

Tutorium

CG2 LU



- Shadow-Mapping
- Bloom / Glow
- Animation



Shadow Mapping

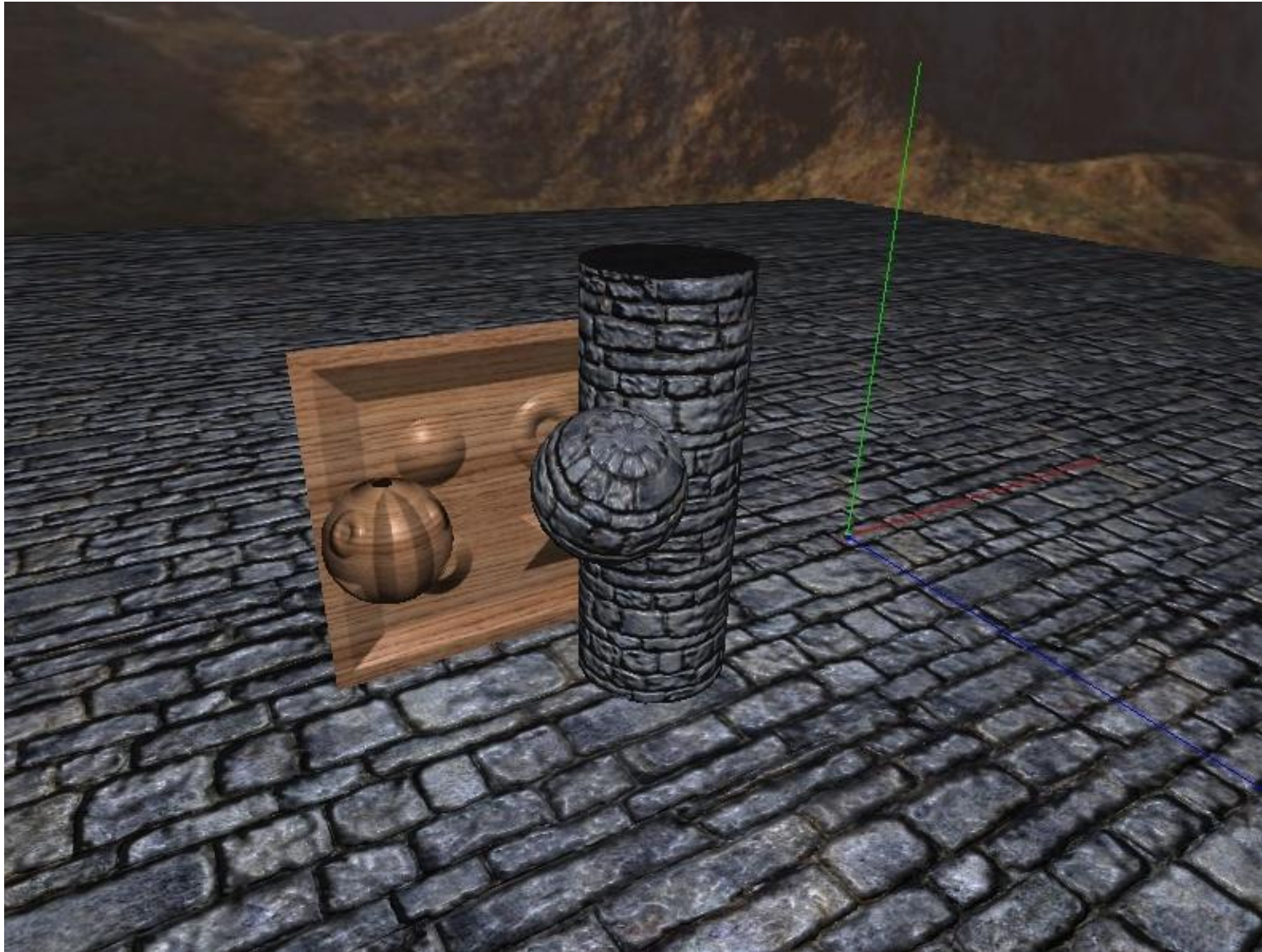
Peter Houska

Institute of Computer Graphics and Algorithms

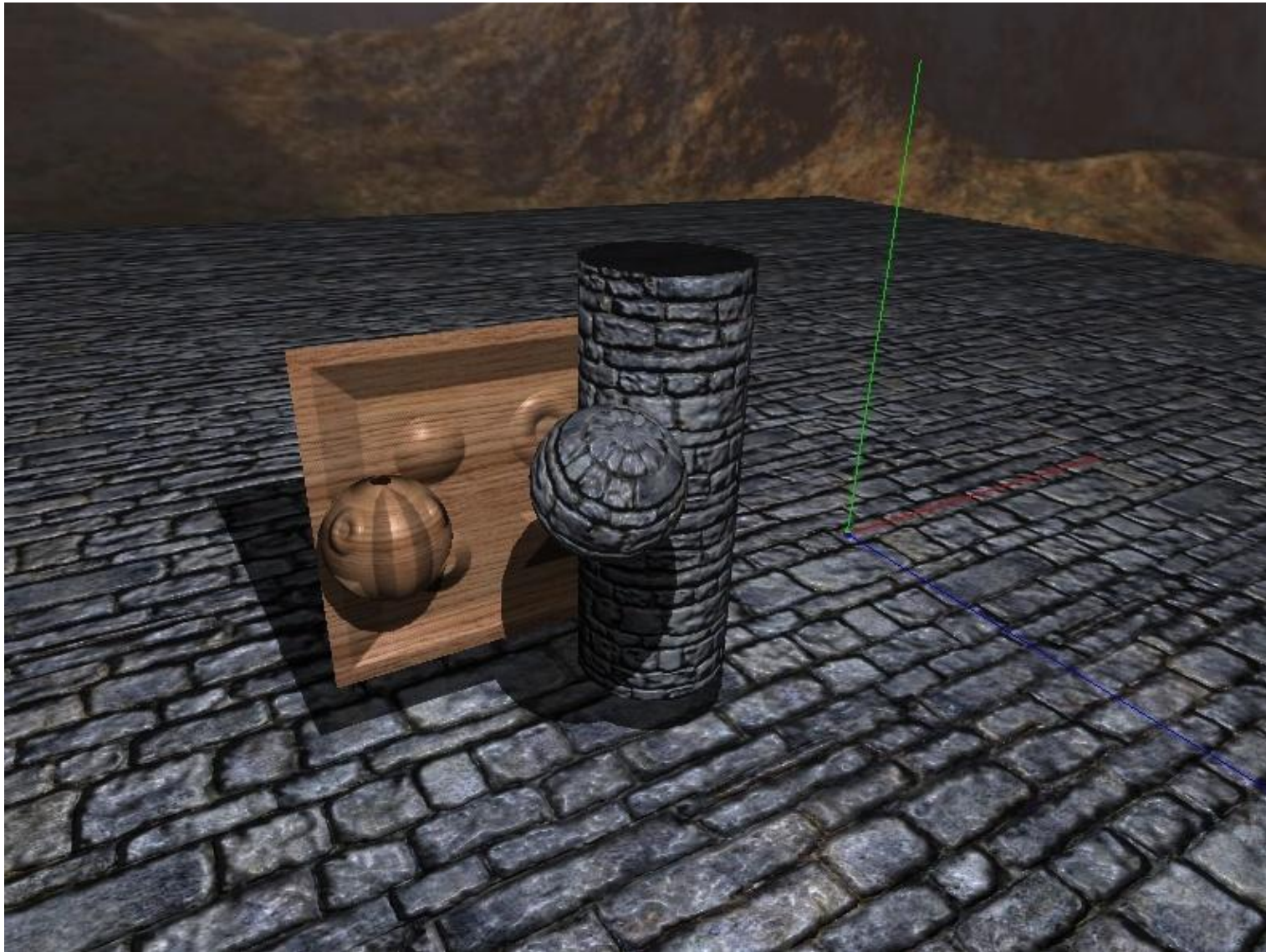
Vienna University of Technology



Why Shadows?



Why Shadows?



- Shadows ...
 - ◆ ... make a scene look more three-dimensional
 - ◆ ... emphasize the spatial relationship of objects among each other
 - ◆ ... tell us where the light comes from
 - ◆ ... should really be there 😊



- Several techniques, e.g.
 - ◆ Shadow Mapping
 - ◆ Shadow Volumes
- Let's take a closer look at Shadow Mapping
 - ◆ 2 pass algorithm
 - ◆ fast on today's GPUs
 - ◆ relatively easy to implement

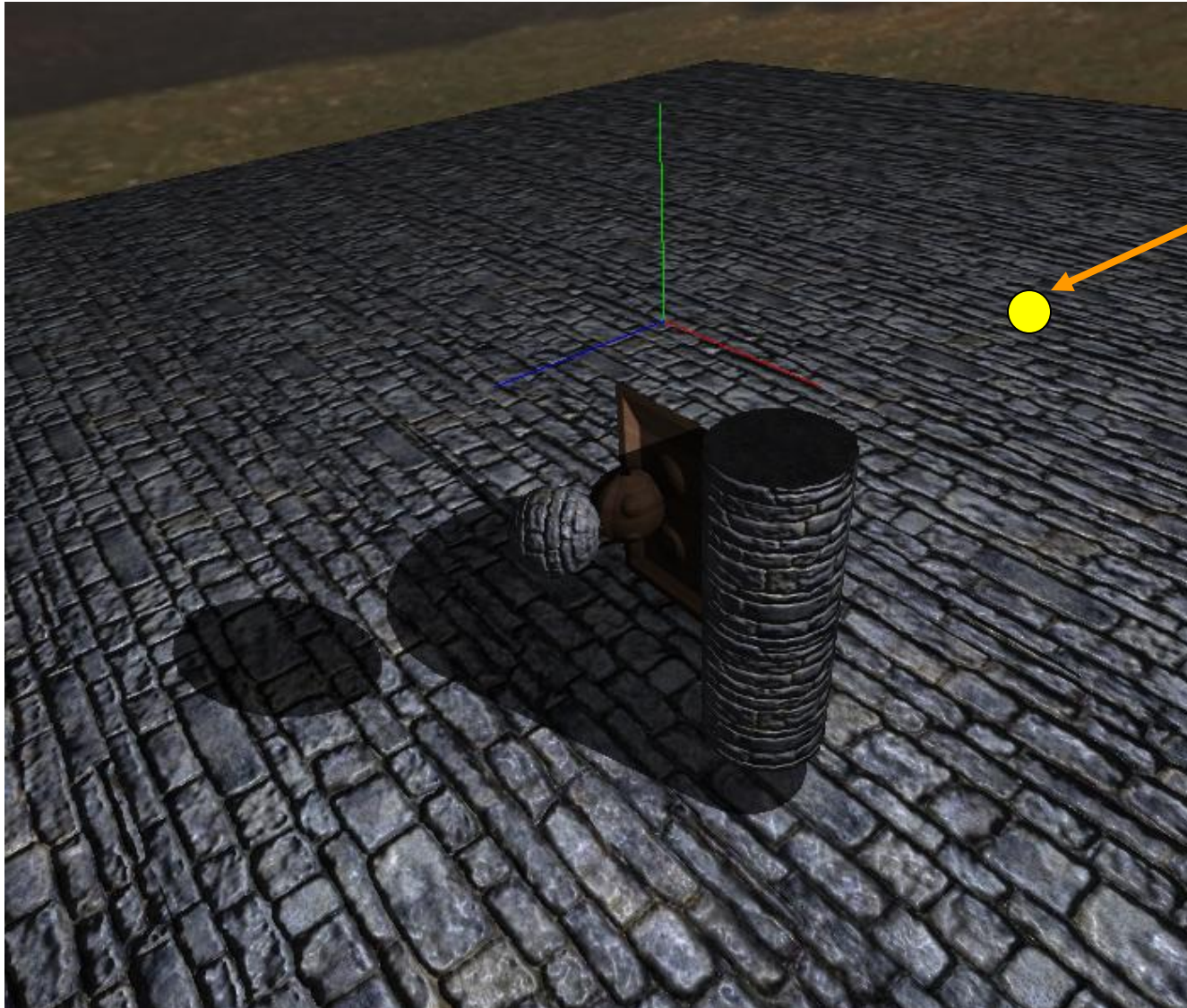


- 1st pass:
 - ◆ assume light source has a “view frustum” (like a camera)
 - ◆ render scene from light source’s position
 - ◆ save depth values only
 - ◆ we end up with a shadow (depth-) map
- 2nd pass:
 - ◆ render scene as usual
 - transform vertices to light space, too
 - ◆ for each fragment, compare its depth to previously stored depth (read it from shadow map)
 - $Z_{\text{fragment}} > Z_{\text{from_shadow_map}} \Rightarrow$ fragment lies in shadow
 - fragment must be in light space!!!



