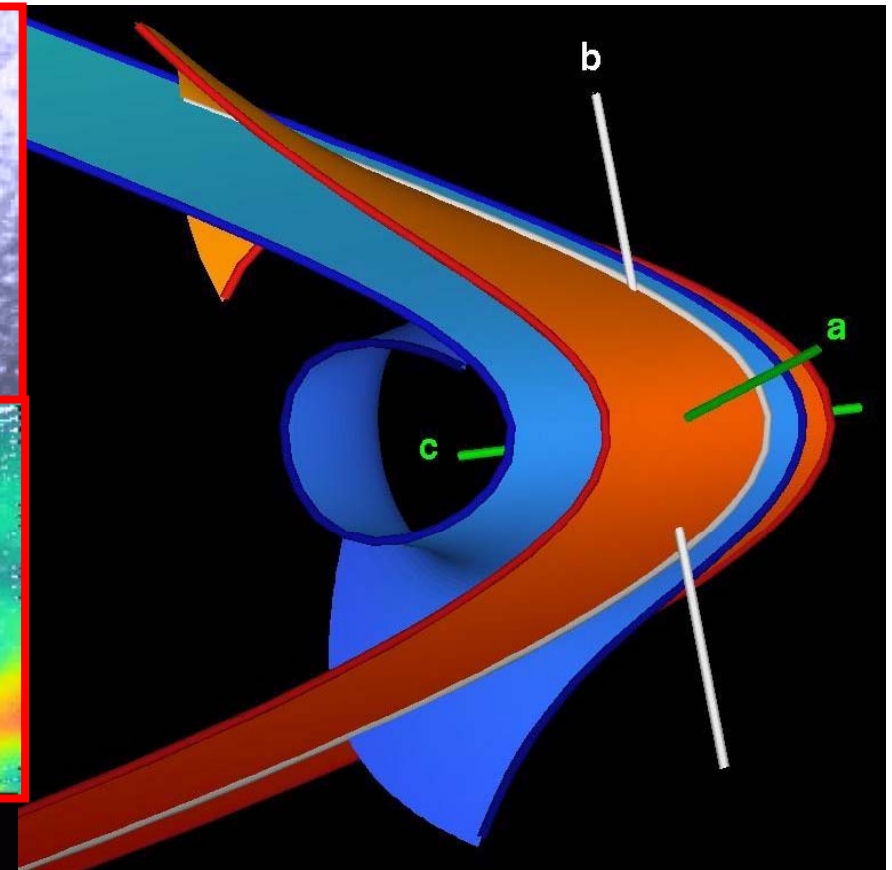
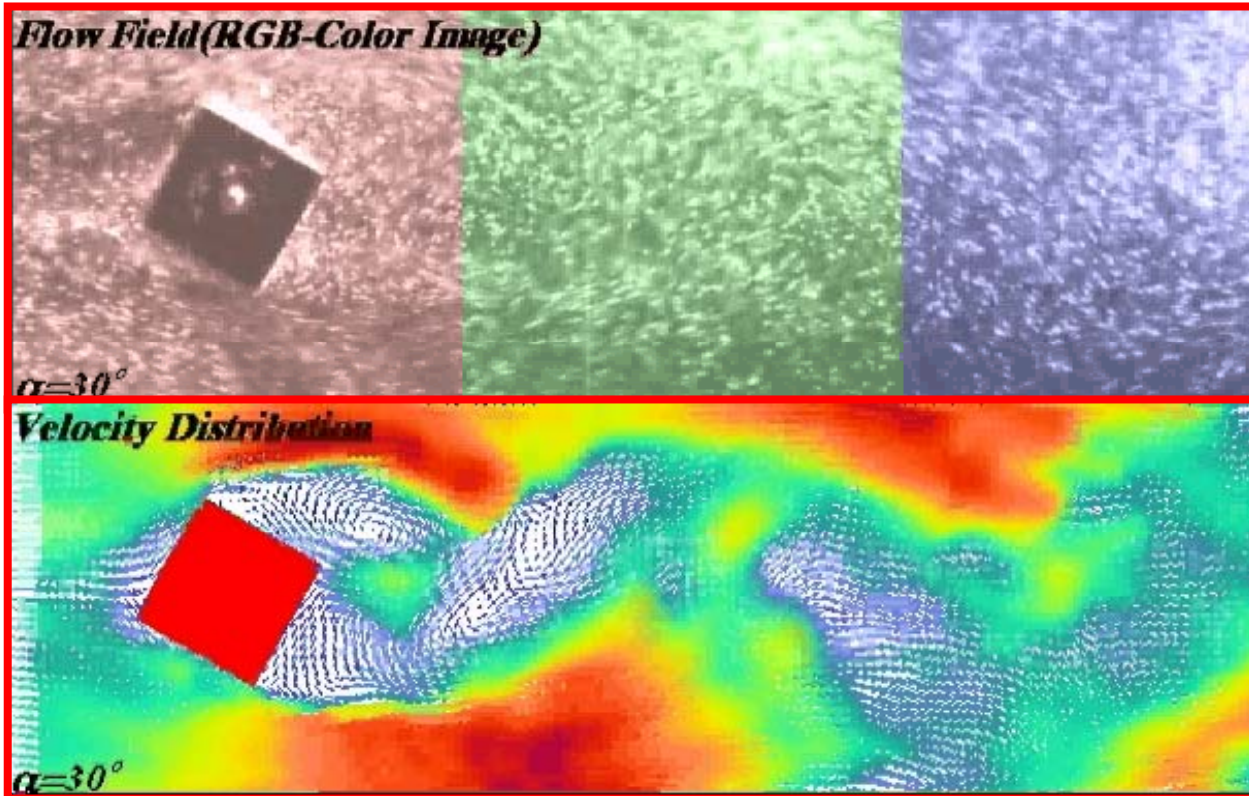
- Simulation:
 - ◆ Flow: set of samples (n dimensions of data), e.g. given on curvilinear grid
 - ◆ Most important primitive: tetrahedron (cell)
- Measurement:
 - ◆ Flow-vectors: reconstruction out of correlations, often calculated on regular grids
- Modelling:
 - ◆ Flow: analytic formula, can be evaluated “everywhere”



Data Source – Examples 1/2



Data Source – Examples 2/2



■ Simulation:

- ◆ Flow space modelled with grid
- ◆ FEM (finite elements method),
CfD (computational fluid dynamics)

■ Measurements:

- ◆ Optical methods + pattern recognition,
e.g.: PIV (particle image velocimetry)

■ Models:

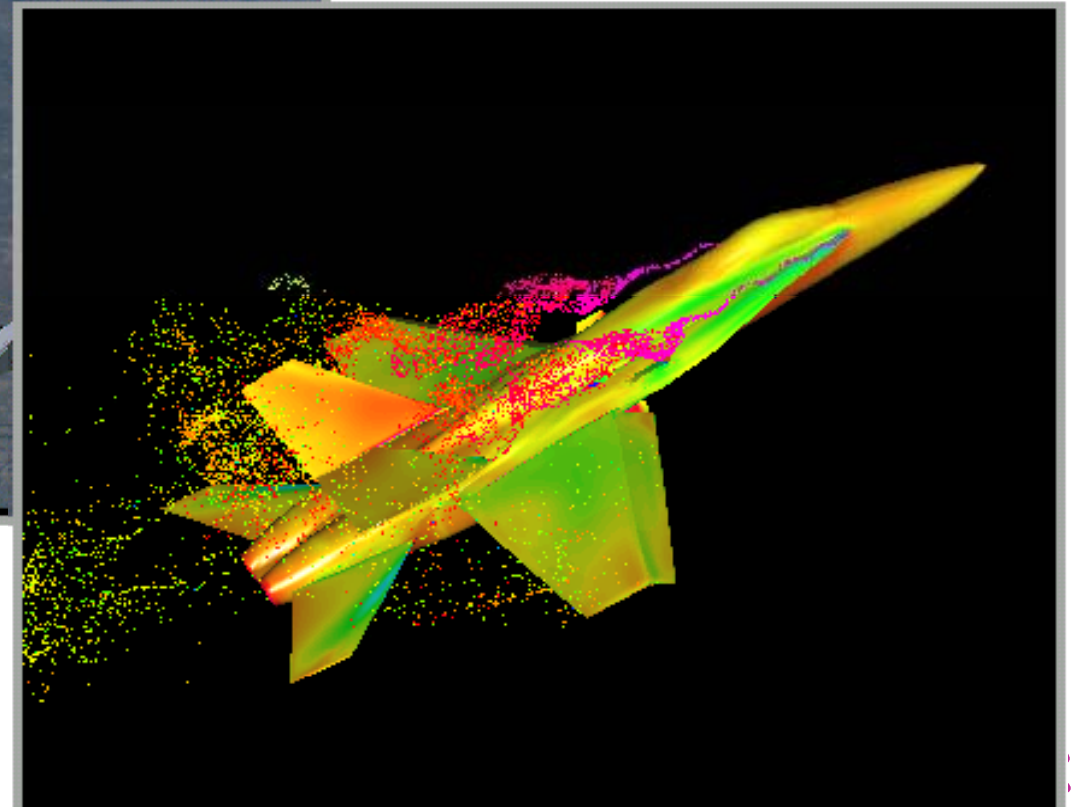
- ◆ Differential equation systems $\frac{dx}{dt}$





Experiment

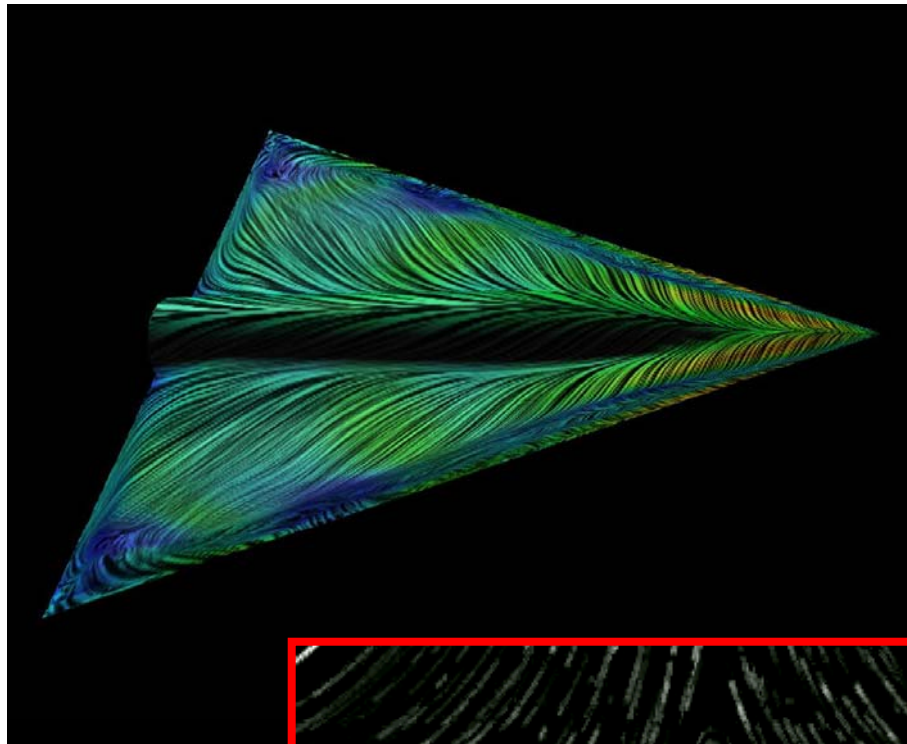
Simulation



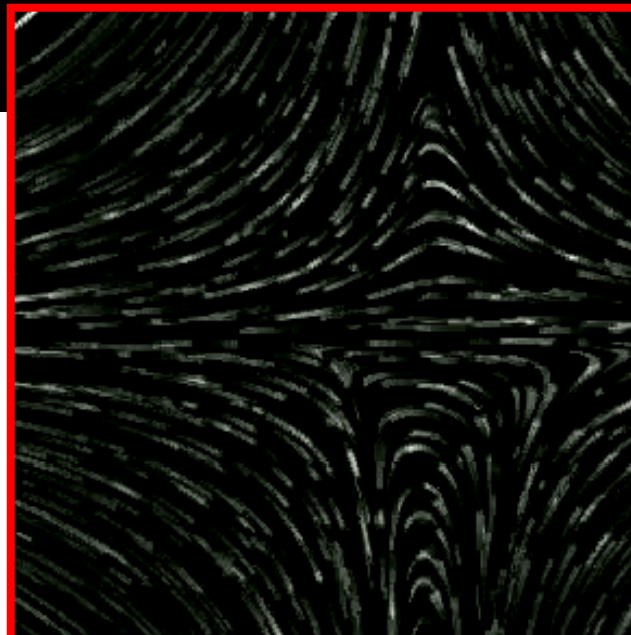
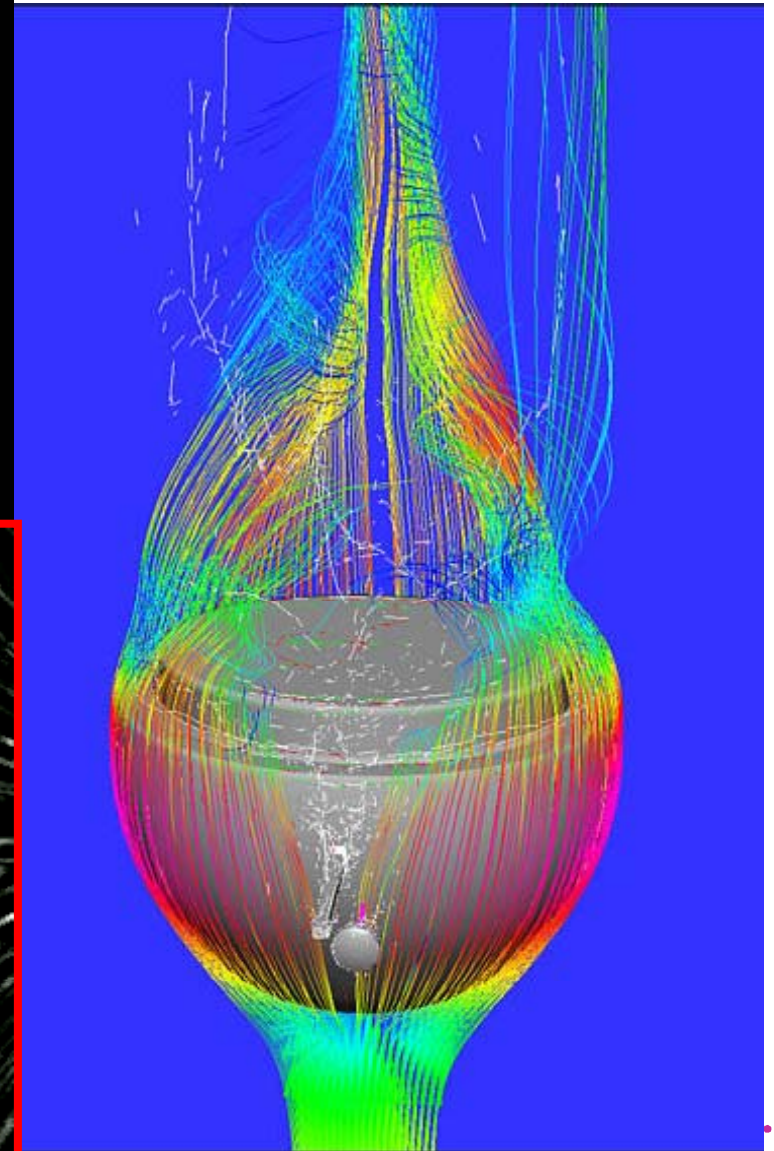
- 2D-Flow visualization
 - ◆ 2D×2D-Flows
 - ◆ Models, slice flows (2D out of 3D)
- Visualization of surface flows
 - ◆ 3D-flows around “obstacles”
 - ◆ Boundary flows on surfaces (2D)
- 3D-Flow visualization
 - ◆ 3D×3D-flows
 - ◆ Simulations, 3D-models