Scene – “Meta” View

Eye



Light Source



Scene – Light Source View

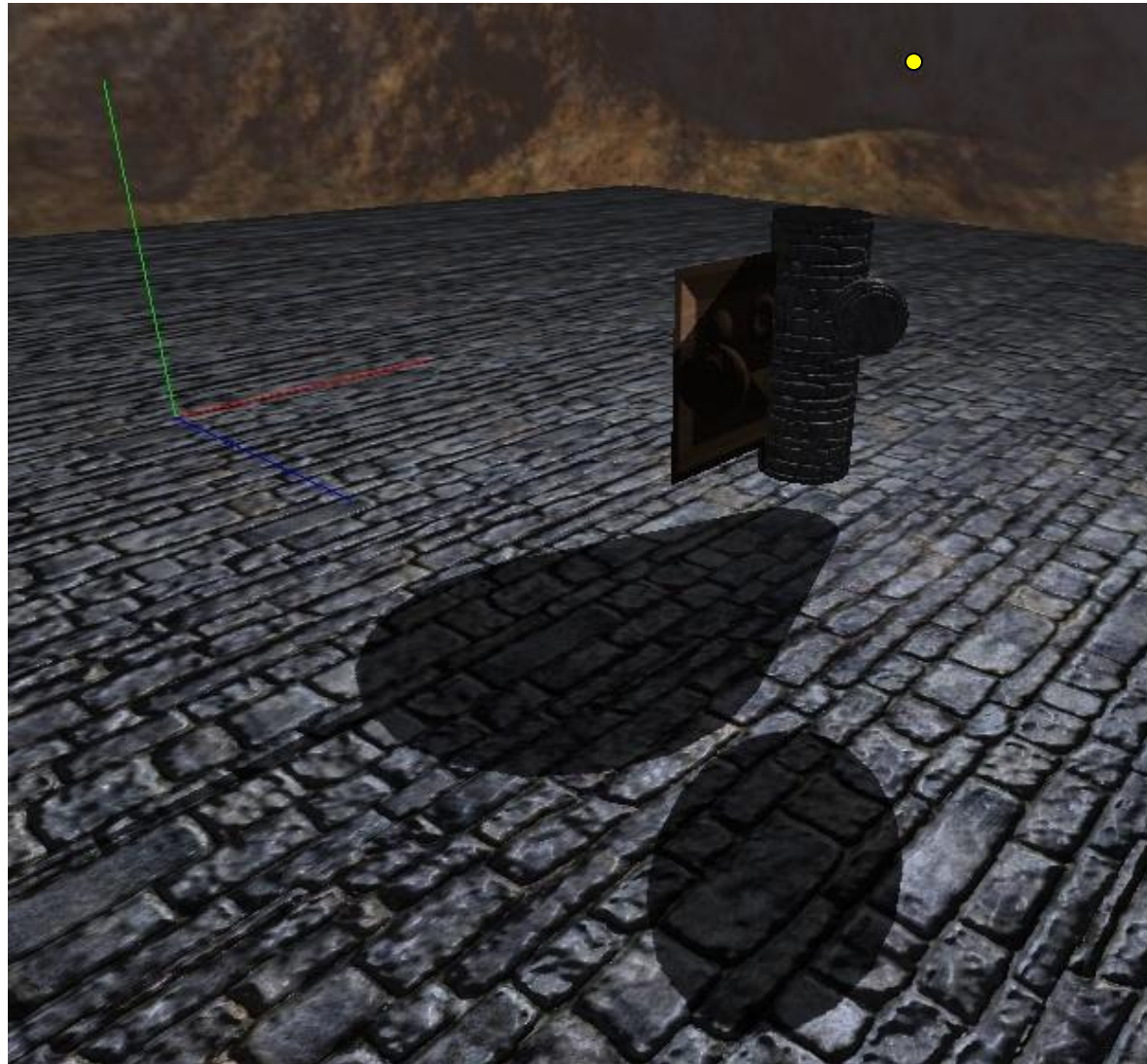


Scene – Light Source View (Depth Only)

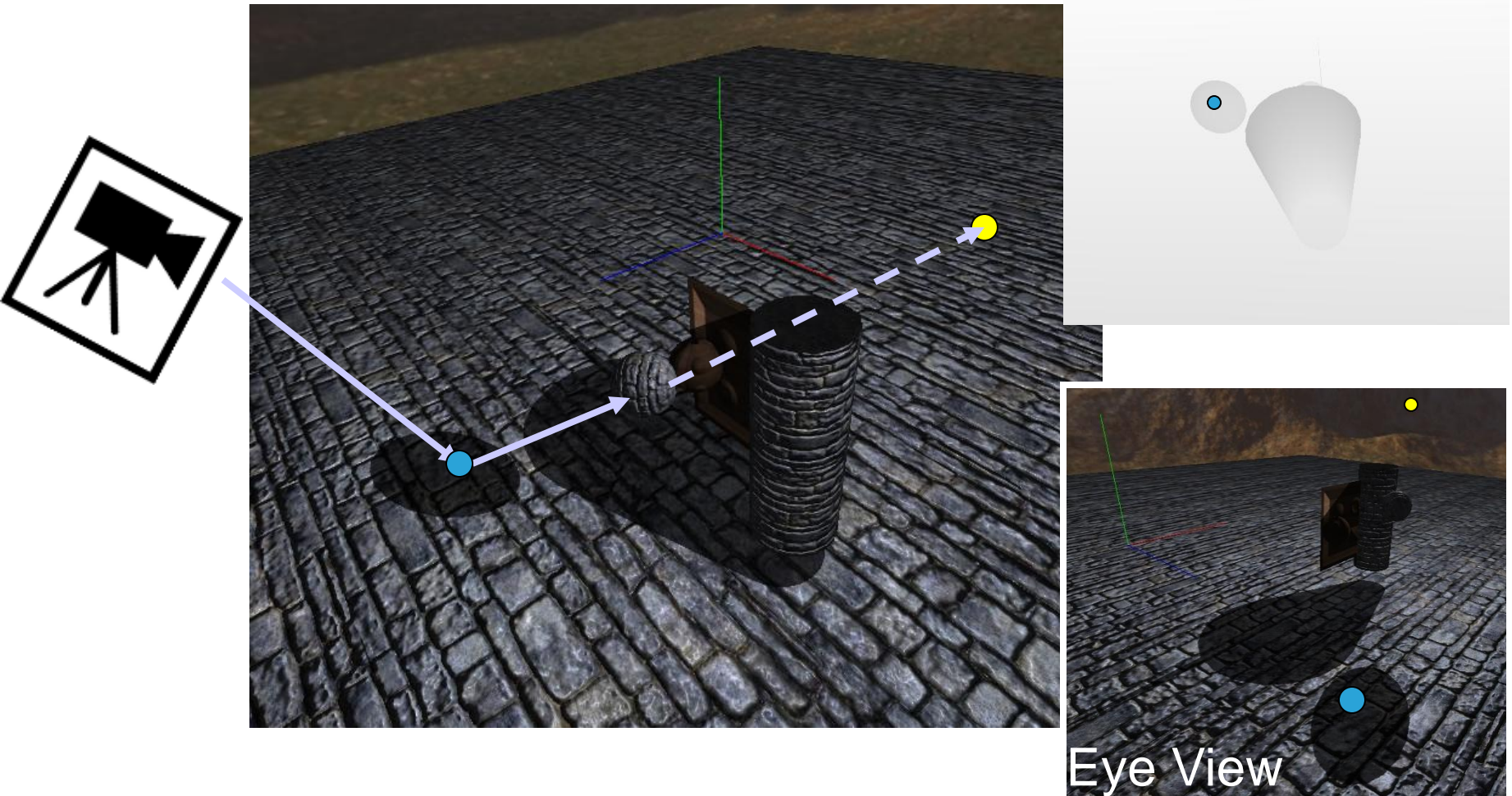


This is actually the shadow map!

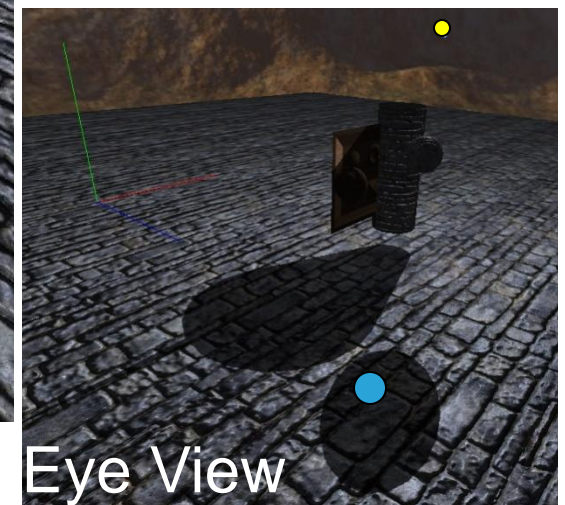
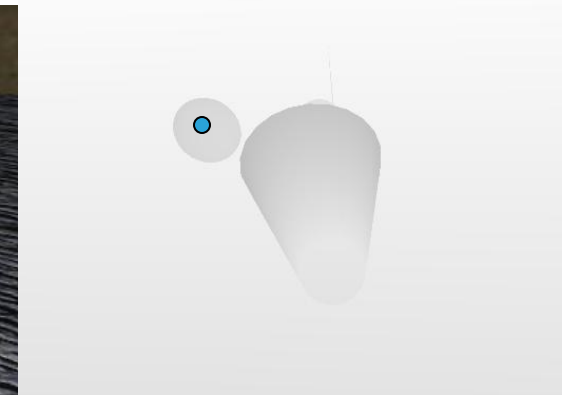
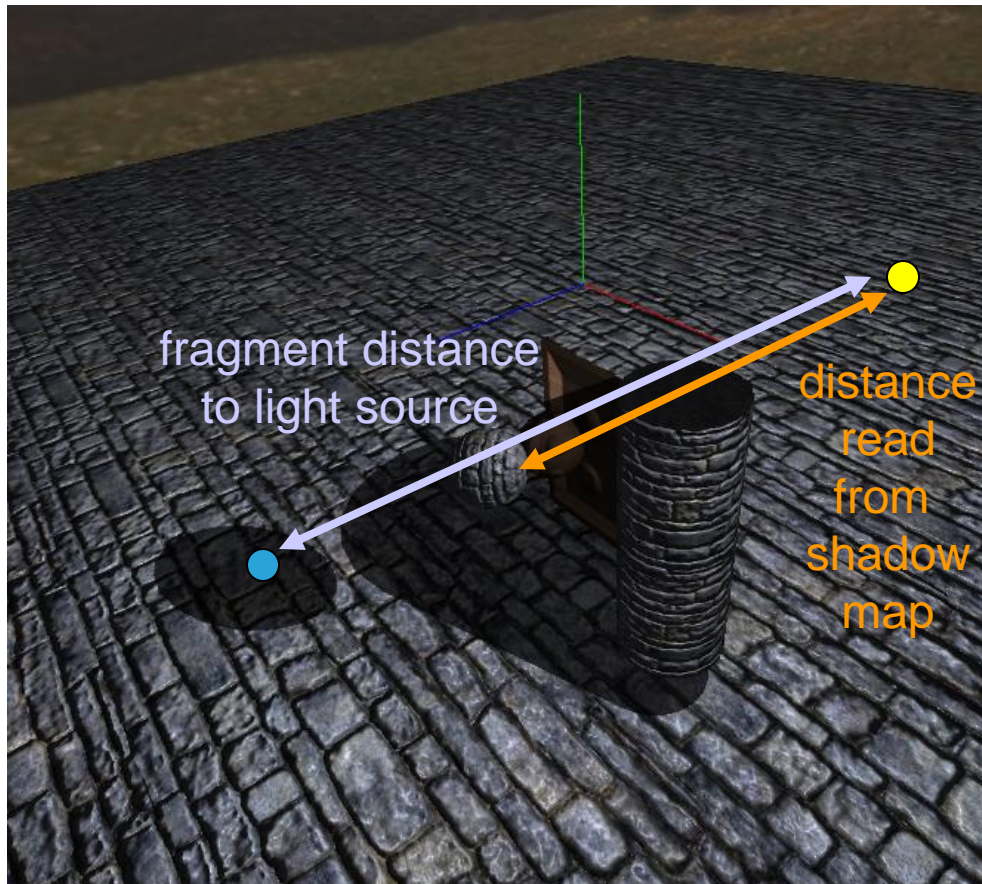
Scene – Eye View



“Meta“ View



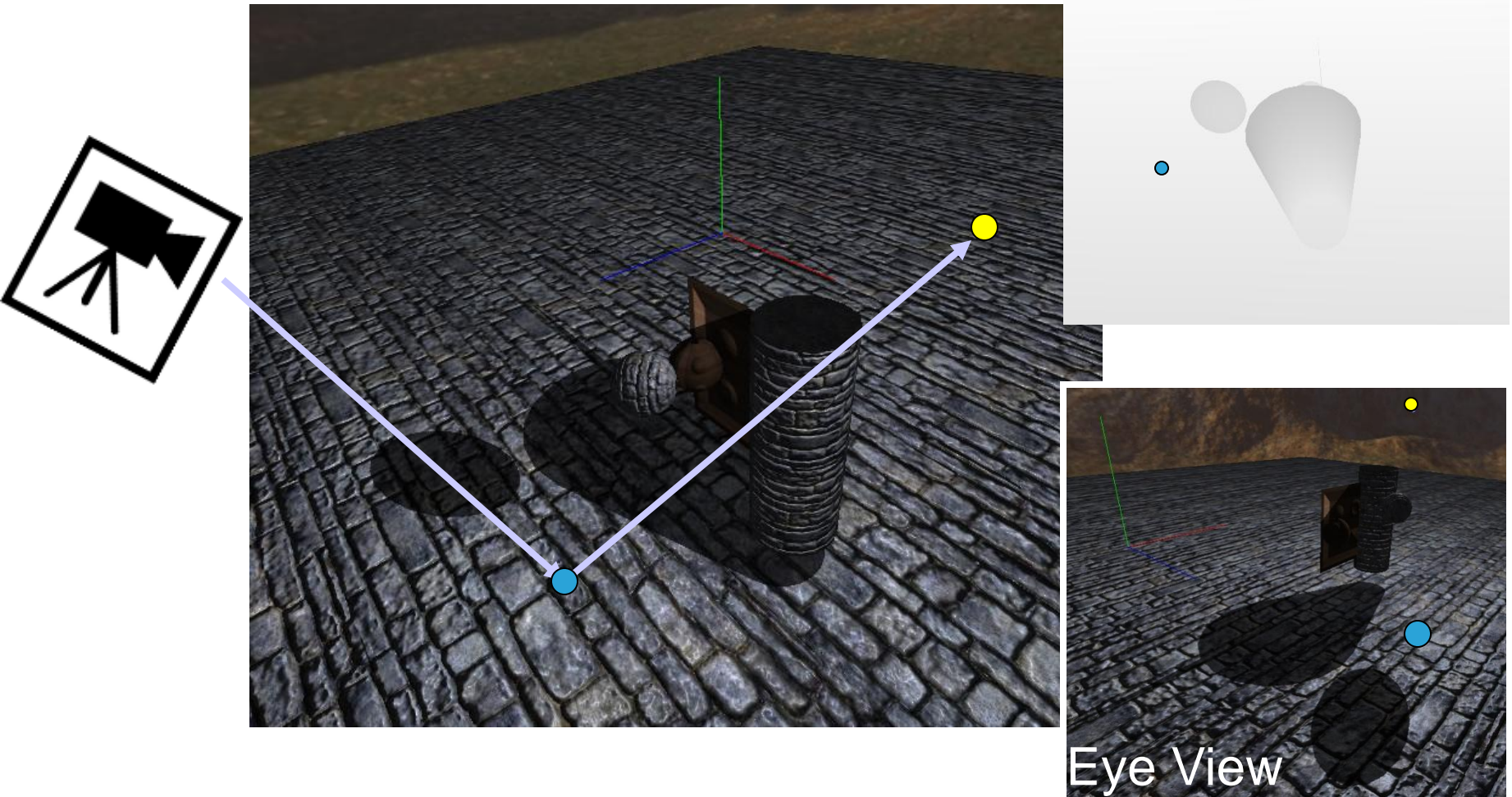
“Meta“ View



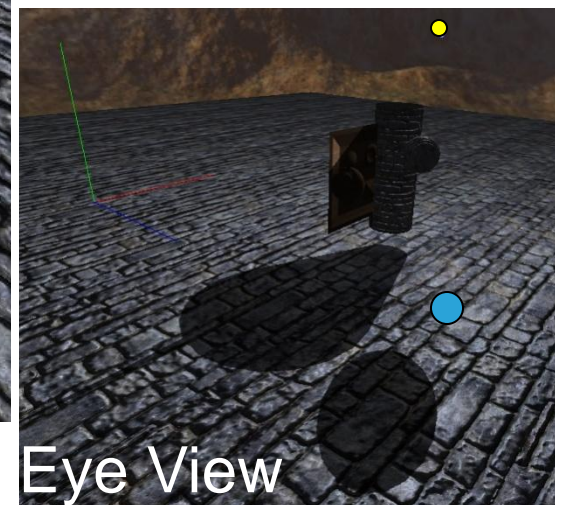
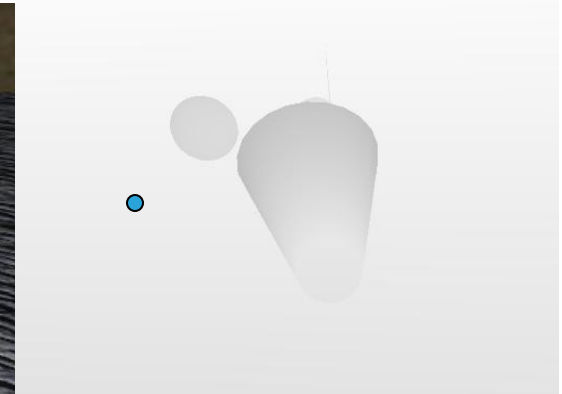
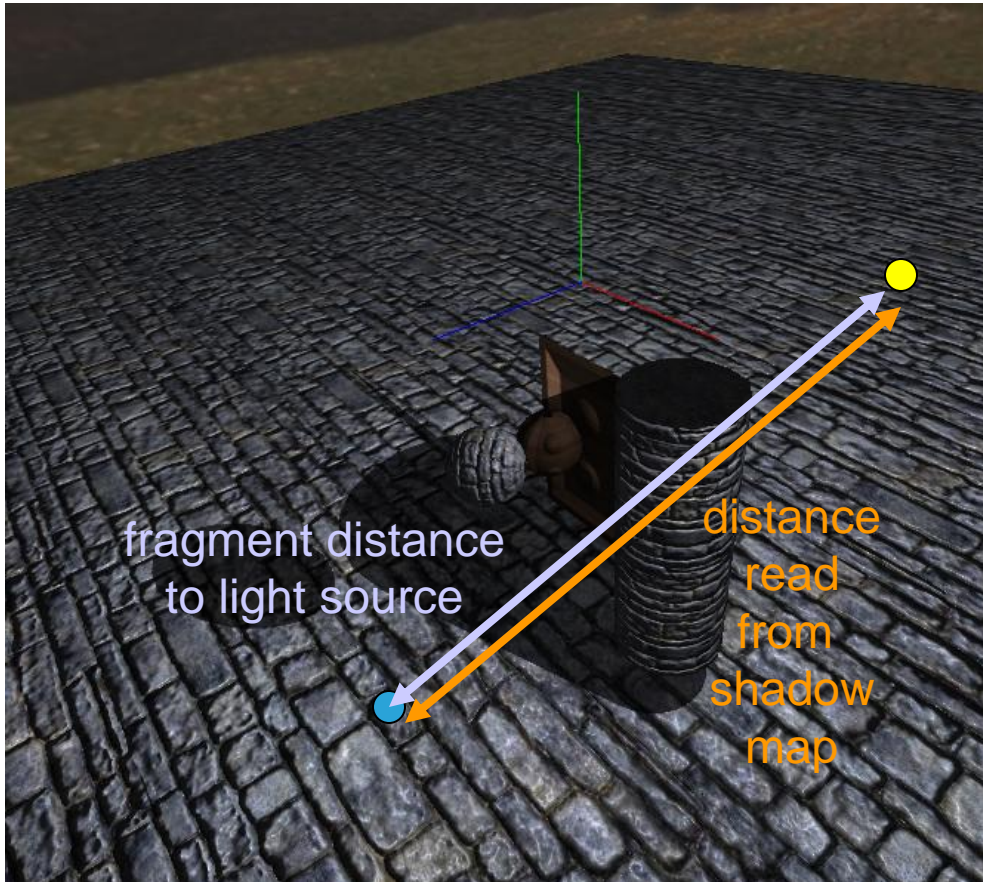
Eye View