Surface



3D

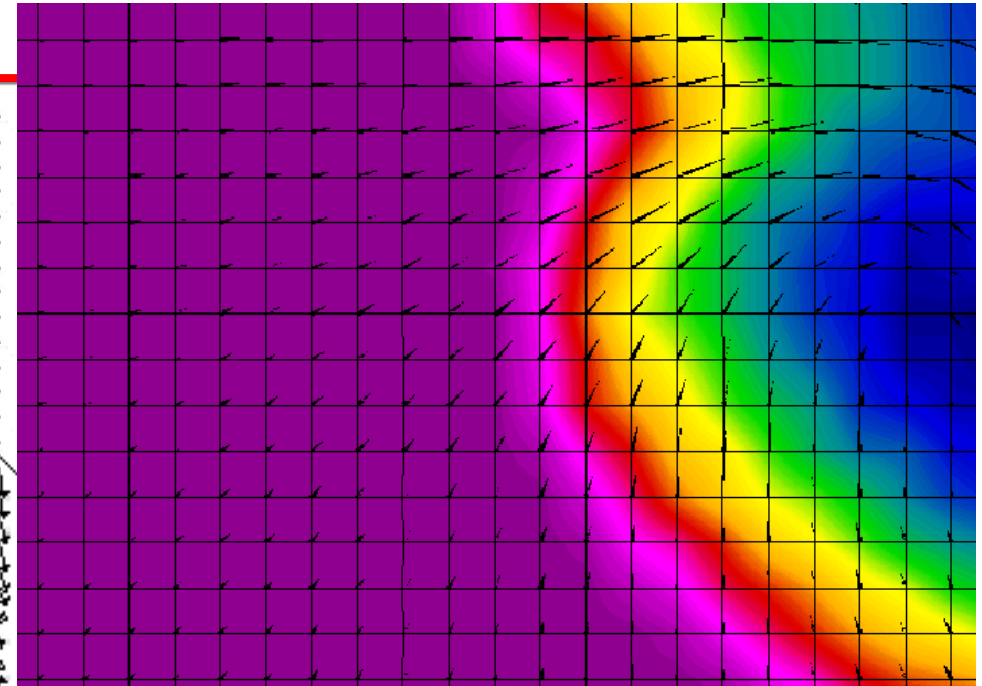
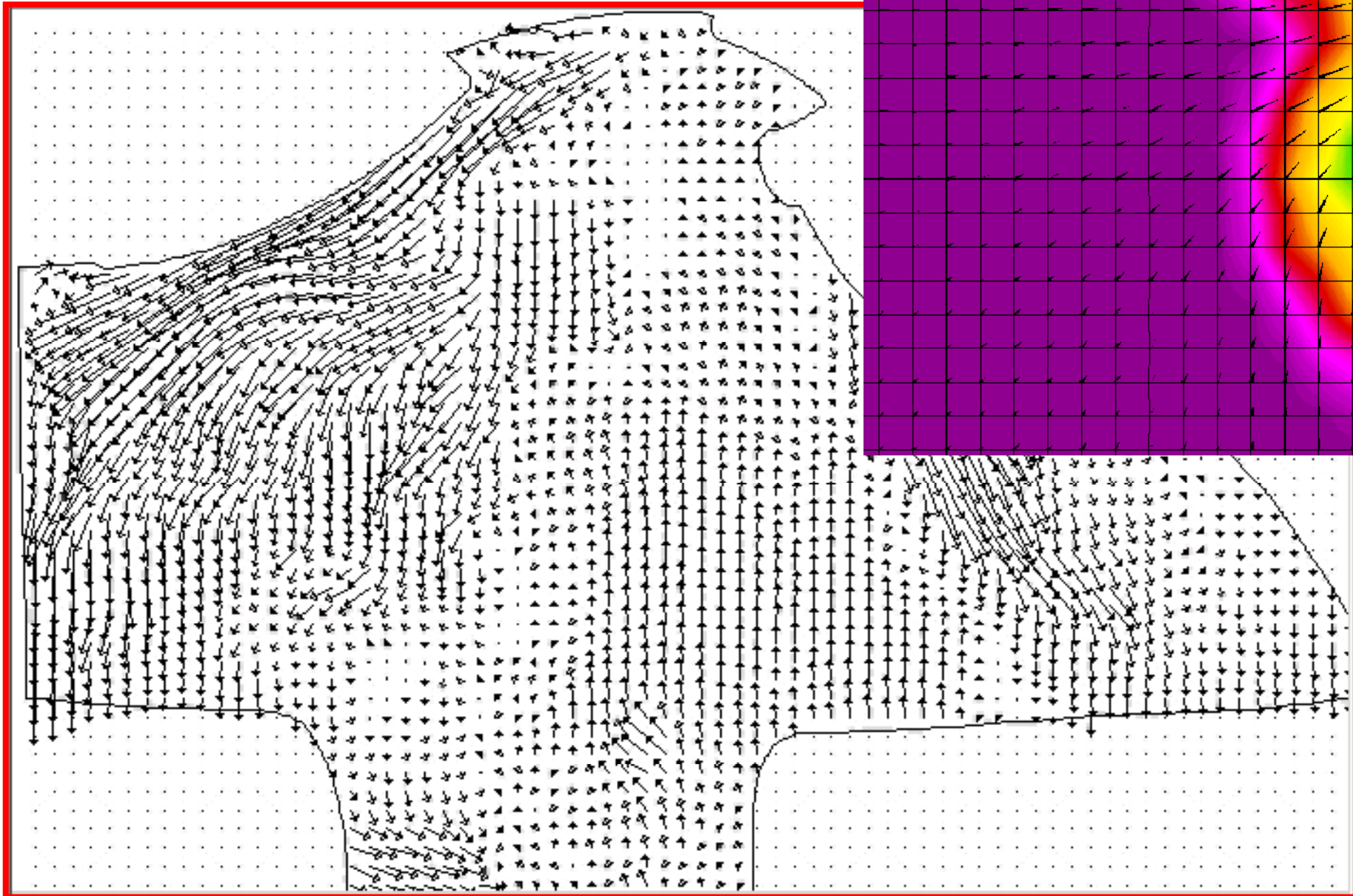


2D

- **Steady (time-independent) flows:**
 - ◆ Flow static over time
 - ◆ $\mathbf{v}(\mathbf{x}): \mathbb{R}^n \rightarrow \mathbb{R}^n$, e.g., laminar flows
 - ◆ Simpler interrelationship
- **Time-dependent (unsteady) flows:**
 - ◆ Flow itself changes over time
 - ◆ $\mathbf{v}(\mathbf{x}, t): \mathbb{R}^n \times \mathbb{R}^1 \rightarrow \mathbb{R}^n$, e.g., turbulent flows
 - ◆ More complex interrelationship



Time-Dependent vs. Steady Flow

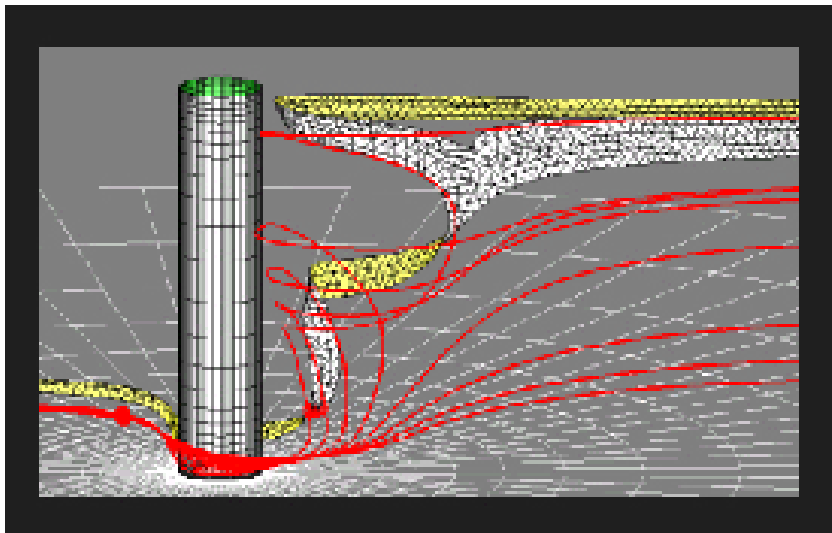


- Data size in the course of time:

Data set name and year	Number of vertices	Size (MB)
McDonnell Douglas MD-80 '89	230,000	13
McDonnell Douglas F/A-18 '91	900,000	32
Space shuttle launch vehicle '90	1,000,000	34
Space shuttle launch vehicle '93	6,000,000	216
Space shuttle launch vehicle '96	30,000,000	1,080
Advanced subsonic transport '98	60,000,000	2,160
Army UH-60 Blackhawk '99	100,000,000	~4,000

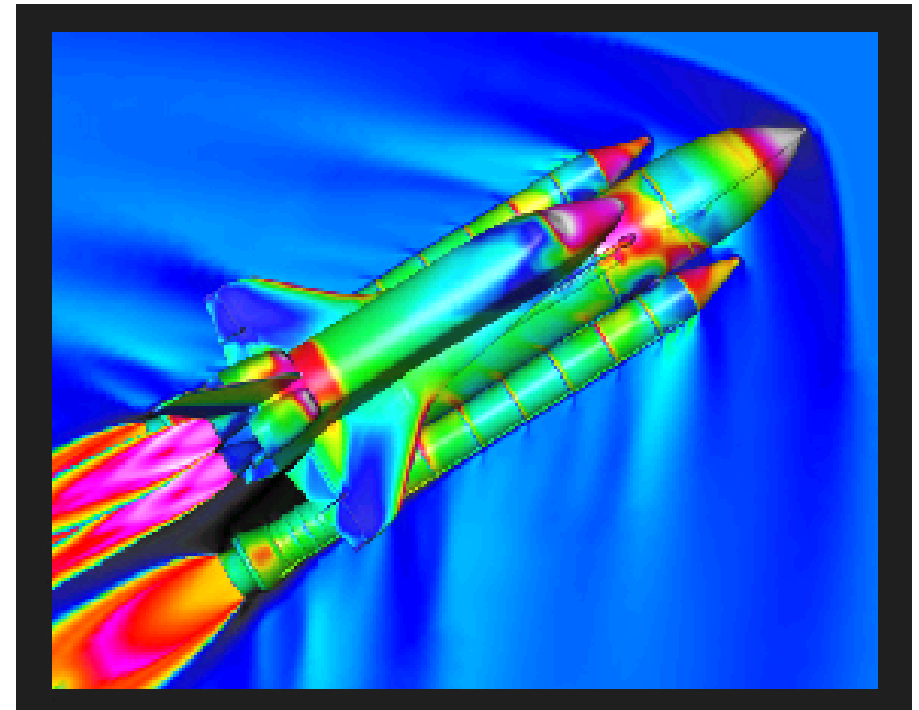


Time-Independent (Steady) Data



Single Zone
100K Nodes
4 MB

(1985)



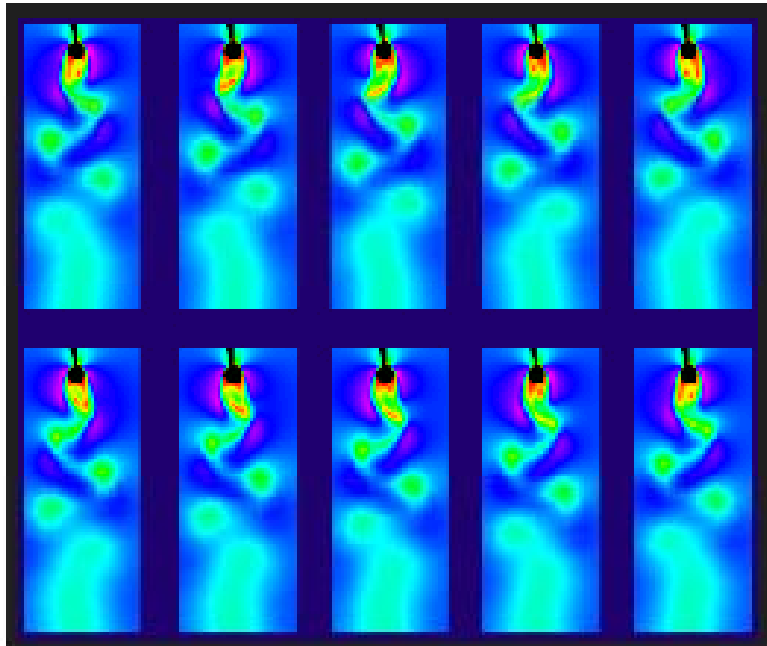
128 Zones
30M Nodes
1080 MB

(1996)

■ Historical development:

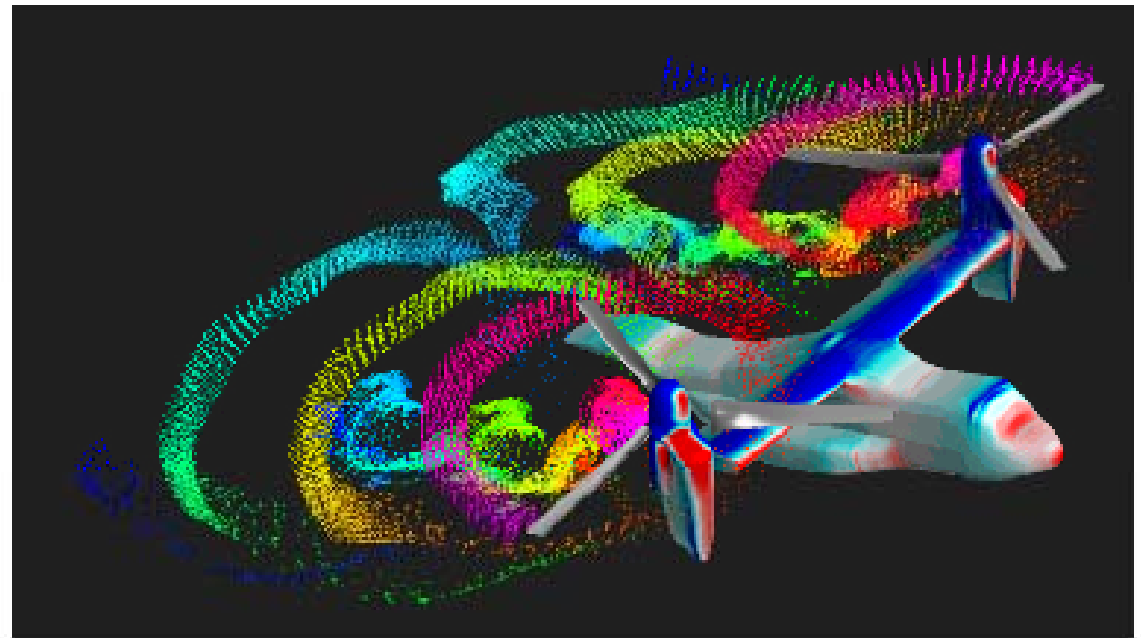
Data set name and year	# vertices	# time steps	size (MB)
Tapered Cylinder '90	131,000	400	1,050
McDonnell Douglas F/A-18 '92	1,200,000	400	12,800
Descending Delta Wing '93	900,000	1,800	64,800
Bell-Boeing V-22 tiltrotor '93	1,300,000	1,450	140,000
Bell-Boeing V-22 tiltrotor '98	10,000,000	1,450	600,000





Single Zone
128K Nodes
1 GB

(1990)



25 Zones (9 Moving)
2.8M Nodes
300 GB

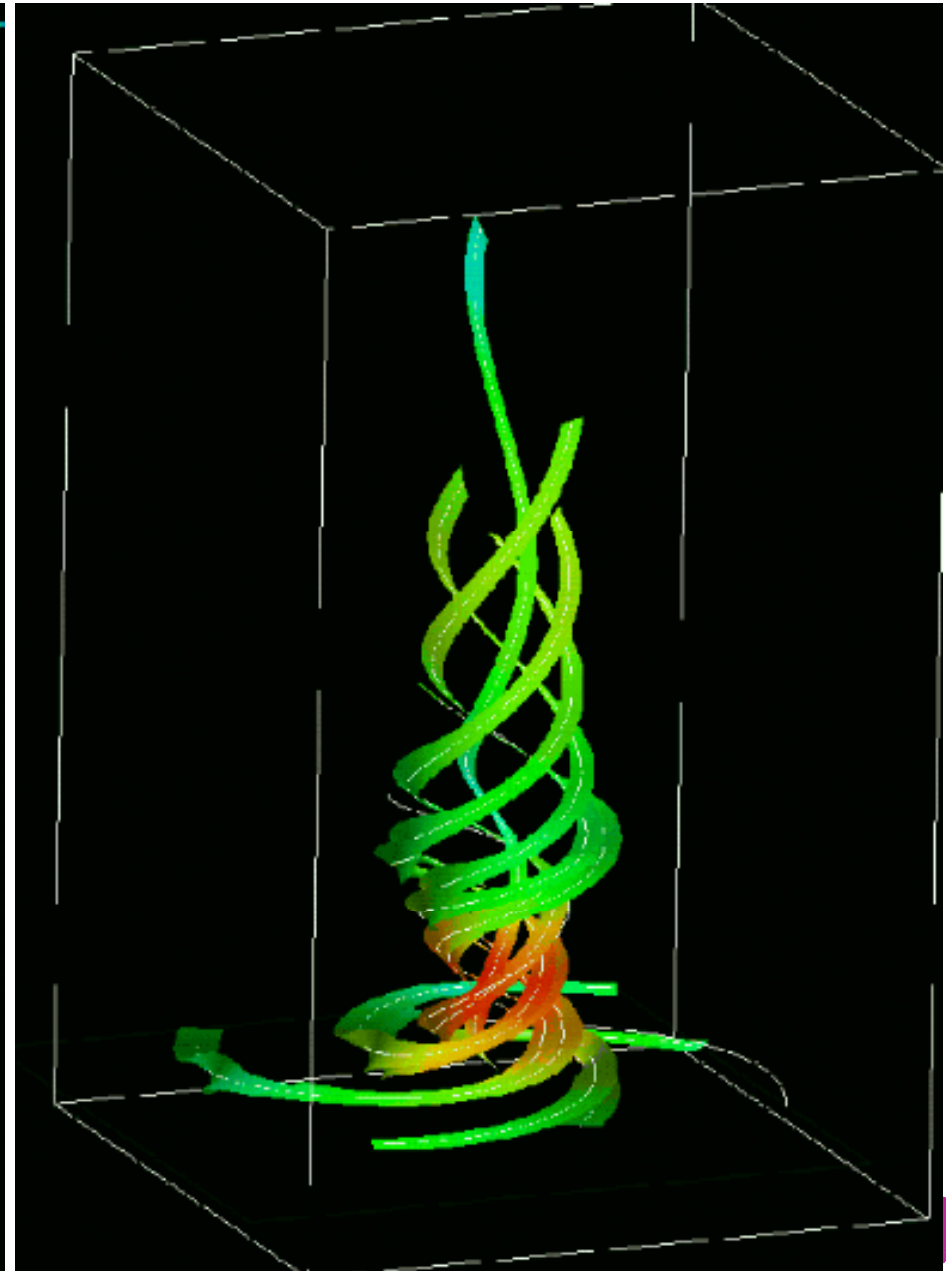
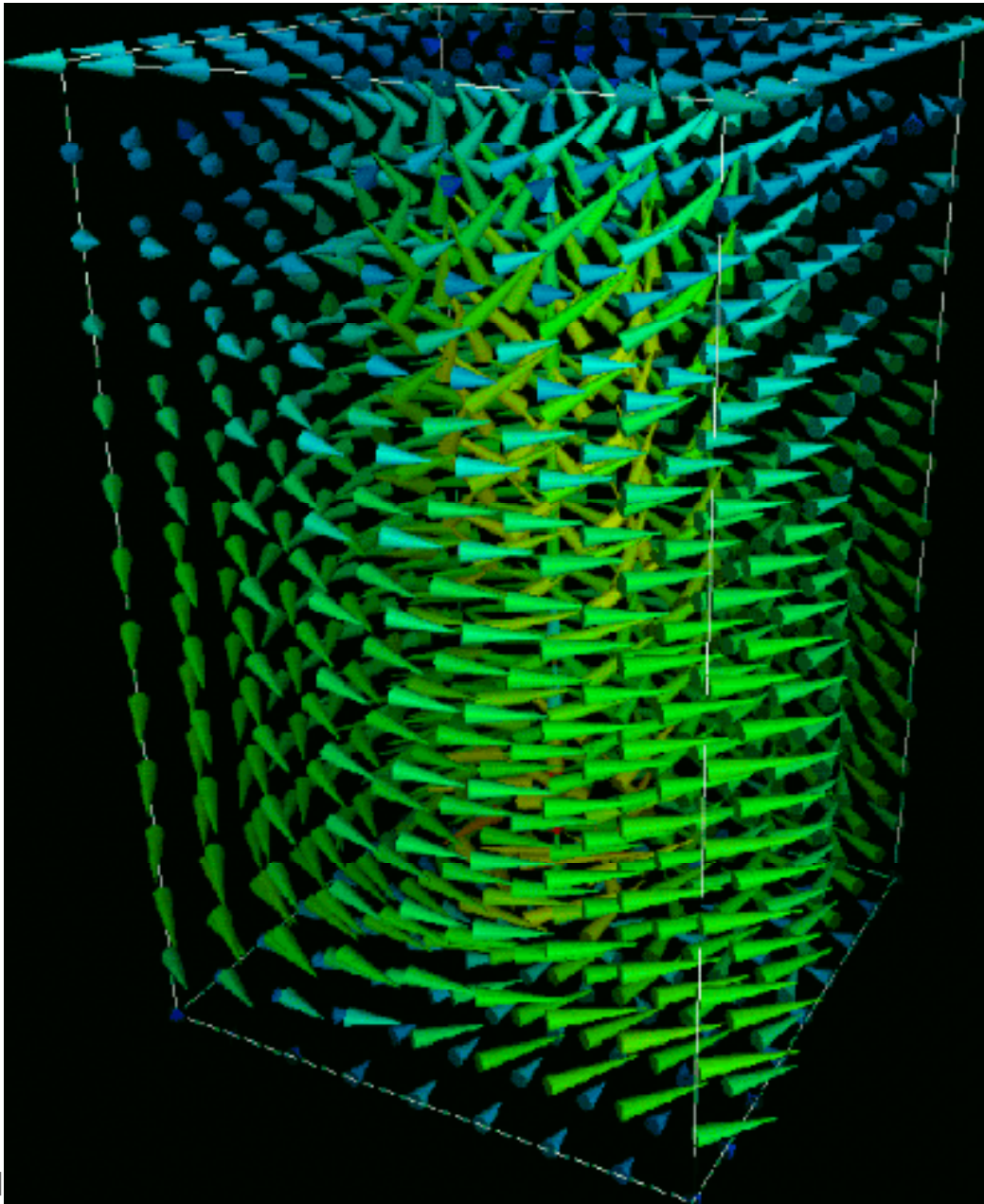
(1996)



- Direct flow visualization:
 - ◆ Overview on current flow state
 - ◆ Visualization of vectors
 - ◆ Arrow plots, smearing techniques
- Indirect flow visualization:
 - ◆ Usage of intermediate representation:
vector-field integration over time
 - ◆ Visualization of temporal evolution
 - ◆ Streamlines, streamsurfaces



Direct vs. Indirect Flow Vis. – Example

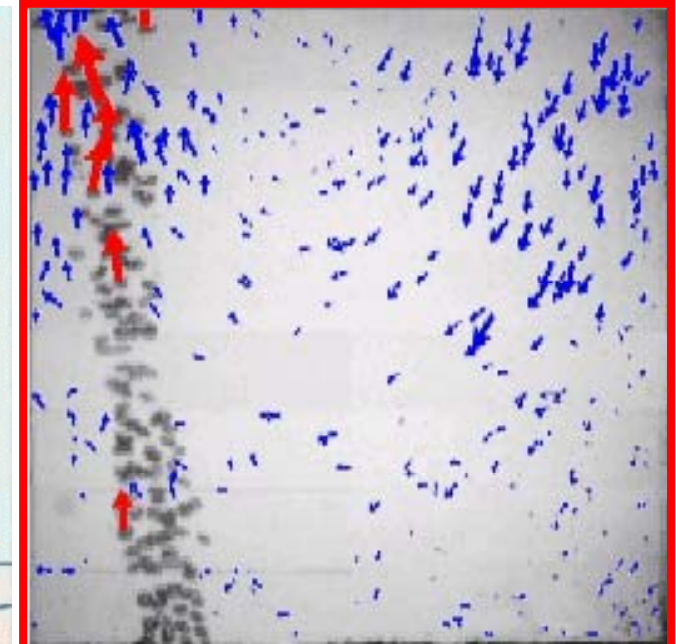
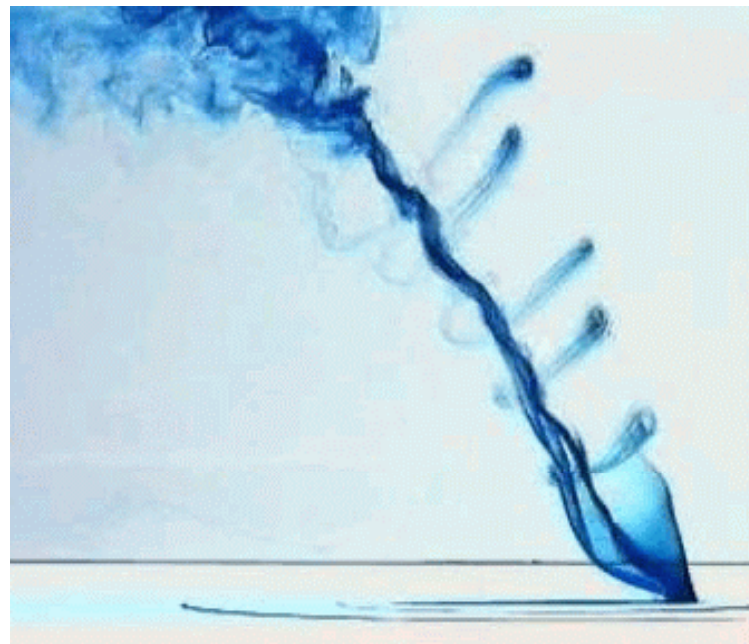
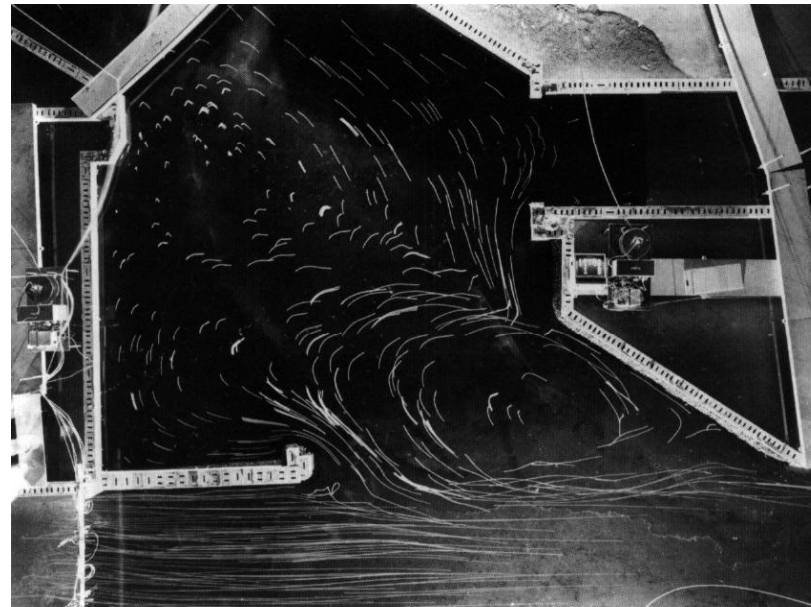


Experimental Flow Visualization

Optical Methods, etc.