“Meta“ View



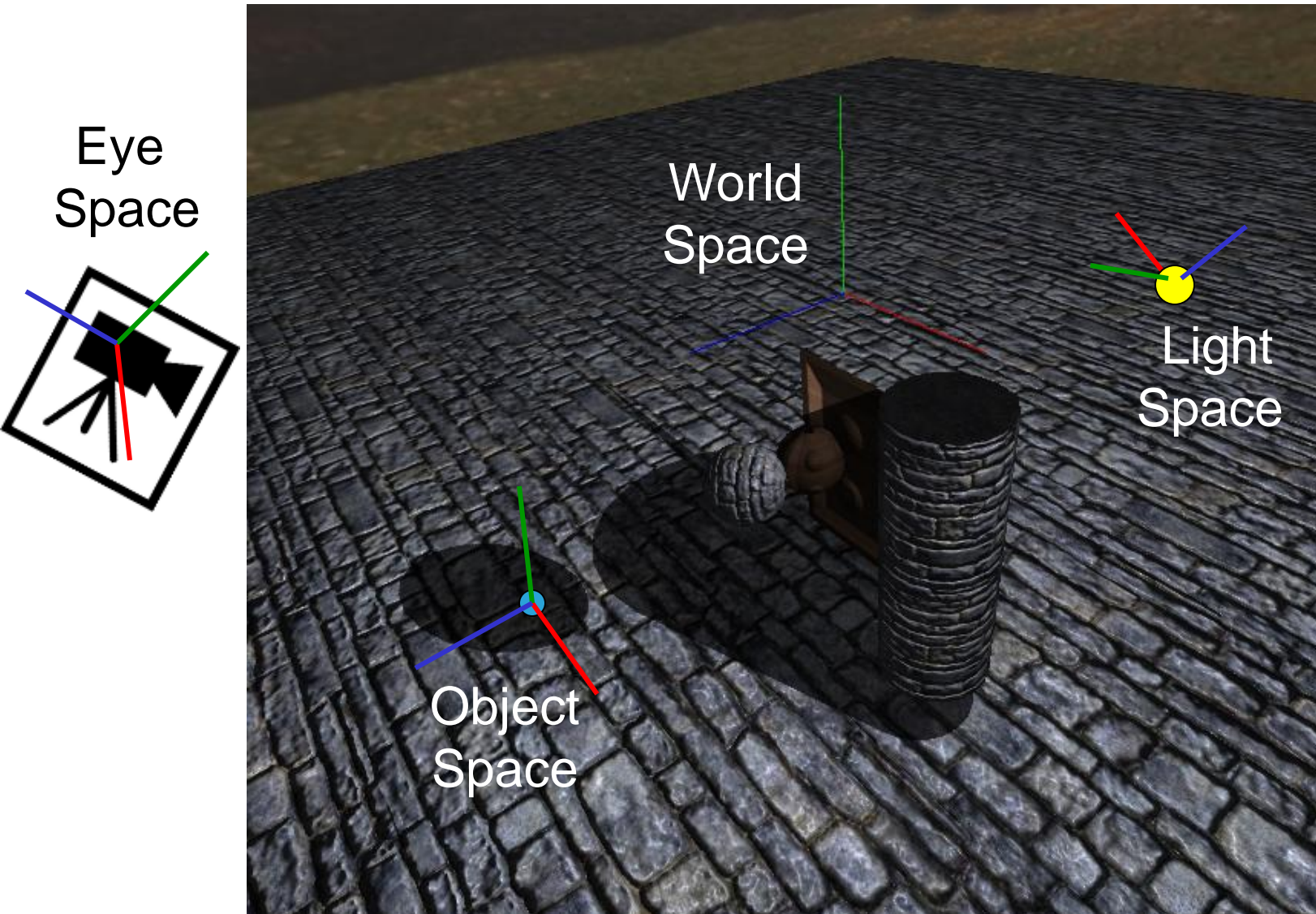
“Meta“ View



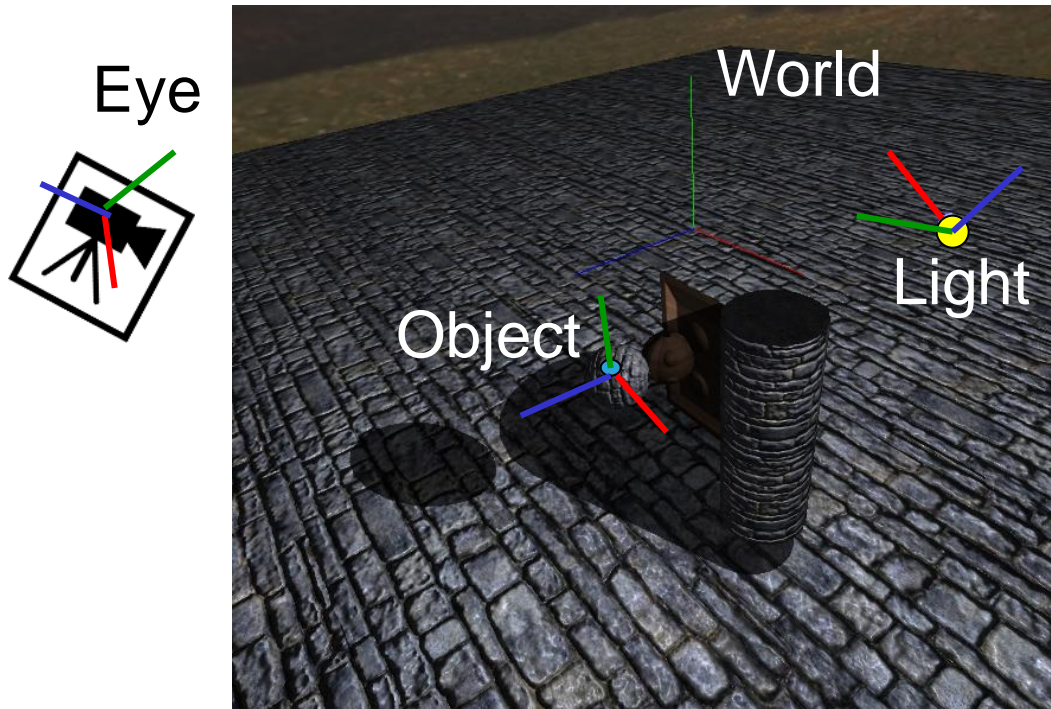
Eye View



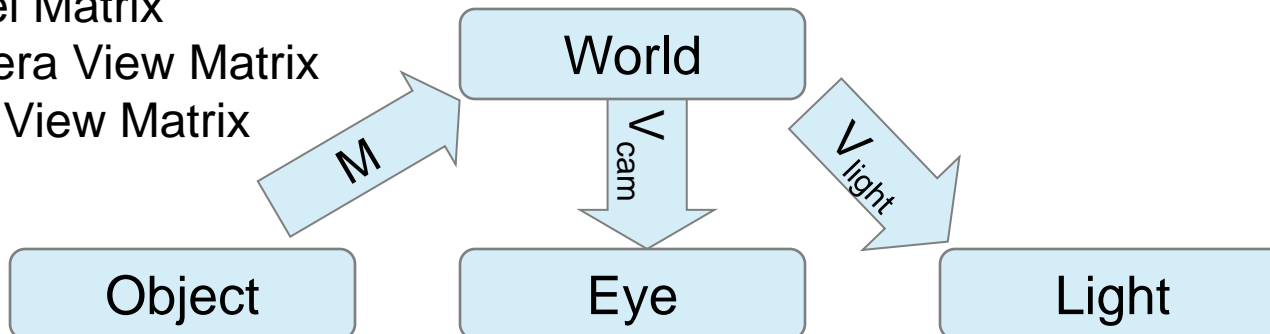
Involved Coordinate Systems



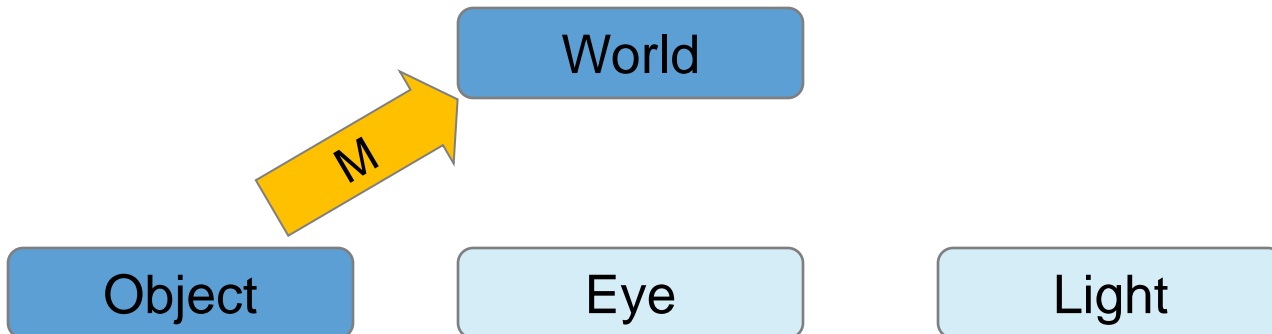
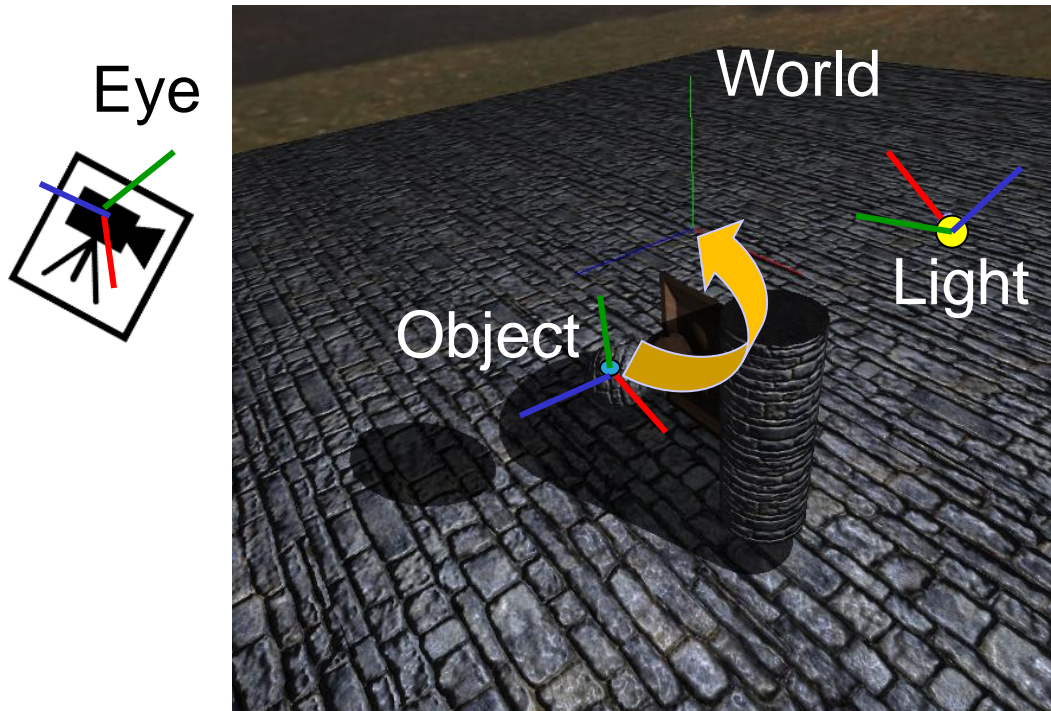
Involved Coordinate Systems



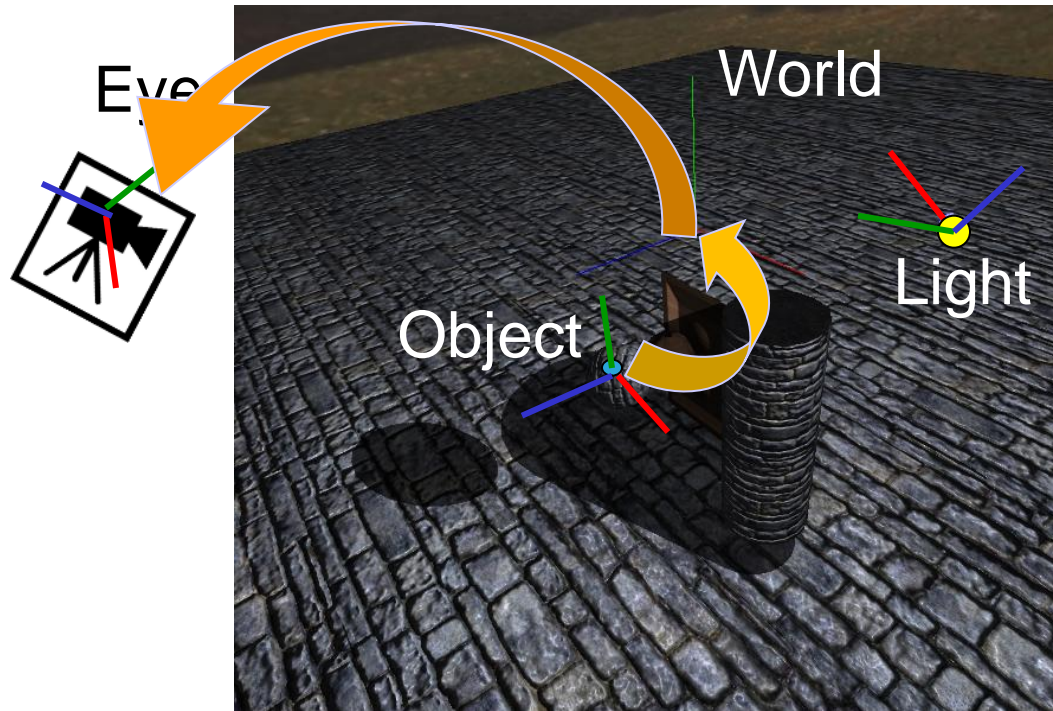
M ... Model Matrix
 V_{cam} ... Camera View Matrix
 V_{light} ... Light View Matrix