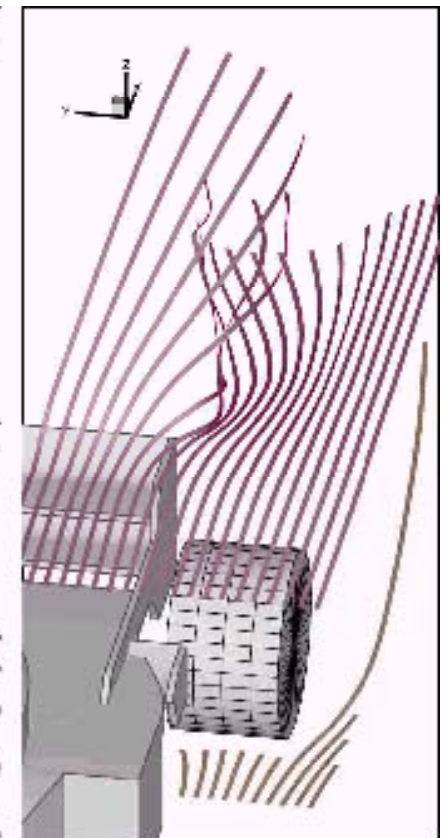
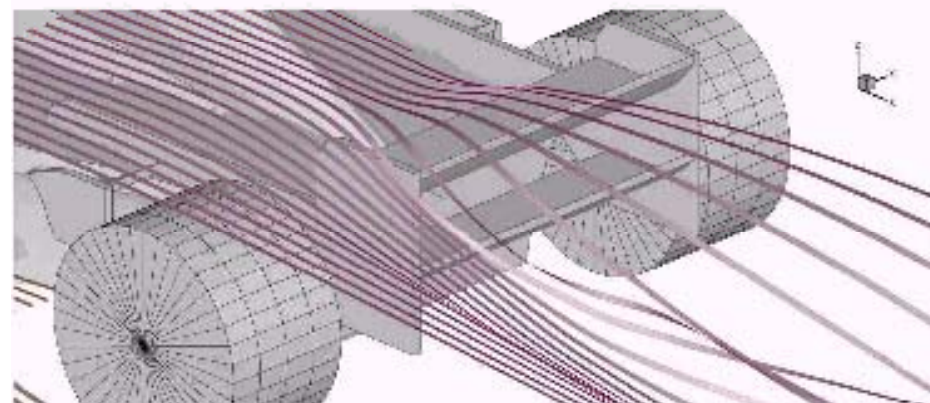
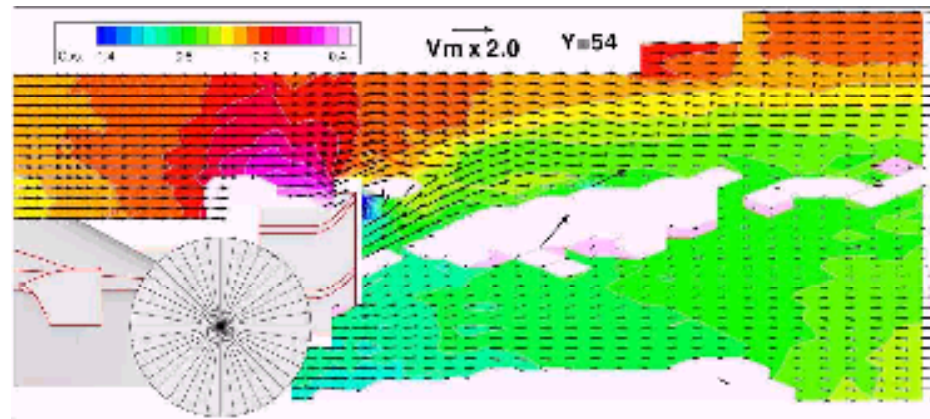


- Injection of color, smoke, particles
- Optical methods:
 - ◆ Schlieren, shadows



Example: Car-Design

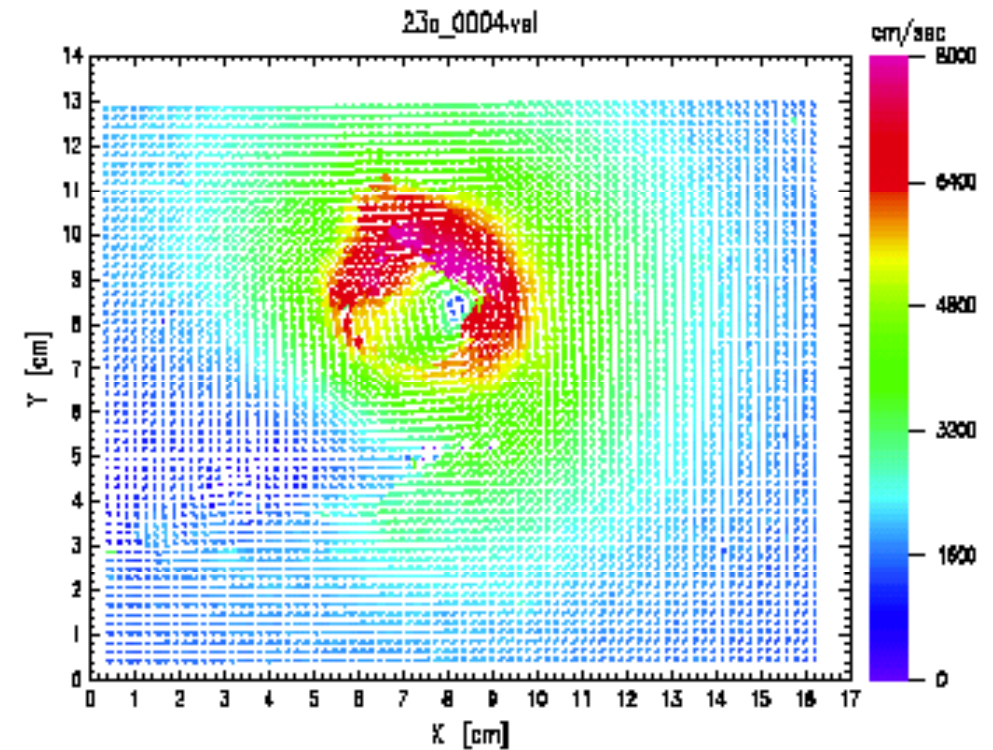
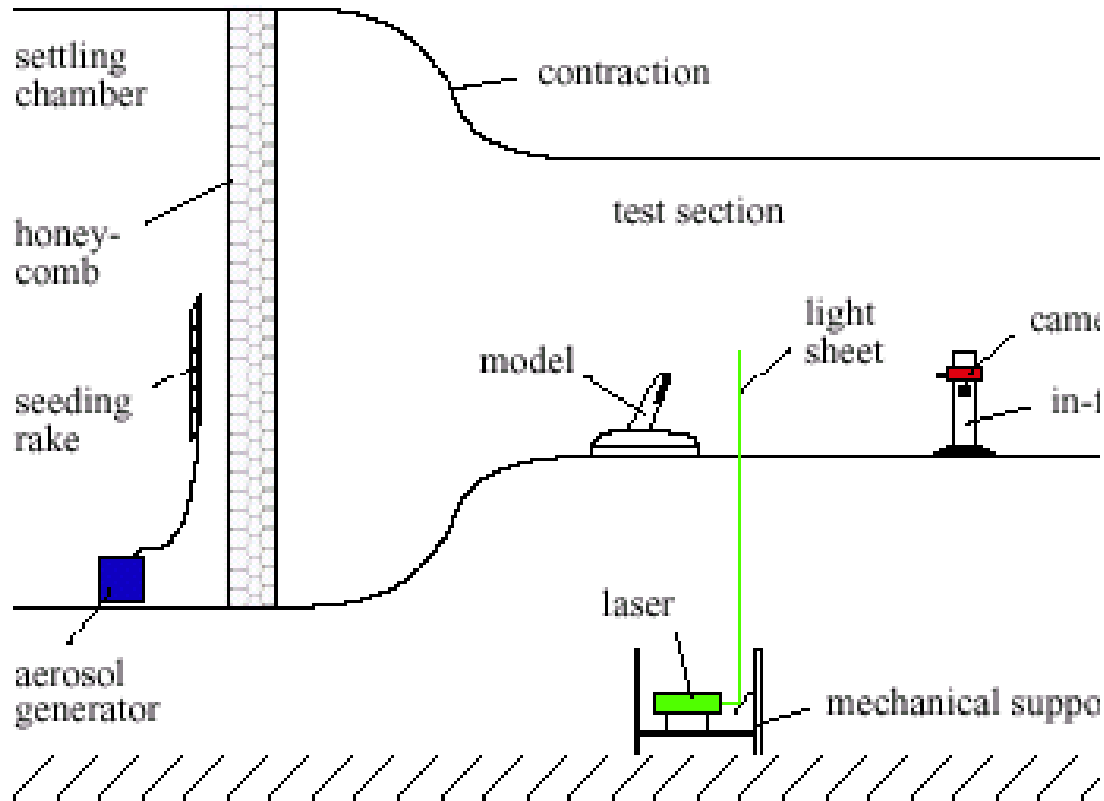
- Ferrari-model, so-called five-hole probe (no back flows)



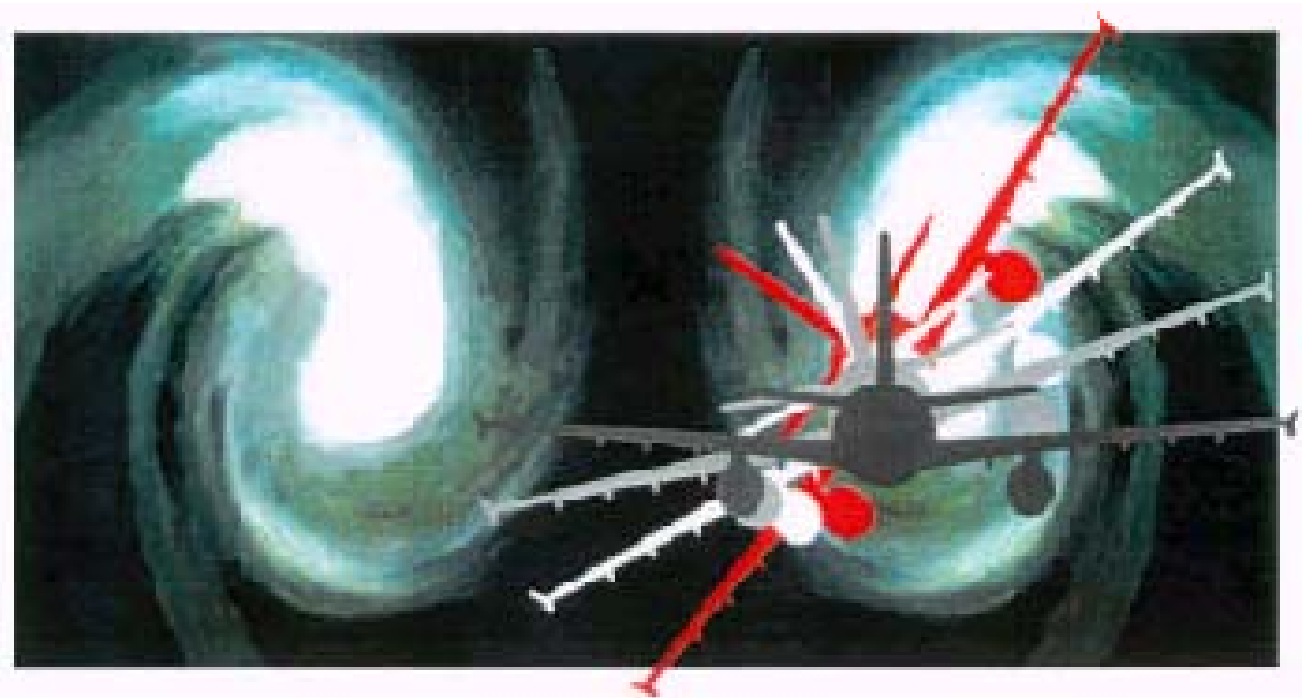
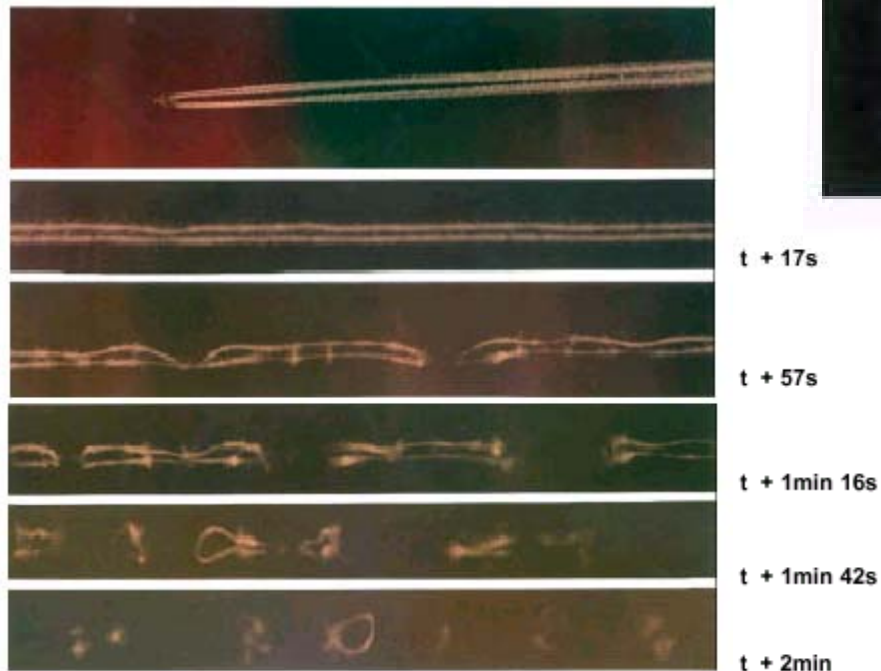
- Laser + correlation analysis:
 - ◆ Real flow, e.g., in wind tunnel
 - ◆ Injection of particles (as uniform as possible)
 - ◆ At interesting locations:
2-times fast illumination with laser-slice
 - ◆ Image capture (high-speed camera),
then correlation analysis of particles
 - ◆ Vector calculation / reconstruction,
typically only 2D-vectors