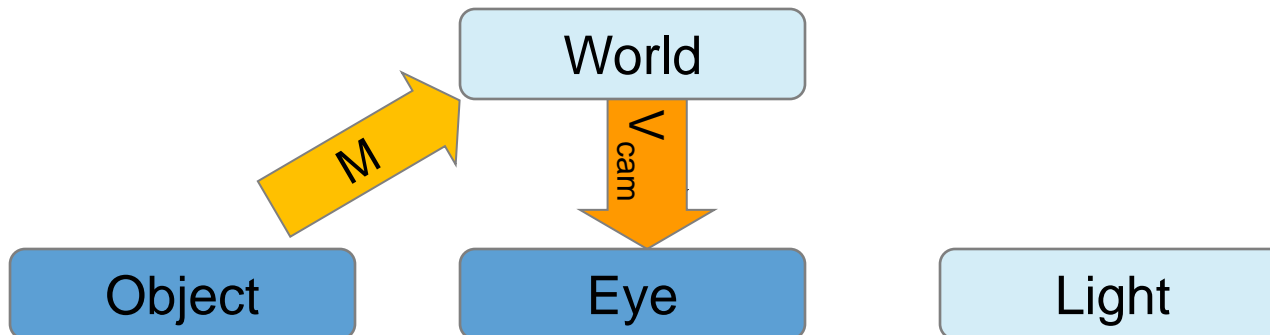
Transforming to World Space



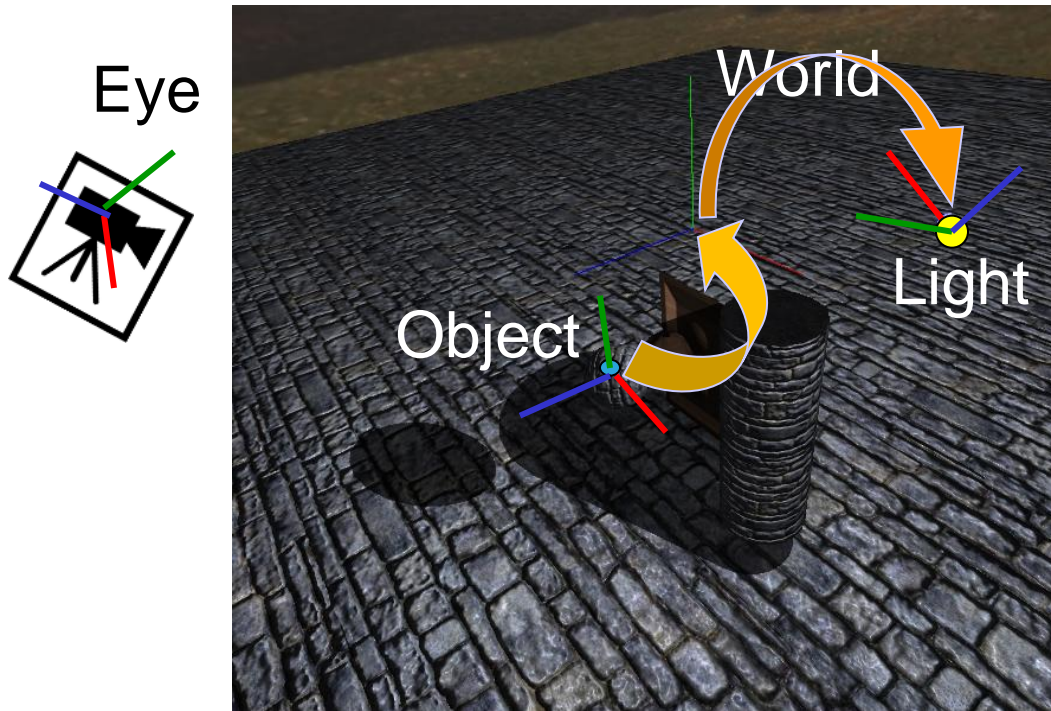
Transforming to Eye Space



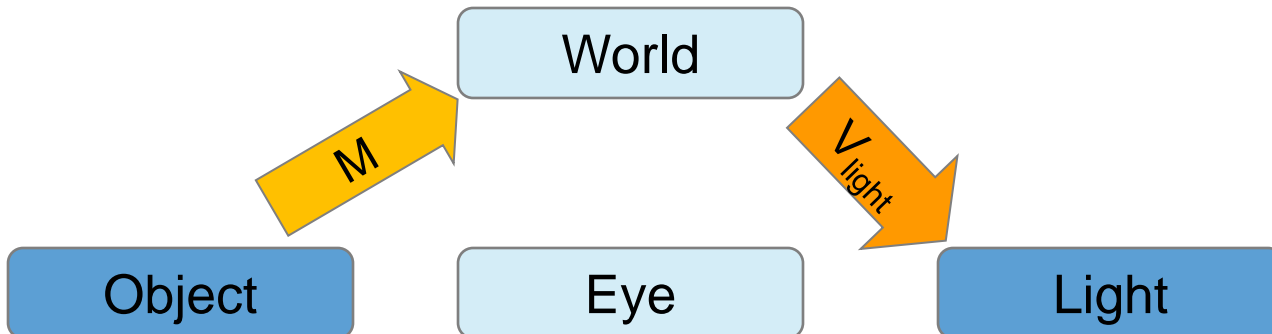
rendering from the eye's point of view



Transforming to Light Space



rendering from the light source's point of view



1st pass: Create Shadow Map

```
// create the texture we'll use for the shadowmap
glGenTextures(1, &shadow_tex_ID);
glBindTexture(GL_TEXTURE_2D, shadow_tex_ID);
glTexImage2D (GL_TEXTURE_2D, 0, GL_DEPTH_COMPONENT24,
              SM_width, SM_height, 0,
              GL_DEPTH_COMPONENT, GL_UNSIGNED_BYTE, NULL);

// attach texture to an FBO
glGenFramebuffers(1, &shadow_FBO);
glBindFramebuffer(GL_FRAMEBUFFER, shadow_FBO);
glFramebufferTexture2D(GL_FRAMEBUFFER, GL_DEPTH_ATTACHMENT,
                      GL_TEXTURE_2D, shadow_tex_ID, 0);

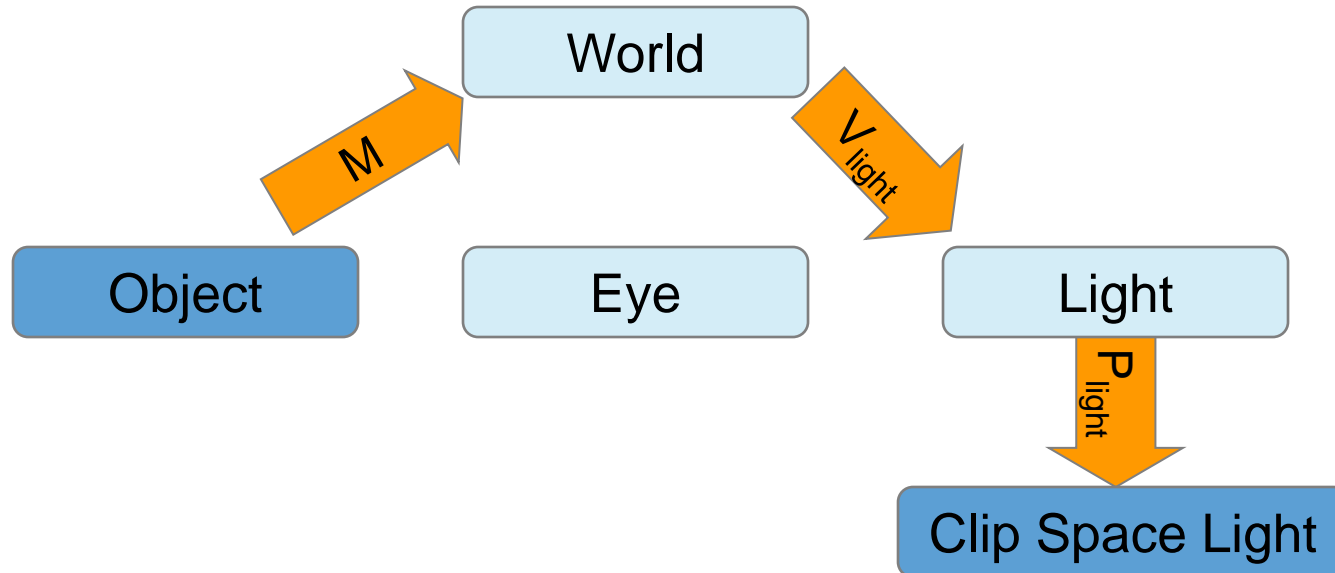
glDrawBuffer(GL_NONE); // essential for depth-only FBOs!!!
glReadBuffer(GL_NONE); // essential for depth-only FBOs!!!

// then, just before rendering
glBindFramebuffer(GL_FRAMEBUFFER, shadow_FBO);
```



1st pass: Create Shadow Map

- The “view” matrix must be set to V_{light}
- Note: No projection matrix used up to now!
 - ◆ but light-“camera” involves another projection!

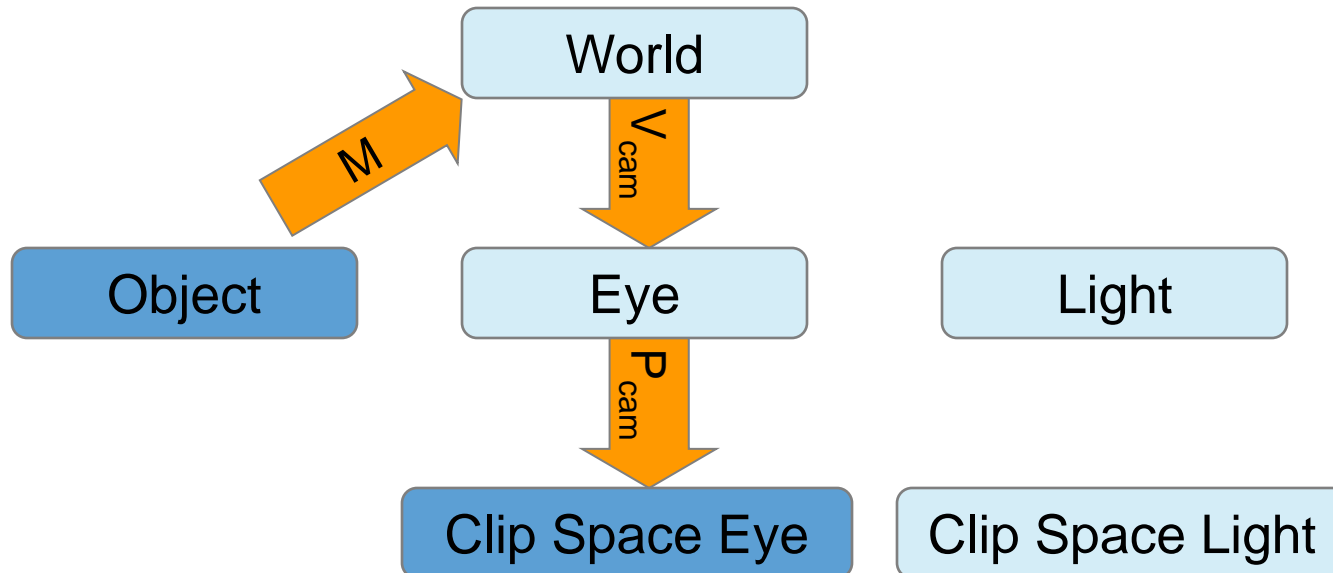


- Turn off all effects when rendering to the shadow map
 - ◆ No textures, lighting, etc.



- Transform vertices to eye space and project as usual

- ◆ $v' = P_{\text{cam}} * V_{\text{cam}} * M * v$



- Also transform vertices to projected light space (= clip space light)
 - ◆ basically the same steps as in the 1st pass:
 - $V_{\text{proj_lightspace}} = (P_{\text{light}} * V_{\text{light}}) * M * v$
 - $V_{\text{proj_lightspace}}$ is essentially the texture coordinate for accessing the shadow map
 - ◆ Note:
 - the light source's projection matrix may be different from the eye's projection matrix
 - Since OpenGL-FF does not store a separate model matrix, FF-shadow mapping works like this (could still be used, even when using shaders):
 - ◆ $V_{\text{proj_lightspace}} = (P_{\text{light}} * V_{\text{light}} * V_{\text{cam}}^{-1}) * \underbrace{V_{\text{cam}} * M}_{\text{combined modelview matrix}} * v$



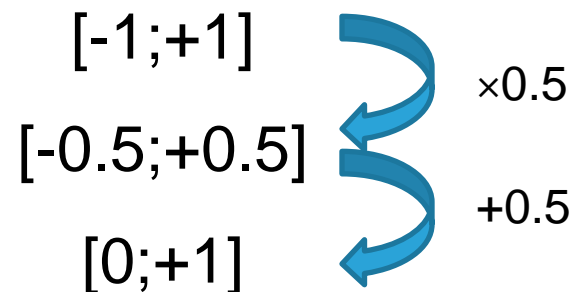
- One last issue...

- Let $v_{\text{proj_lightspace}} = \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}$

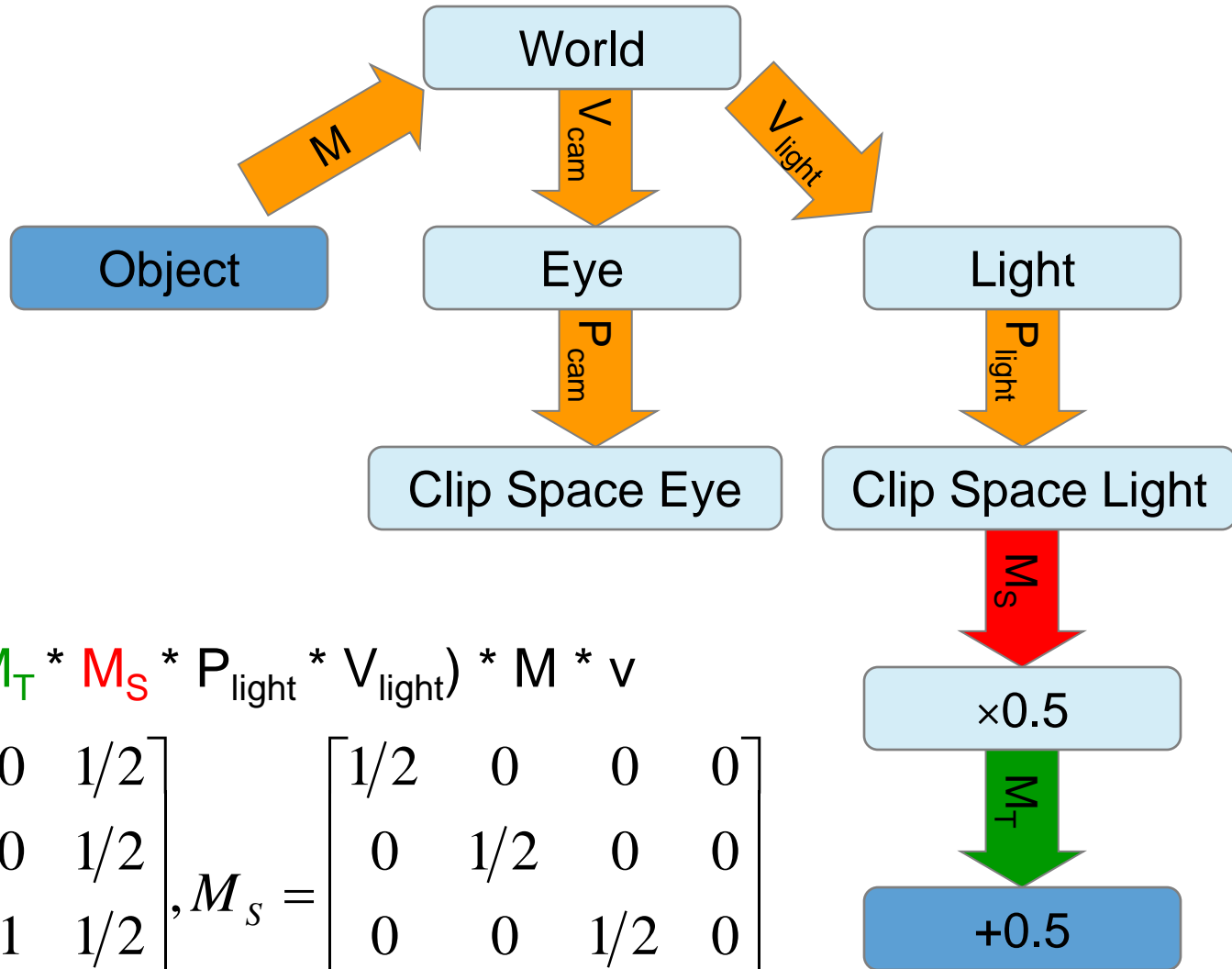
- After perspective division: $\begin{pmatrix} -1 \\ -1 \\ -1 \\ 1 \end{pmatrix} \leq \begin{pmatrix} x/w \\ y/w \\ z/w \\ 1 \end{pmatrix} \leq \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$