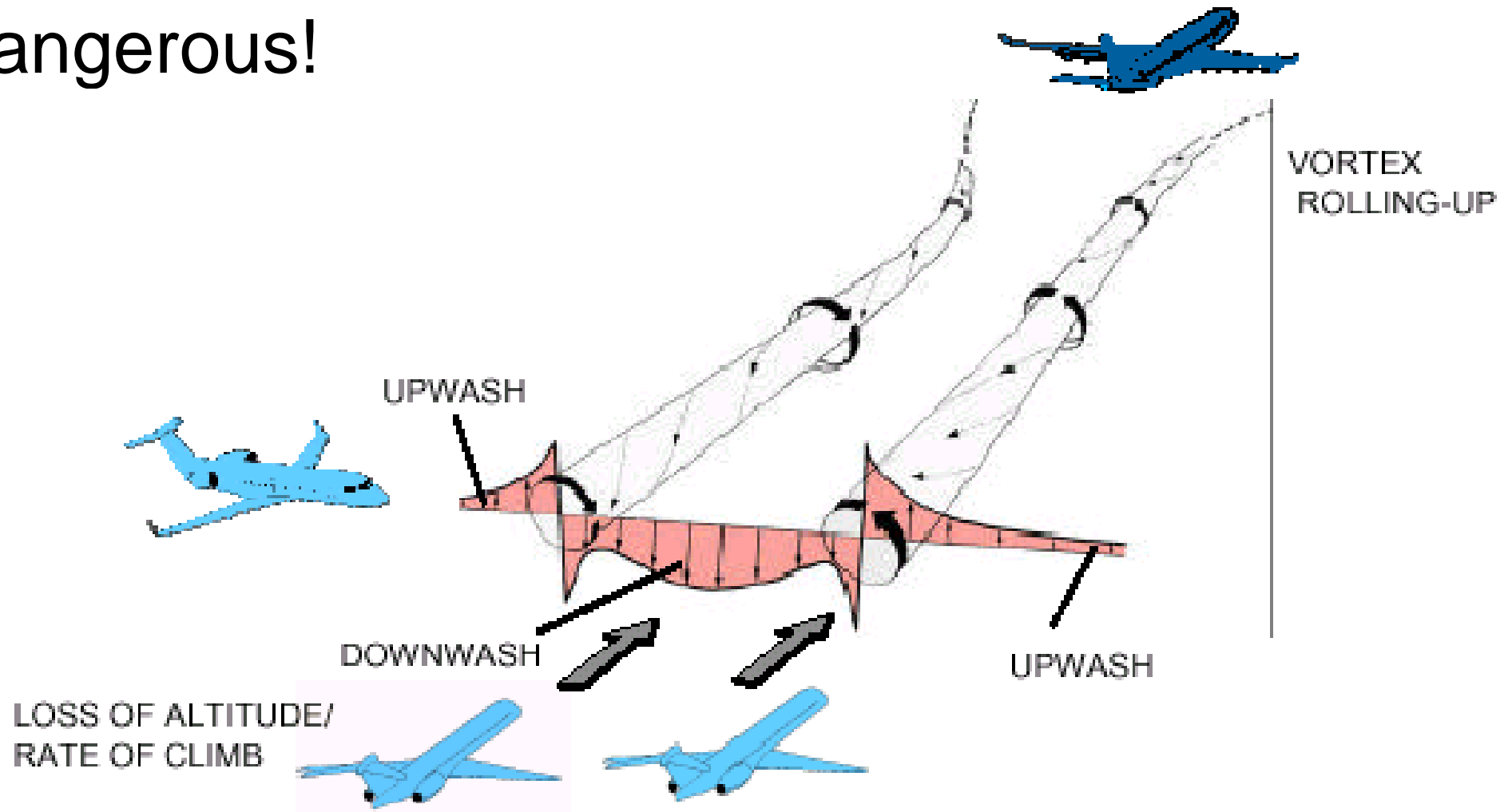
■ Setup and typical result:



- Problem: Air behind airplanes is turbulent

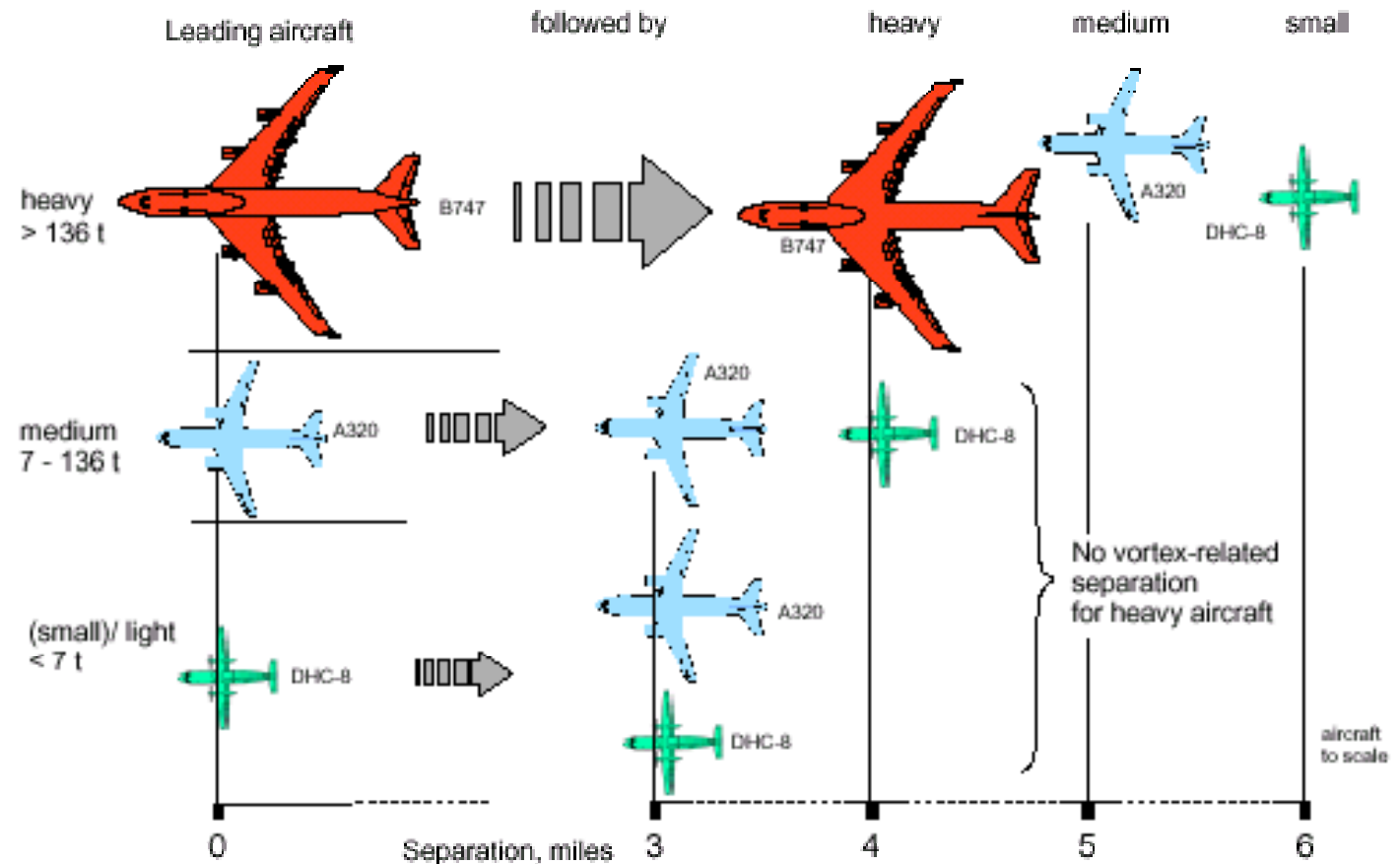


- Vortex:
dangerous!



Example: Wing-Tip Vortex 3/7

- Therefore:
keep
distance!



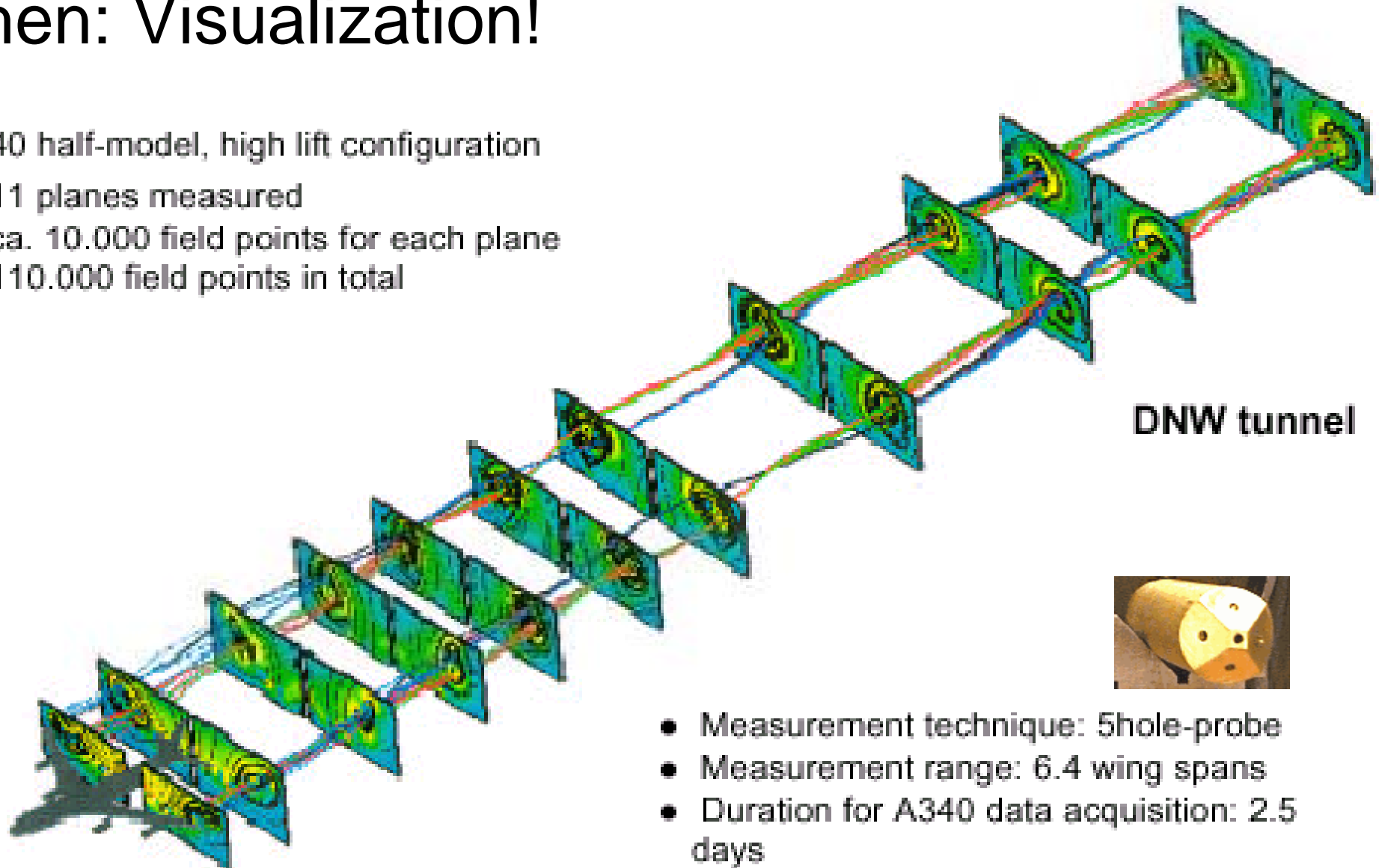
- Tests in wind tunnel:



■ Then: Visualization!

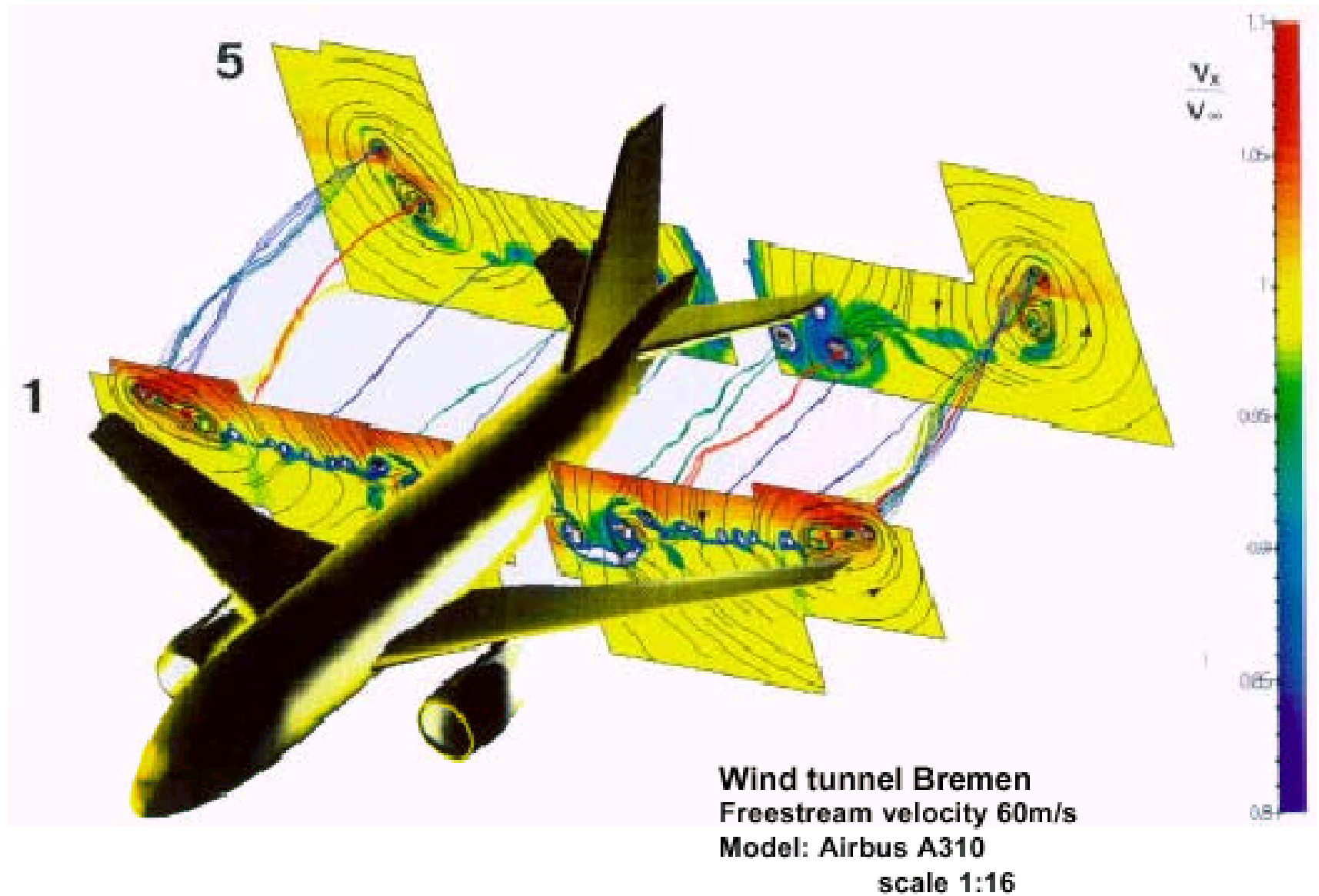
A340 half-model, high lift configuration