- So "standard" OpenGL projection matrix generates xyz-clip-space coordinates in the range $[-1;+1]$ after perspective division
 - ◆ i.e. in normalized device coordinates
- To access the shadow map, however, we need coordinates in the range $[0;+1]$
 - ◆ Apply scaling and translation



2nd pass: Render from Eye's POV



$$SM_{\text{texcoord}} = (M_T * M_S * P_{\text{light}} * V_{\text{light}}) * M * v$$

$$M_T = \begin{bmatrix} 1 & 0 & 0 & 1/2 \\ 0 & 1 & 0 & 1/2 \\ 0 & 0 & 1 & 1/2 \\ 0 & 0 & 0 & 1 \end{bmatrix}, M_S = \begin{bmatrix} 1/2 & 0 & 0 & 0 \\ 0 & 1/2 & 0 & 0 \\ 0 & 0 & 1/2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



■ $\text{tex_mat} = M_T * M_S * P_{\text{light}} * V_{\text{light}}$

```
#version 140
```

```
uniform mat4 M; // model matrix
```

```
uniform mat4 V_cam; // view matrix for the camera
```

```
uniform mat4 P_cam; // projection matrix for the camera
```

```
uniform mat4 tex_mat;
```

```
in vec4 vertex; // attribute passed by the application
```

```
out vec4 SM_tex_coord; // pass on to the FS
```

```
void main(void) {
```

```
    // standard transformation
```

```
    gl_Position = P_cam * V_cam * M * vertex;
```

```
    // shadow texture coords in projected light space
```

```
    SM_tex_coord = tex_mat * M * vertex;
```

```
}
```



- It is faster to precompute all the matrix products once per frame in the application and just pass them to the shader as uniforms
 - ◆ in this case we would end up passing two matrices only
 - one for the eye-space-transform, e.g.
 - ◆ $PVM = P_cam * V_cam * M$
 - one for the light-space-transform, e.g.
 - ◆ $TM = tex_mat * M$



```
#version 140
uniform sampler2D shadow_map; // shadow map is just a texture

in vec4 SM_tex_coord; // passed on from VS
out vec4 fragment_color; // final fragment color

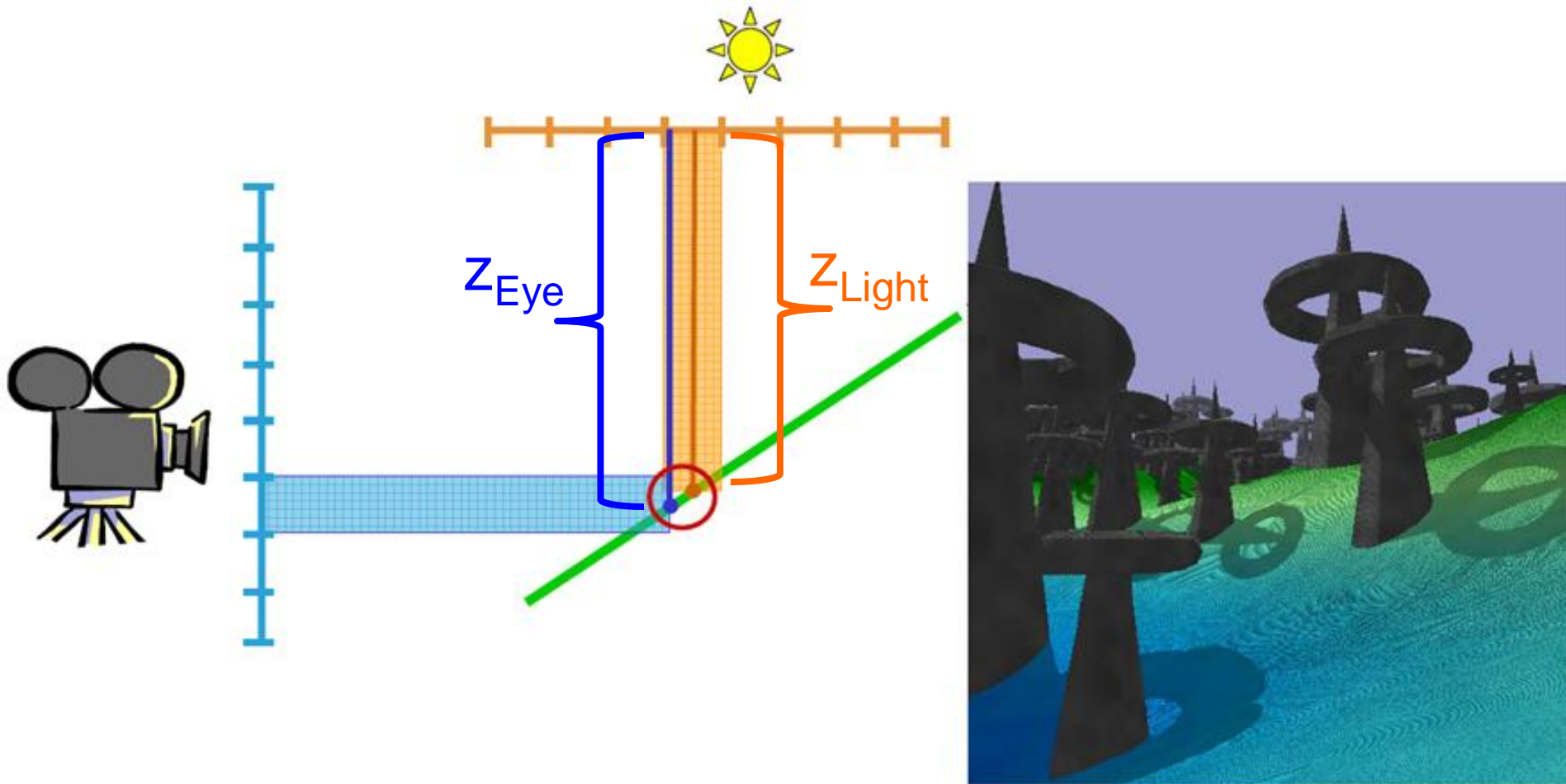
void main(void) {
    // perform perspective division
    vec3 tex_coords = SM_tex_coord.xyz/SM_tex_coord.w;

    // read depth value from shadow map
    float depth = texture(shadow_map, tex_coords.xy).r;

    // perform depth comparison
    float inShadow = (depth < tex_coords.z) ? 1.0 : 0.0;
    // do something with that value ...
}
```



Artifacts – Incorrect Self Shadowing



$Z_{\text{Eye}} > Z_{\text{Light}}$  incorrect self shadowing



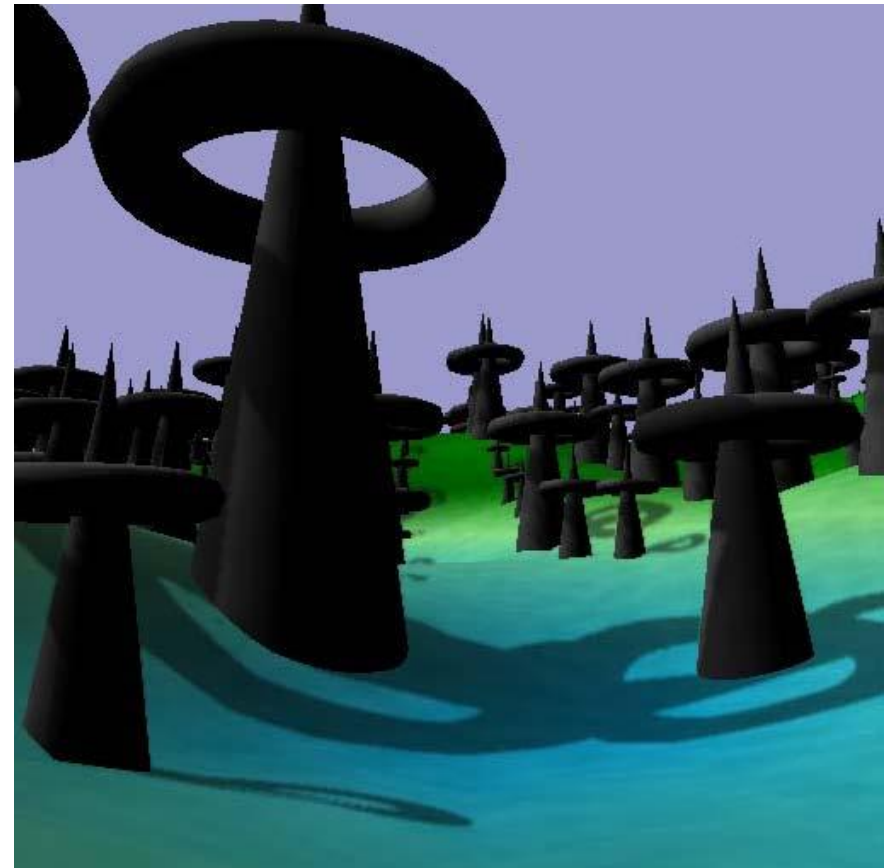
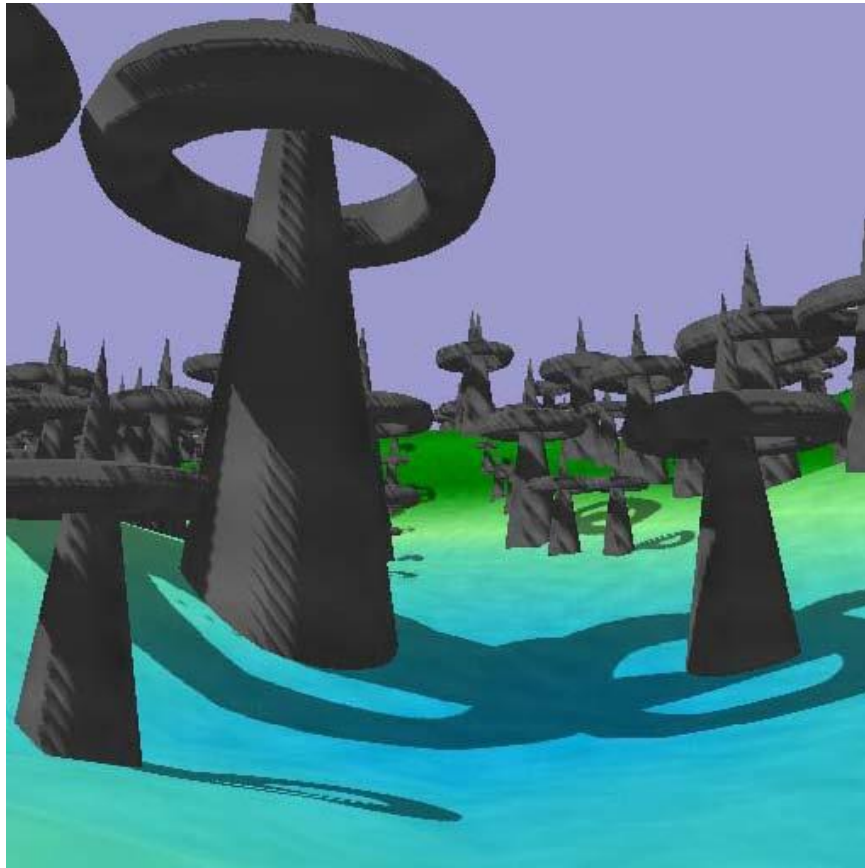
- When rendering to shadow map, either

- ◆ add z-offset to polygons

```
glPolygonOffset(1.1, 4.0); // these values work well
```

- ◆ render objects' backfaces only



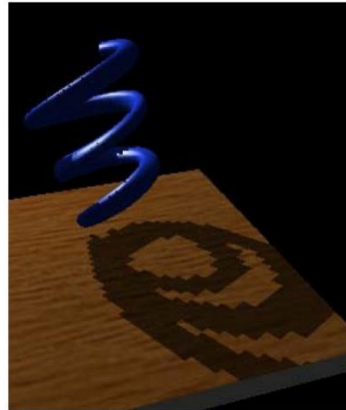


- Decrease ambient term
- Filter shadow map lookup

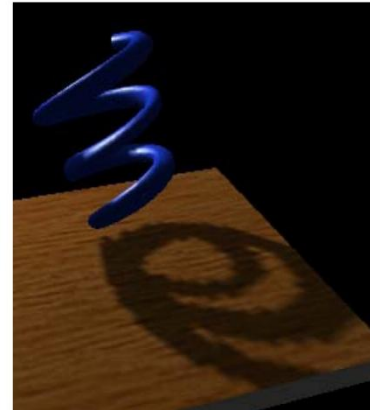


- Enabling HW - percentage closer filtering (PCF):

```
glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_MIN_FILTER, GL_LINEAR);  
glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_MAG_FILTER, GL_LINEAR);
```



GL_NEAREST



GL_LINEAR

- GPU can do depth comparison:

```
glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_COMPARE_MODE,  
                GL_COMPARE_REF_TO_TEXTURE);  
glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_COMPARE_FUNC, GL_LEQUAL);
```

- Having set the previously mentioned texture parameters, we can use another texture access function to read from the shadow map:

```
#version 140
```

```
// tell GPU, that texture map is actually a shadow map  
uniform sampler2DShadow shadow_map;
```

```
// just as before:
```

```
in vec4 SM_tex_coord; // passed on from VS  
out vec4 fragment_color; // final fragment color
```

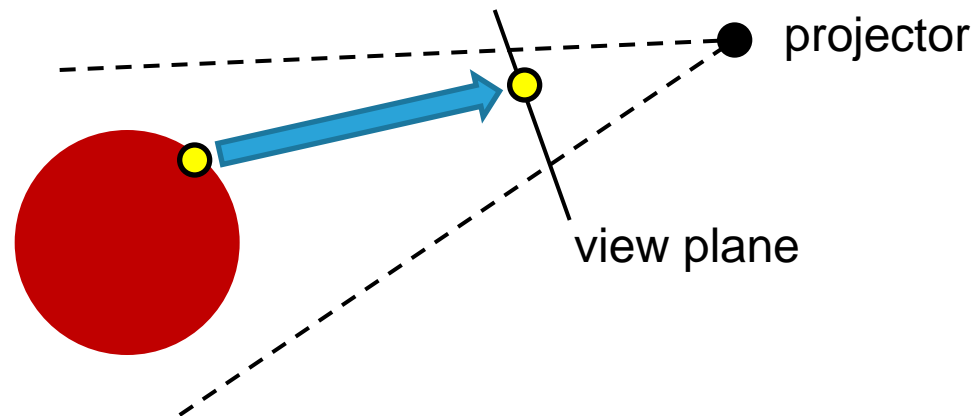
```
void main(void) {  
    // perspective division, depth-comparison and PCF  
    // is implicitly carried out by the GPU  
    float shadow = textureProj(shadow_map, SM_tex_coord);  
    // do something with that value ...  
}
```



- Once shadow mapping works, projective texturing can be implemented easily
- Same transformation steps necessary to access the "texture-to-project"
 - ◆ the only difference:
 - shadow map stores depth information which is fetched, but only used for comparing distances to the corresponding light source
 - projected texture stores the color value itself, so a simple texture lookup determines the fragment's color
 - ◆ is actually easier than shadow mapping!

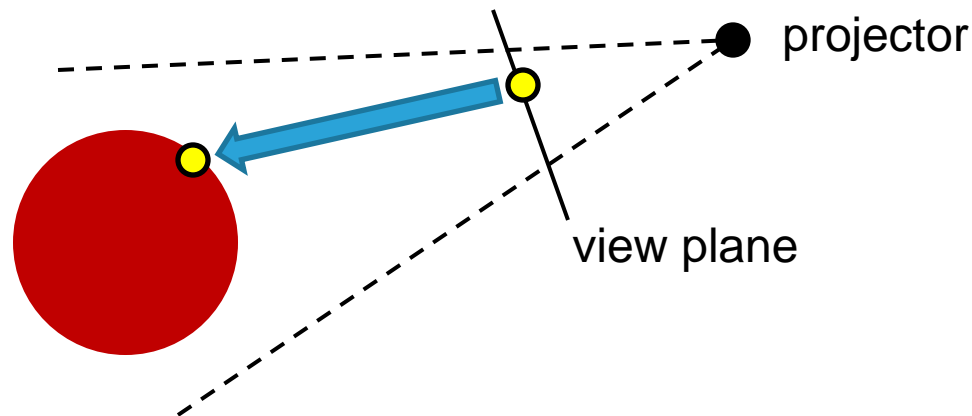


- Render scene from the eye's point of view ...
- ... and also transform the surface positions to **projector space** (for SM this would be **light space**)
 - ◆ i.e. determine, where the world space surface point pierces the projector's viewplane
 - "forward-projection" (scene-to-viewplane)



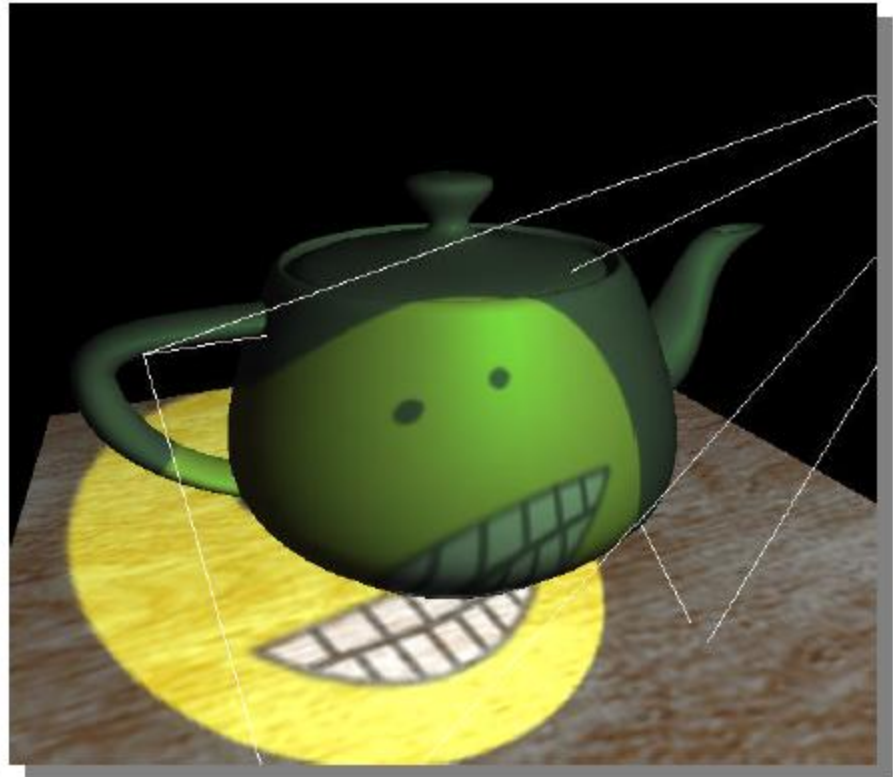
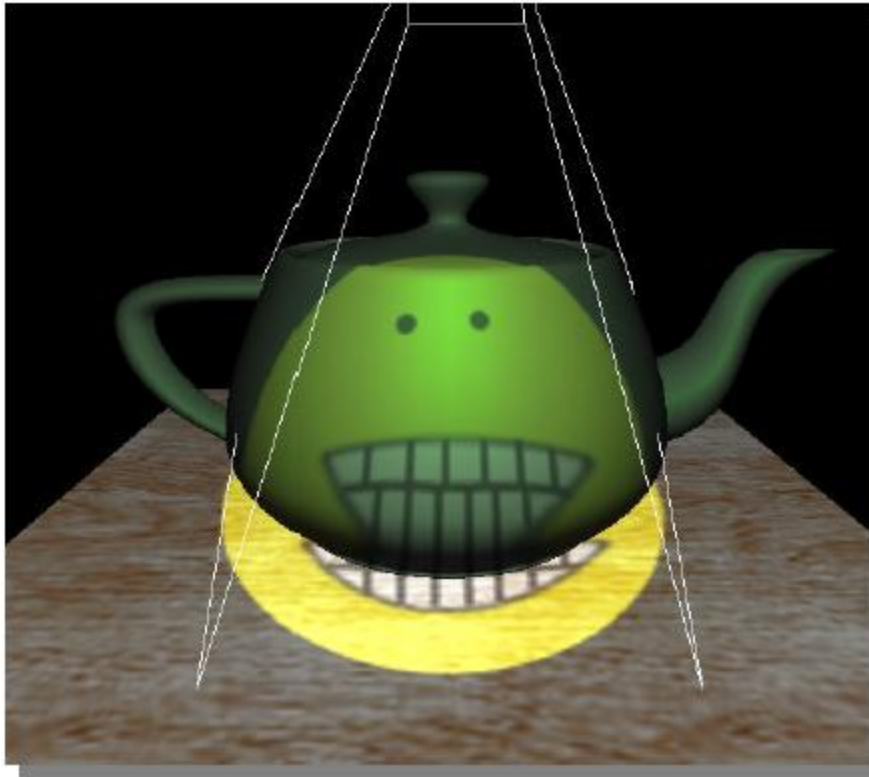
- ◆ the projector's viewplane (a texture) determines the fragment's color

- Another way to figure the mapping to "projector space":
 - ◆ to determine, where the world space surface point pierces the projector's viewplane is equivalent to the following question:
 - where does a point on the projector's viewplane intersect the scene along the projector's viewing rays (~raycasting)
 - ◆ "backward-projection" (viewplane-to-scene)



- ◆ maybe more natural to think about projective texturing this "inverse" way...

Projective Texturing - Example



http://developer.nvidia.com/object/Projective_Texture_Mapping.html

- www.opengl.org/registry
 - ◆ <http://www.opengl.org/registry/doc/glspec31undep.20090528.pdf>
 - ◆ <http://www.opengl.org/registry/doc/GLSLangSpec.Full.1.40.07.pdf>
- http://developer.nvidia.com/object/Projective_Texture_Mapping.html
- http://developer.nvidia.com/object/hwshadowmap_paper.html

- These slides are partly based on a fantastic shadow mapping tutorial written by Martin Knecht