- 11 planes measured
- ca. 10.000 field points for each plane
- 110.000 field points in total

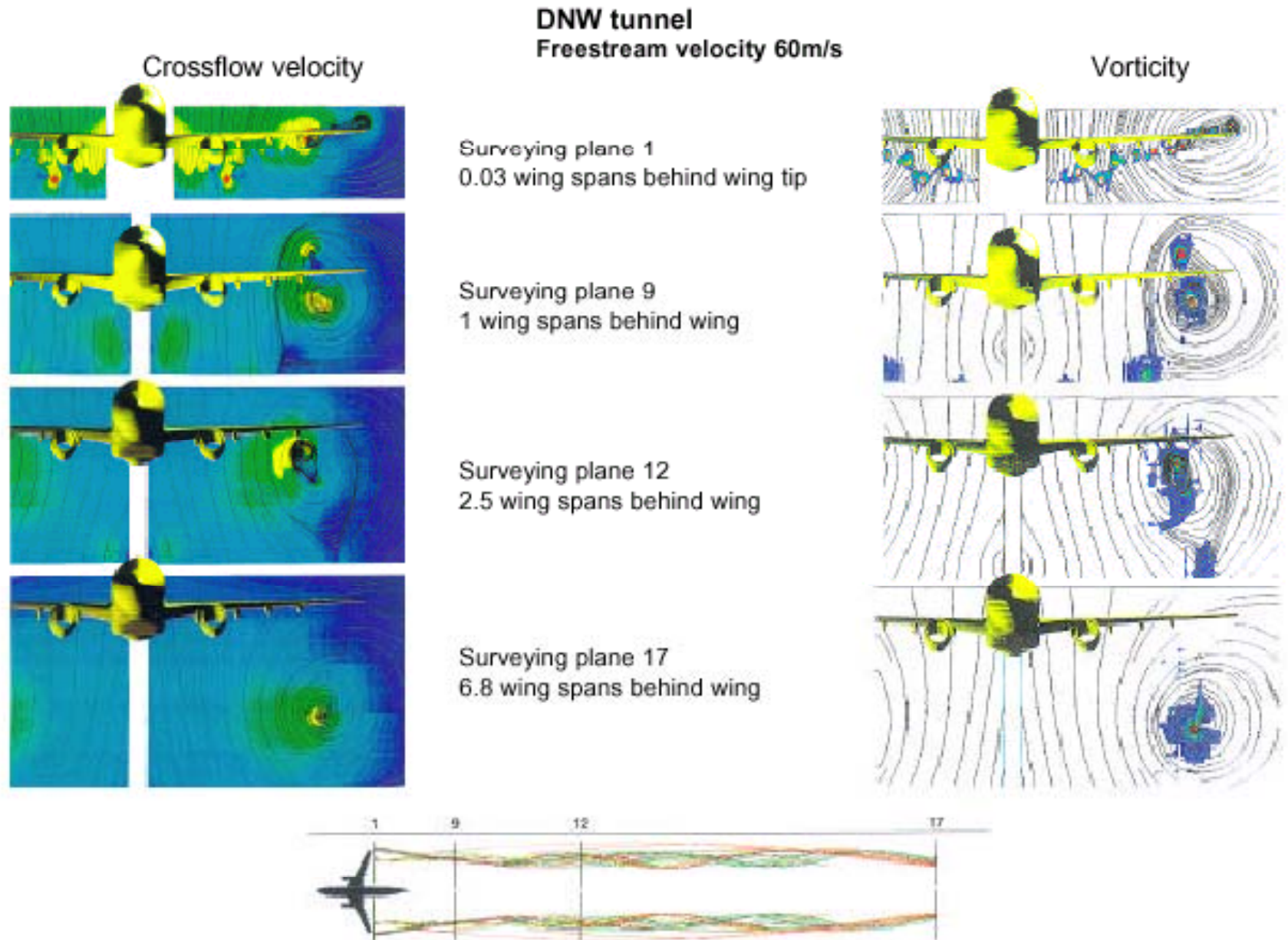


- Measurement technique: 5hole-probe
- Measurement range: 6.4 wing spans
- Duration for A340 data acquisition: 2.5 days

Example: Wing-Tip Vortex 6/7



Example: Wing-Tip Vortex 7/7



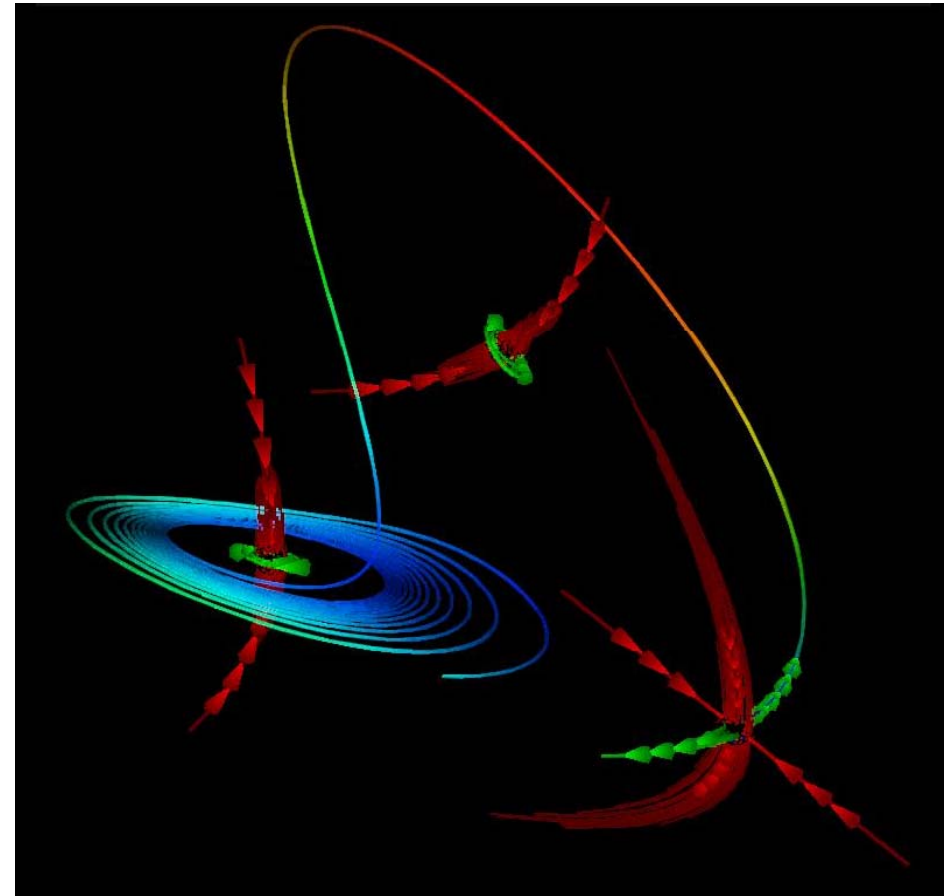
Visualization of Models

Dynamical Systems

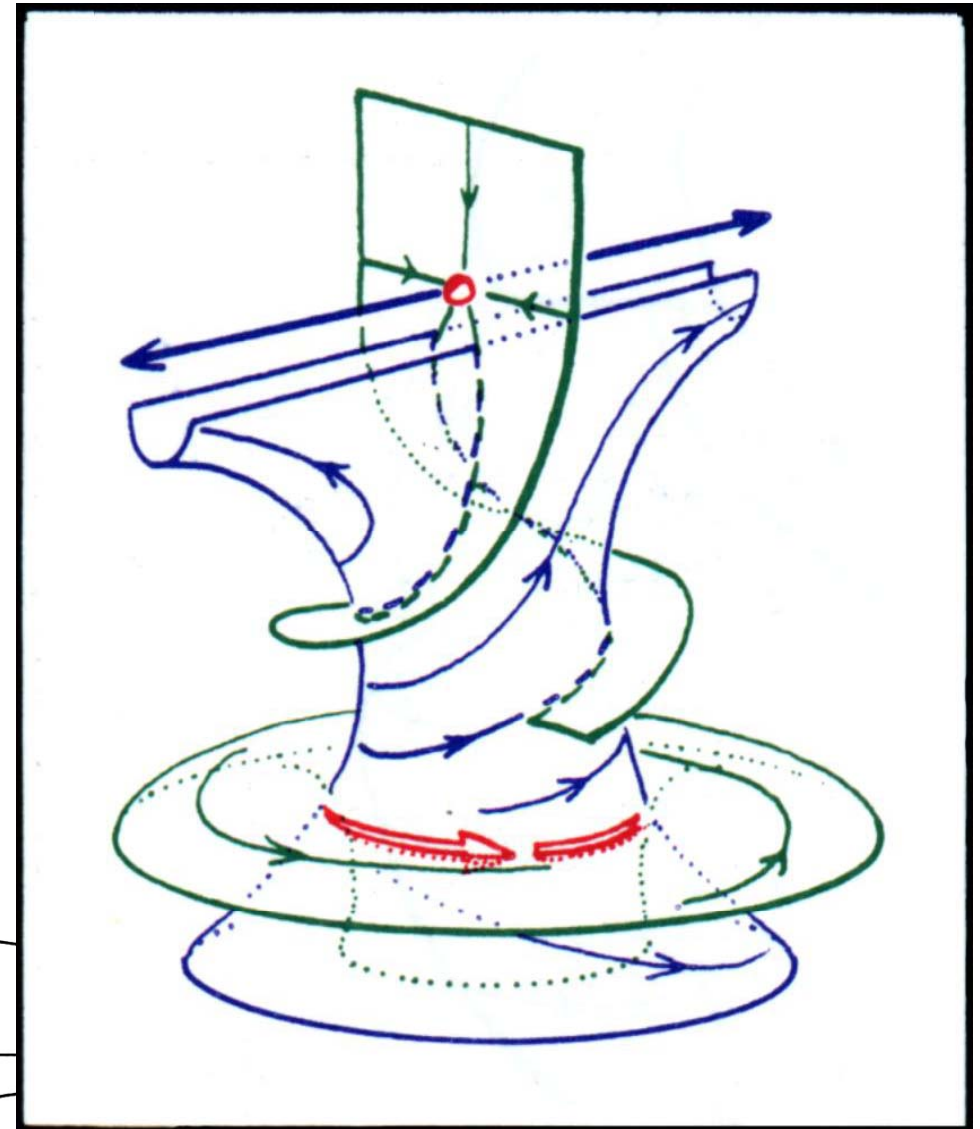
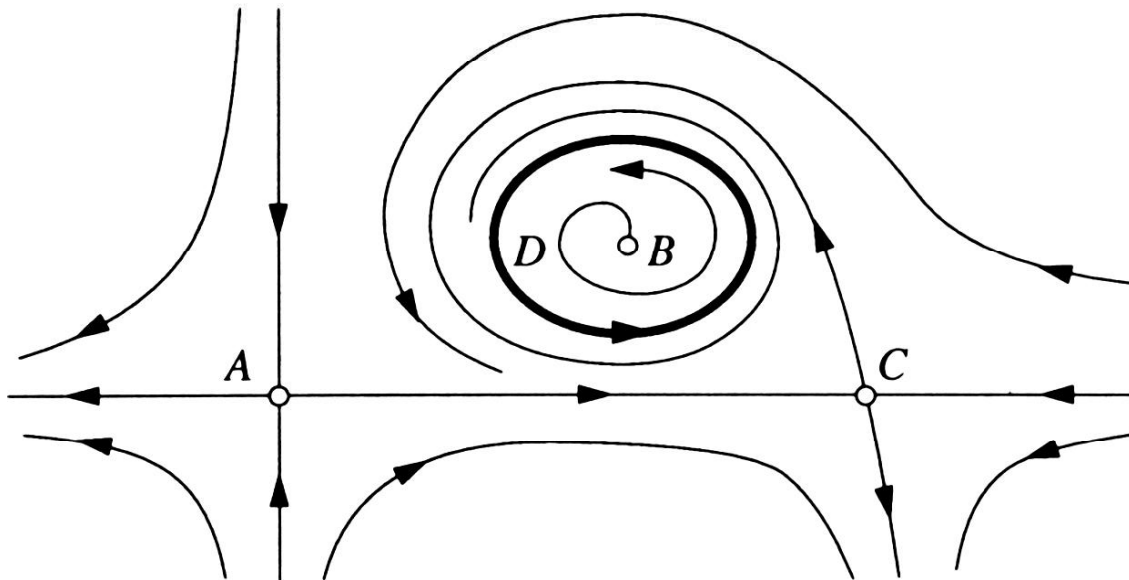


■ Differences:

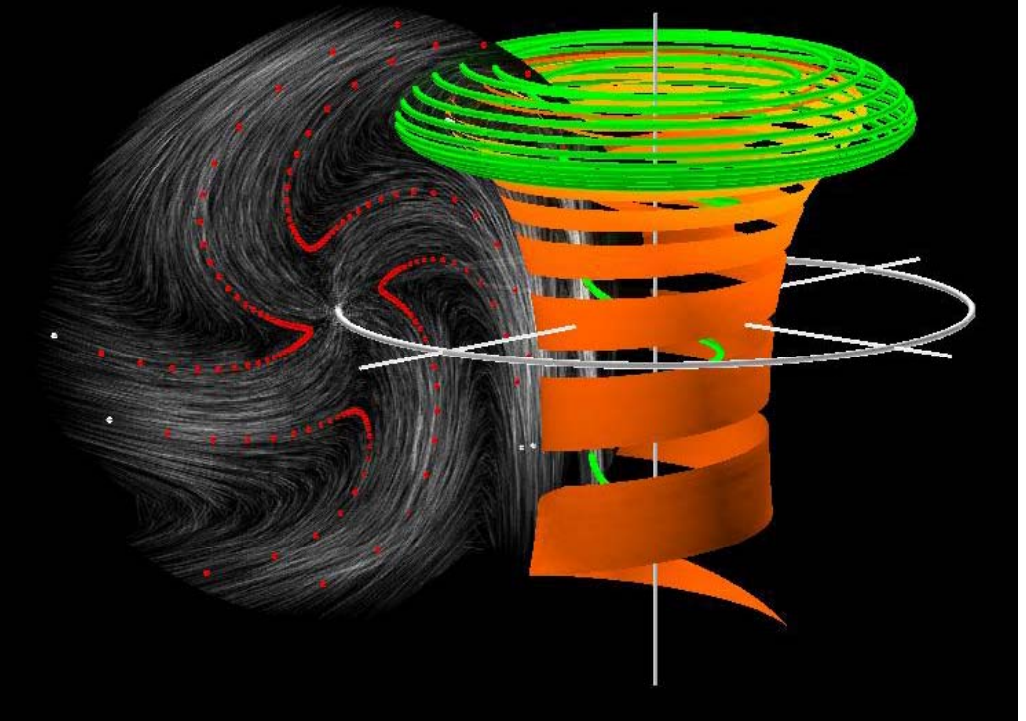
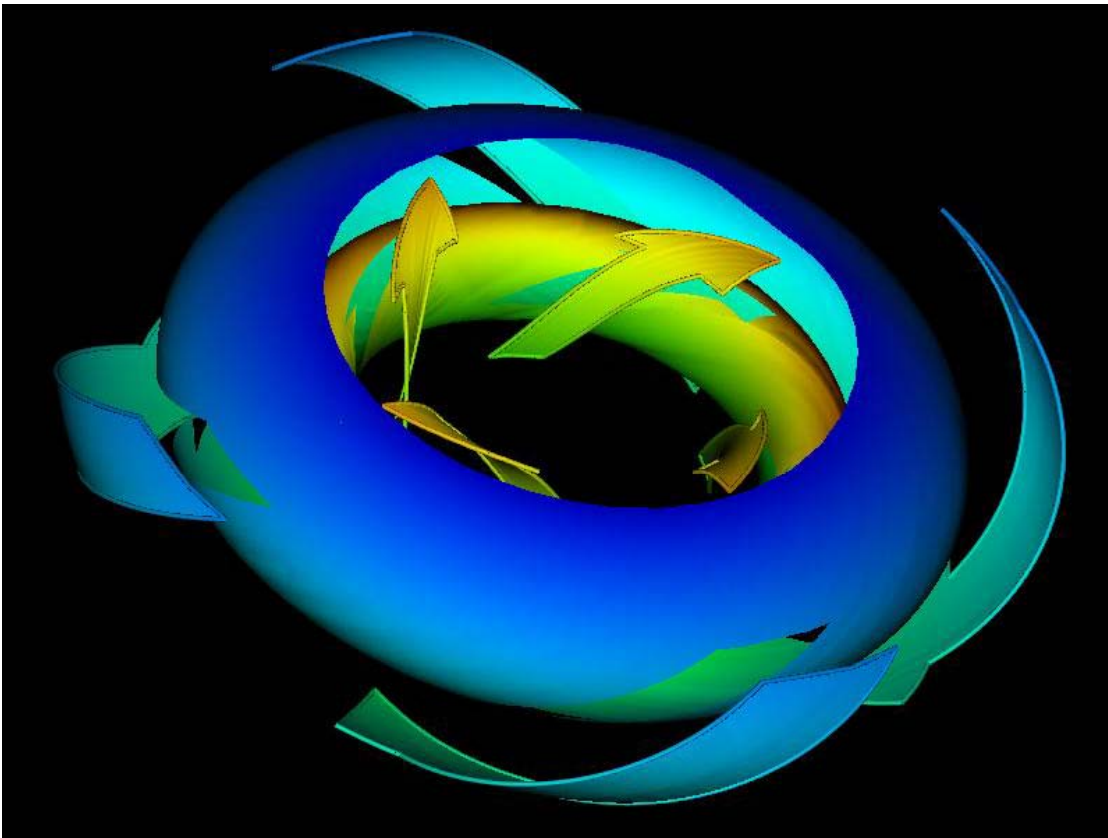
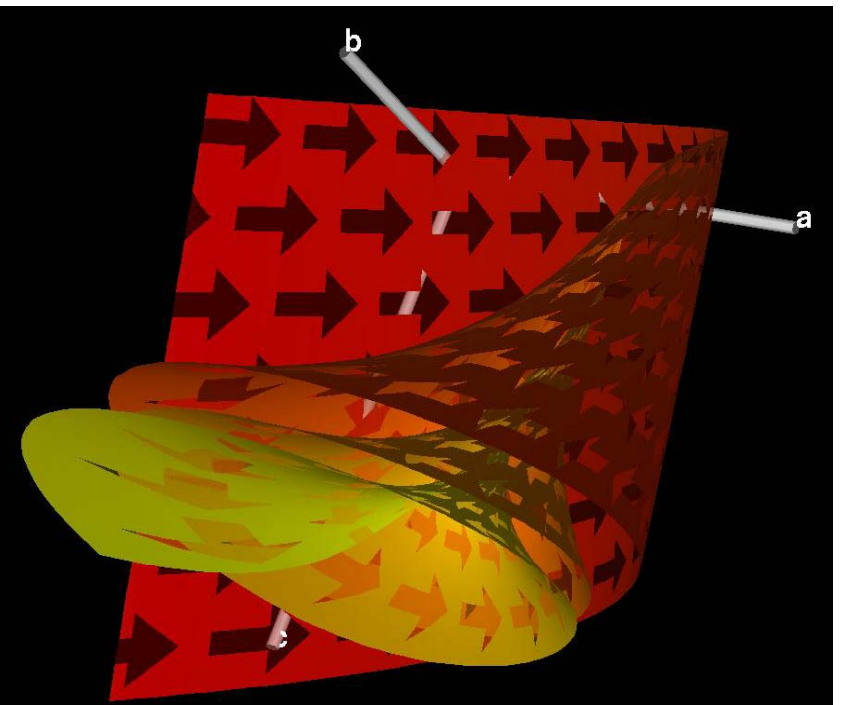
- ◆ Flow analytically def.:
 $\mathbf{dx}/dt = \mathbf{v}(\mathbf{x})$
- ◆ Navier-Stokes equations
- ◆ E.G.: Lorenz-system:
 $dx/dt = \sigma(y-x)$
 $dy/dt = rx-y-xz$
 $dz/dt = xy-bz$
- ◆ Larger variety in data:
 - 2D, 3D, nD
 - Sometimes no natural constraints like non-compressibility or similar



- Sketchy,
“hand drawn”



Visualization of 3D Models

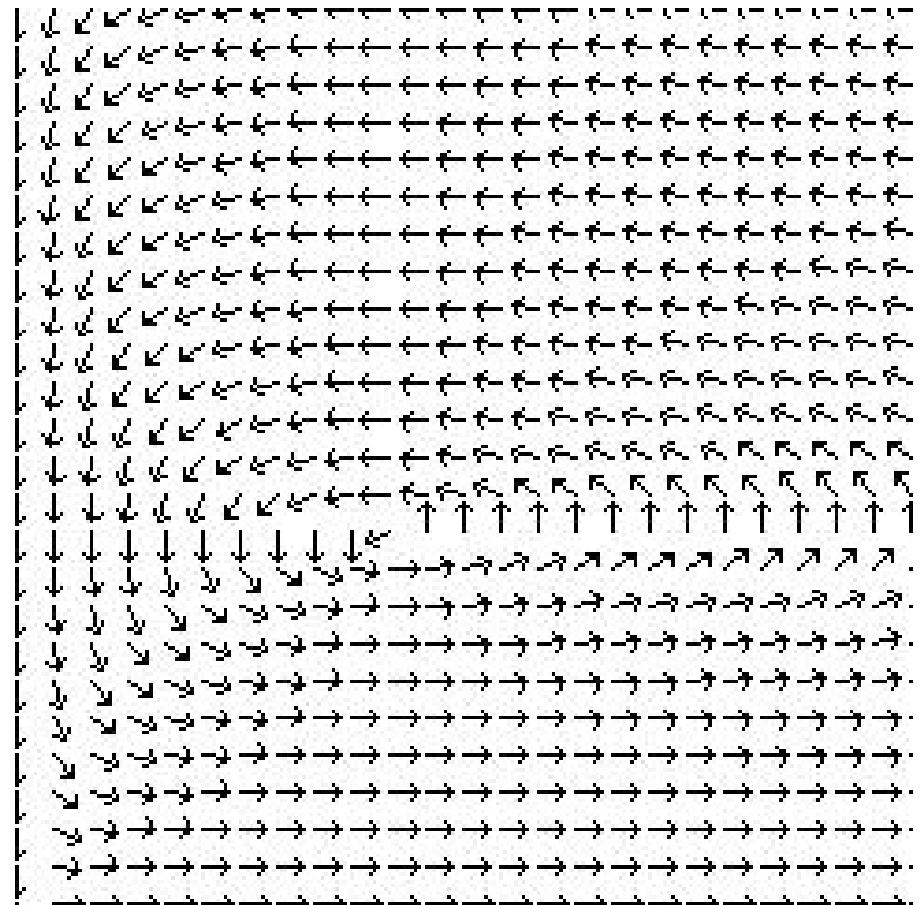


Flow Visualization with Arrows

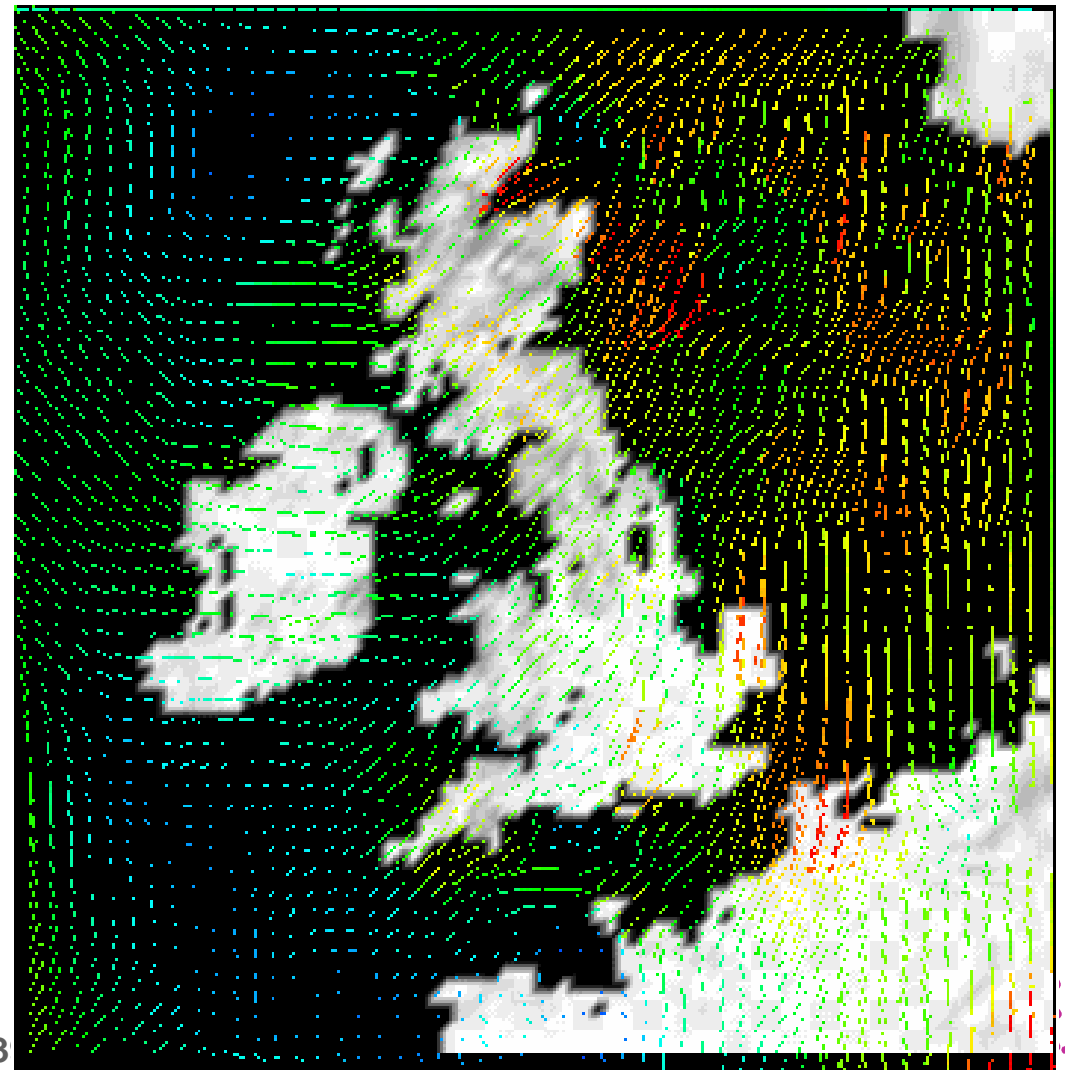
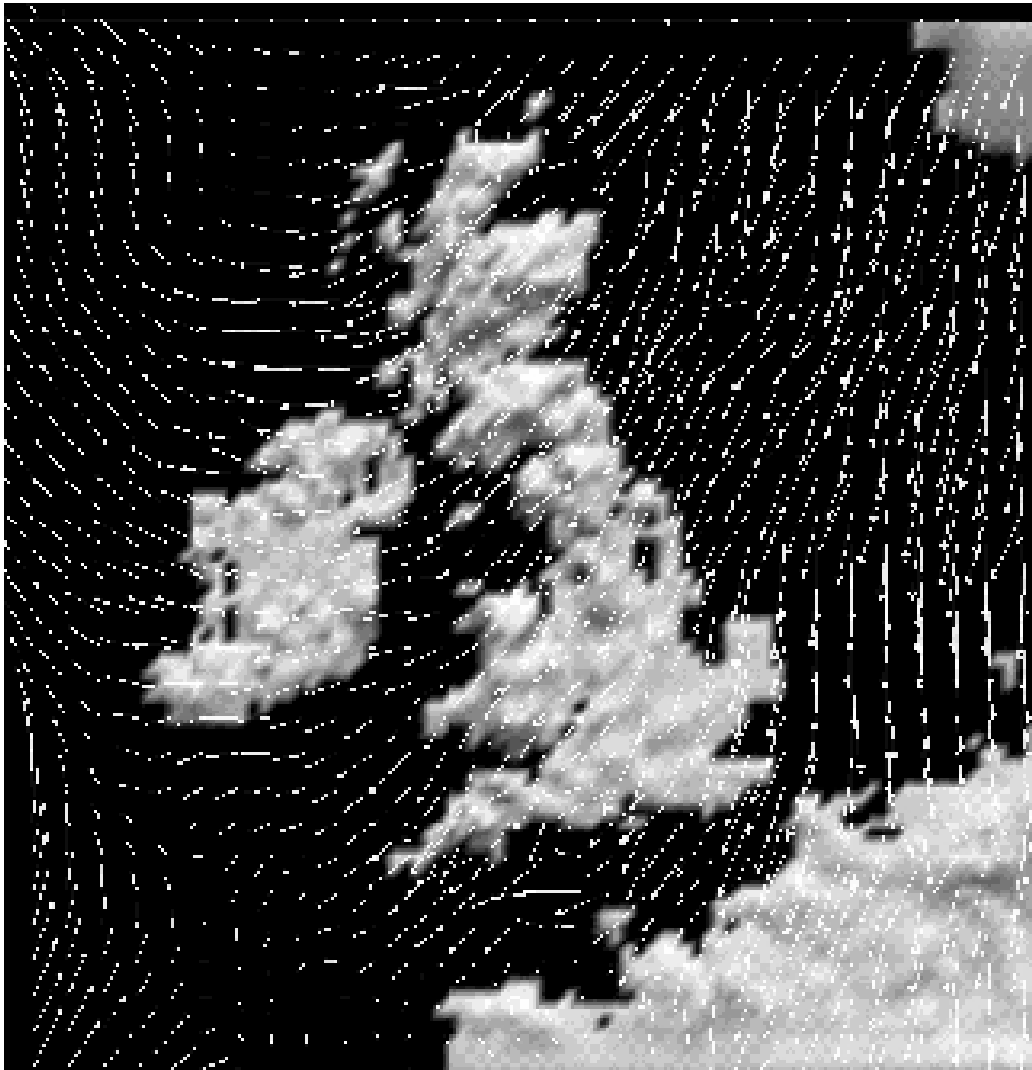
Hedgehog plots, etc.



- Aspects:
 - ◆ Direct Flow Visualization
 - ◆ Normalized arrows vs. scaling with velocity
 - ◆ 2D: quite usable,
3D: often problematic
 - ◆ Sometimes limited expressivity (temporal component missing)
 - ◆ Often used!

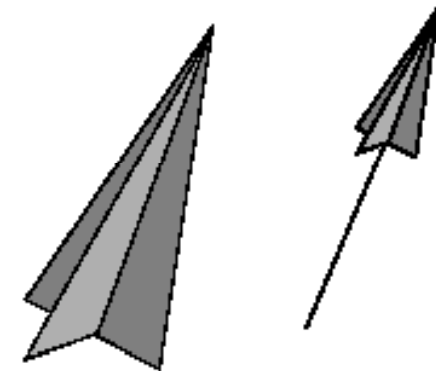
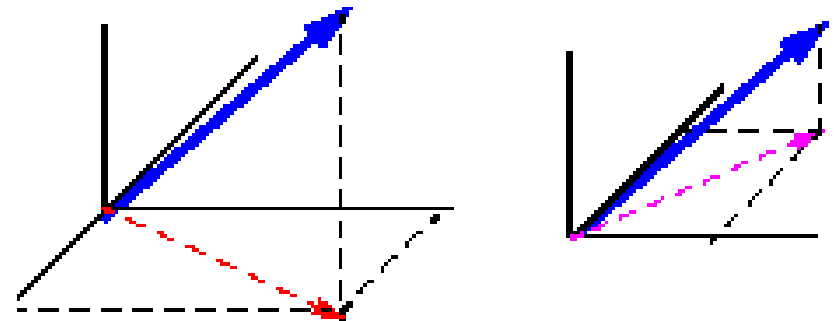


- Scaled arrows vs. color-coded arrows



■ Following problems:

- ◆ Ambiguity
- ◆ Perspective Shortening
- ◆ 1D-objects in 3D: difficult spatial perception
- ◆ Visual clutter

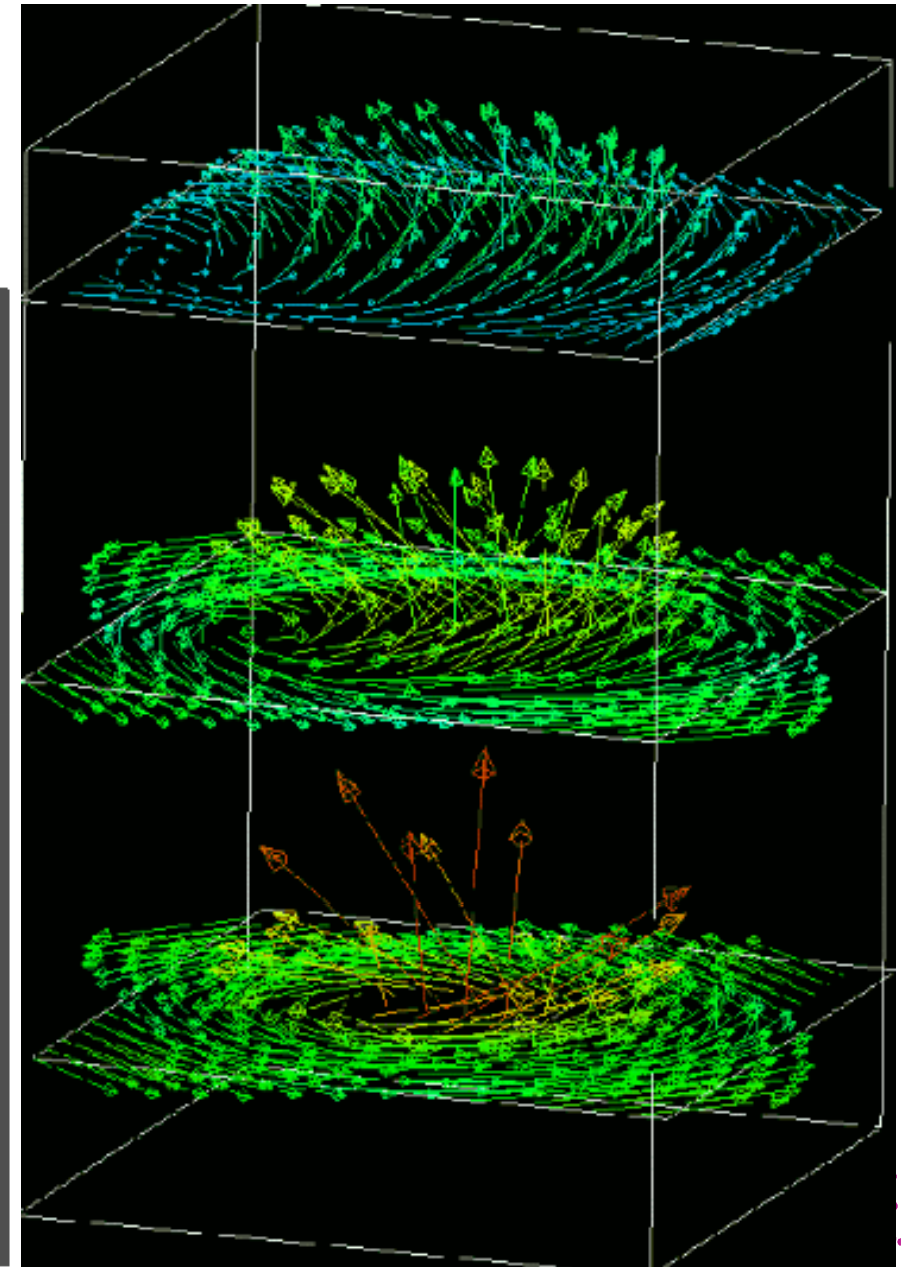
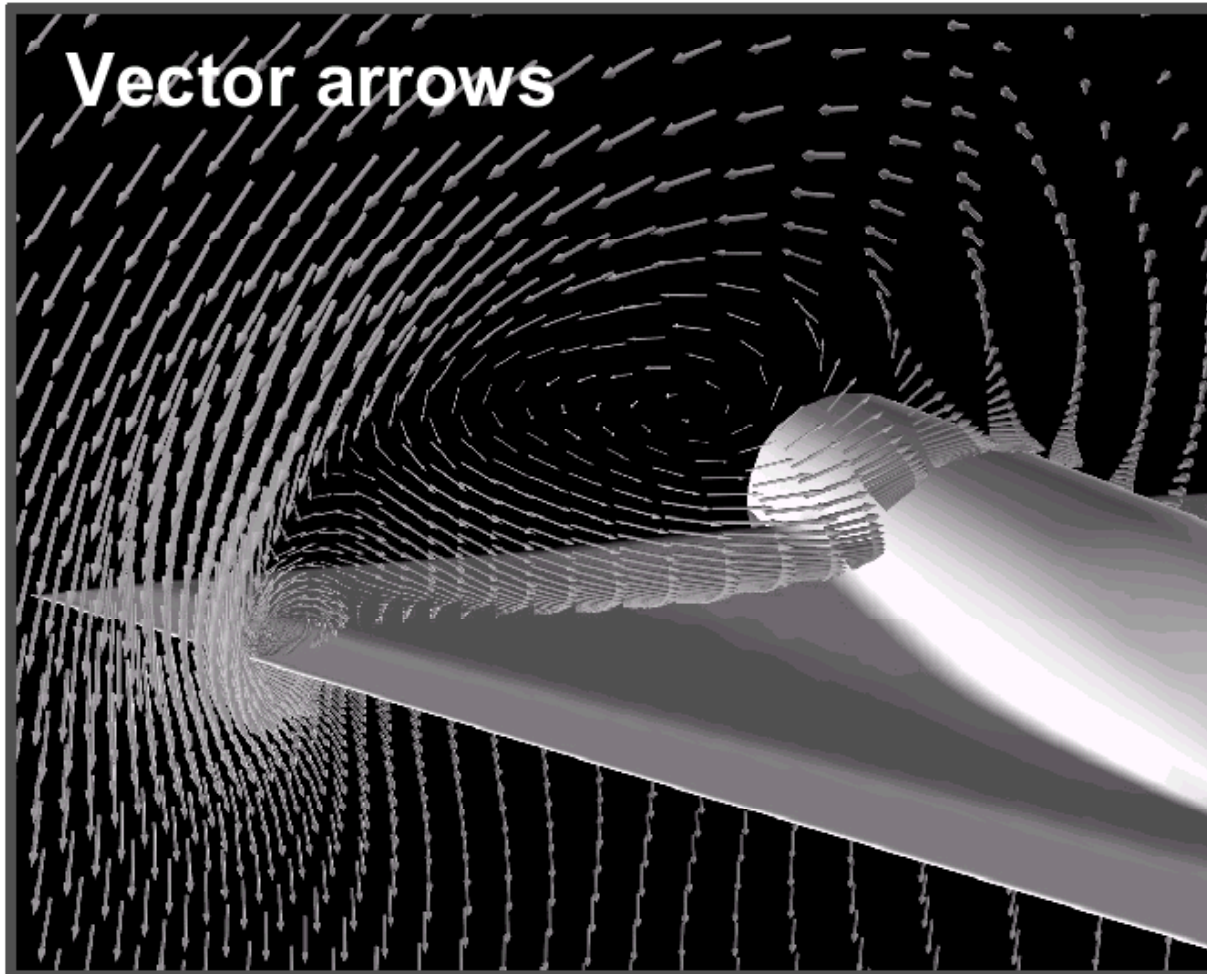


■ Improvement:

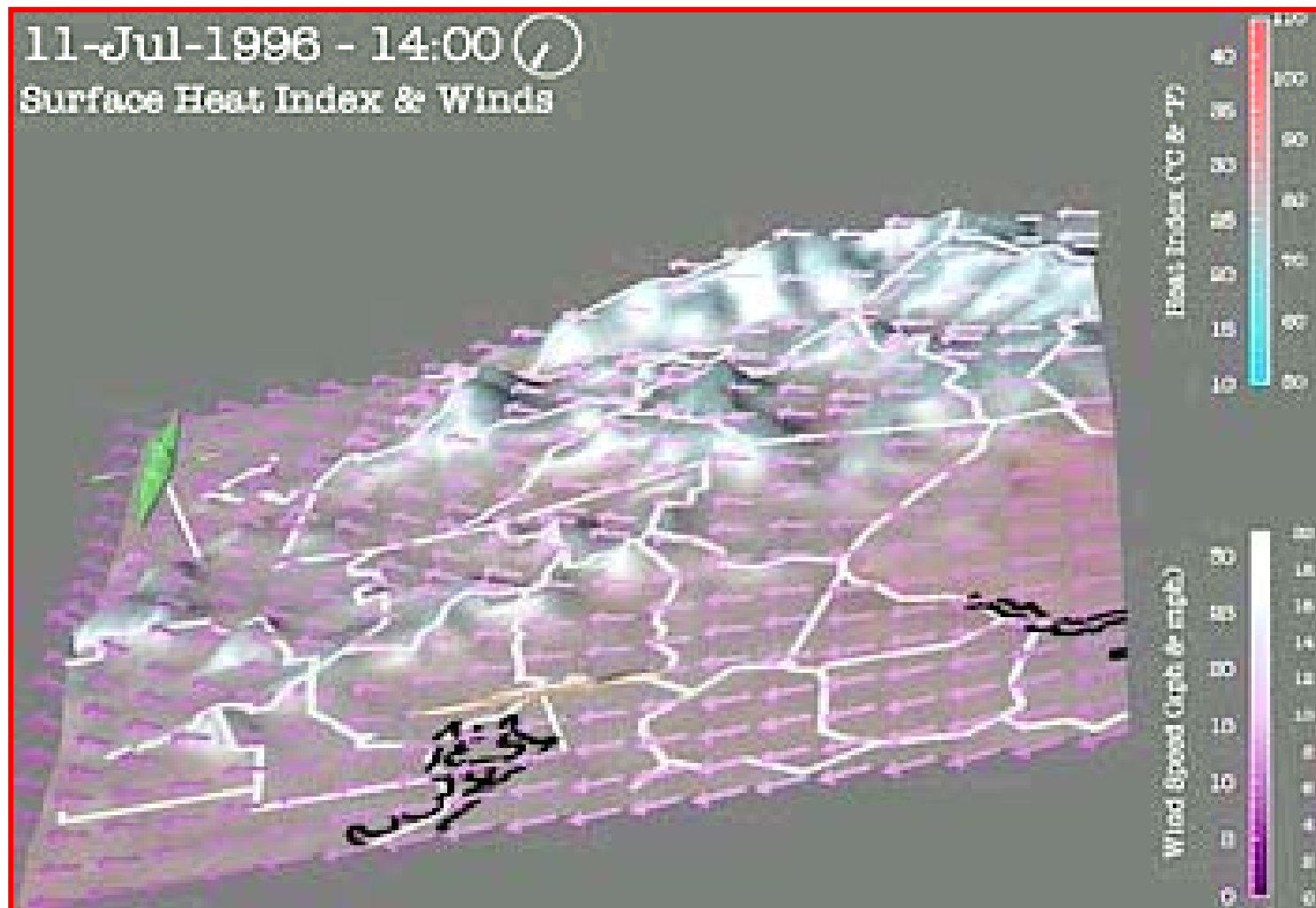
- ◆ 3D-arrows (help to a certain extent)



- **Compromise:**
Arrows only in slices



- Well integrable within “real” 3D:



- For material for this lecture unit
 - ◆ Hans-Georg Pagendarm
 - ◆ Roger Crawfis
 - ◆ Lloyd Treinish
 - ◆ David Kenwright
 - ◆ Terry Hewitt
 - ◆ etc.