Bloom Effect Glow Effect

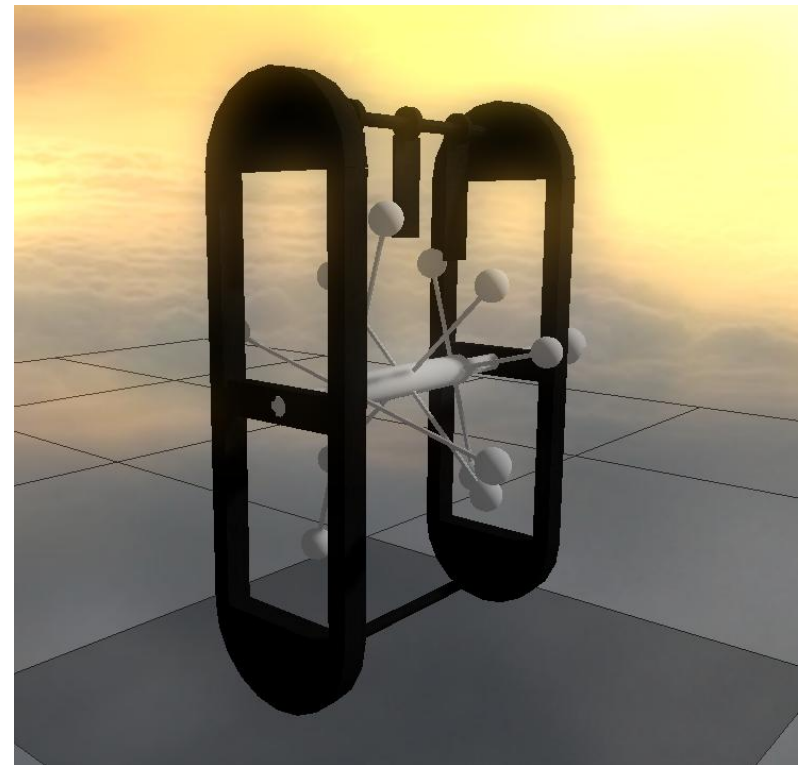
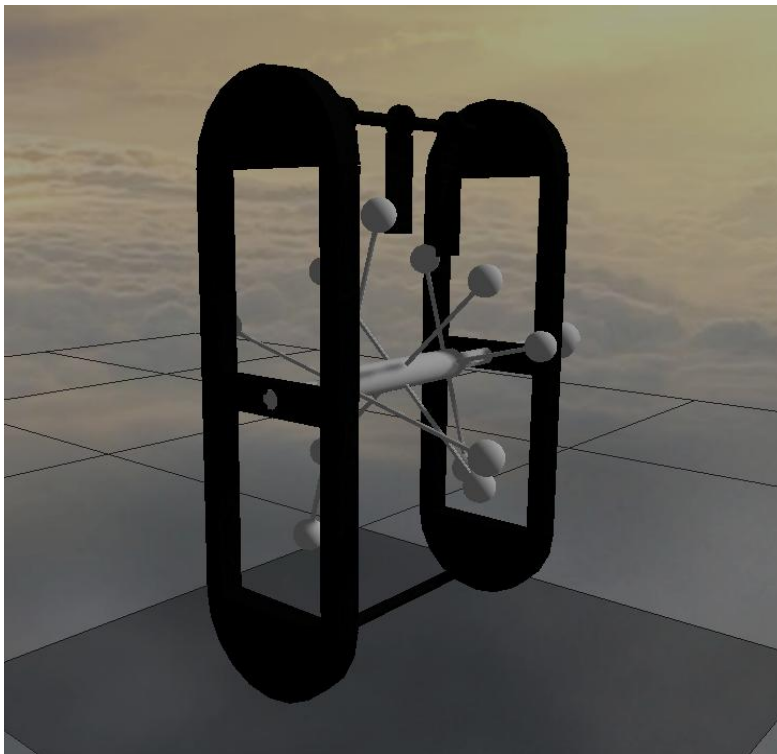
Reinhold Preiner

Institute of Computer Graphics and Algorithms

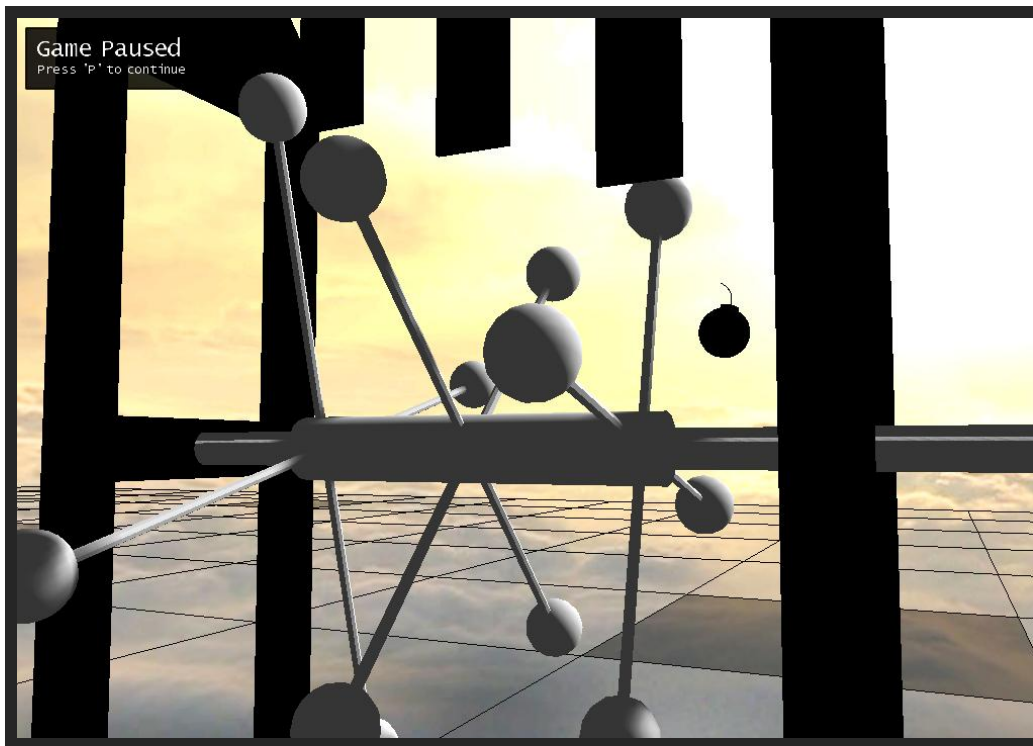
Vienna University of Technology



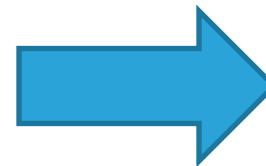
- Screen-space post effect
- Simulates imaging artifact of lenses
- Very bright light produces light bleeding



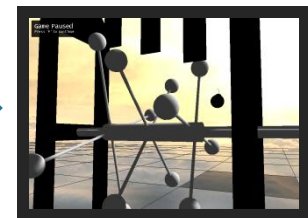
- 1) Render scene to texture S
- 2) Create down-sampled version S'
 - mip-mapping (e.g. 1/8 viewport size)



S



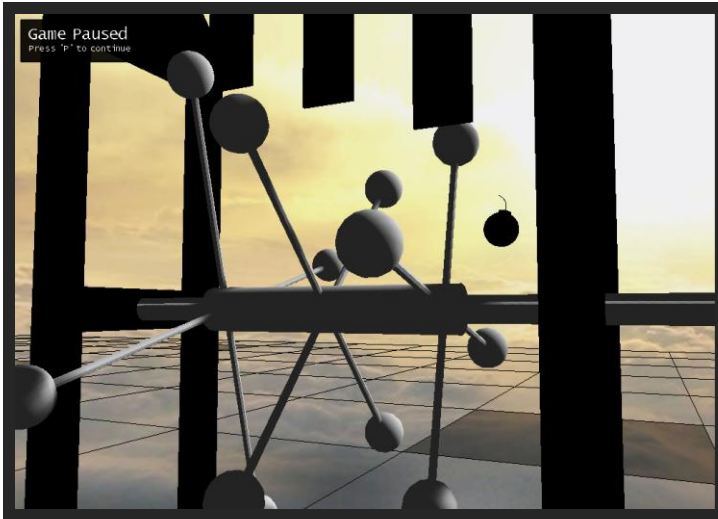
S'



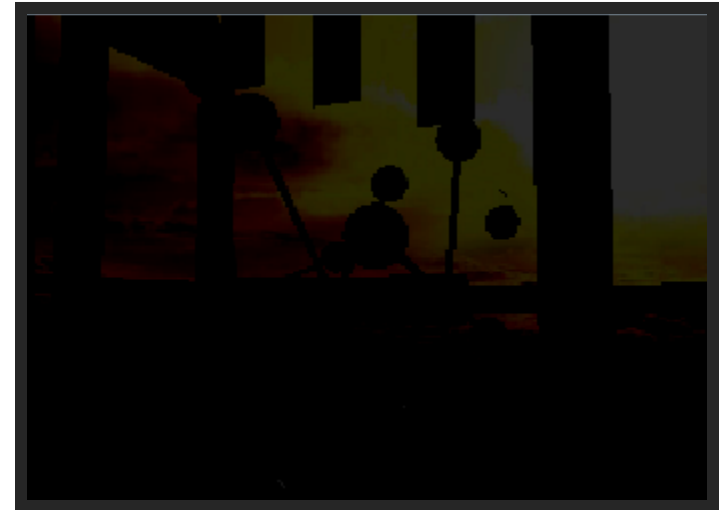
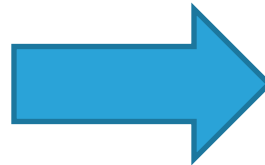
- Find some bright-pass RGB threshold T (e.g. 0.8) – could also continuously change over frames
- Create Bright-pass texture B' from S' , leaving only pixels with $RGB > T$
- Different operators



- $B' = \max(S' - T, 0)$



S'



B'

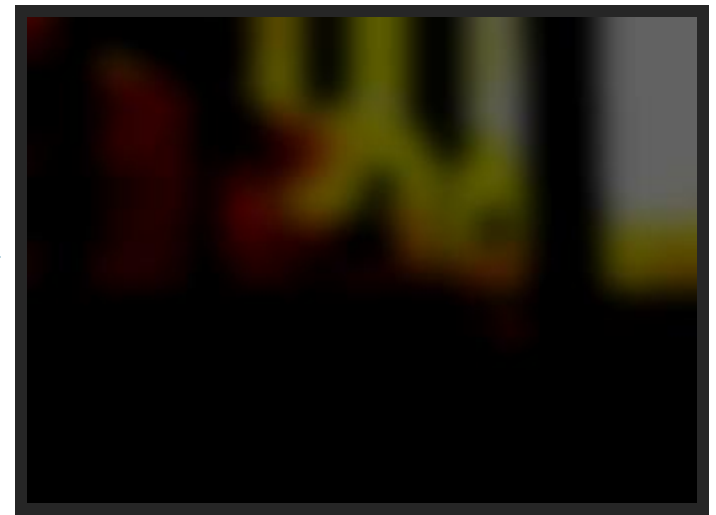
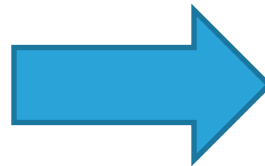
- Other operators possible:

$$B' = S' > T ? S' : 0;$$

(heavy bloom)



- 2D Gauss-Blur \rightarrow Can be decomposed into two 1D passes (x and y)
- Try different kernel sizes! (3, 5, 7, ...)



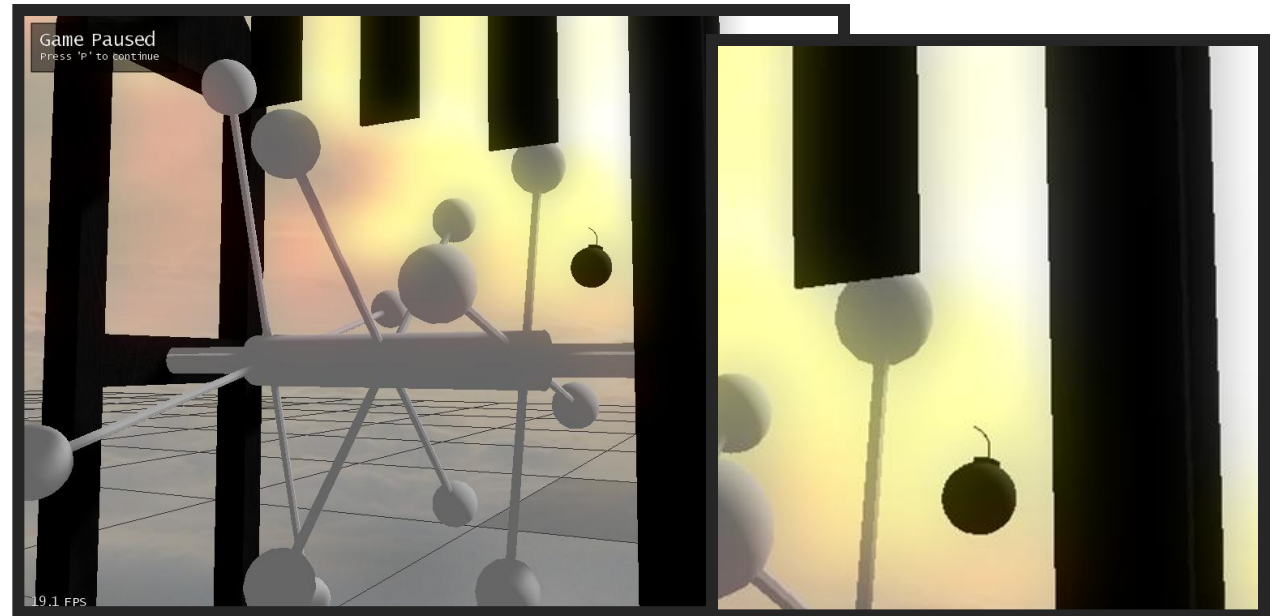
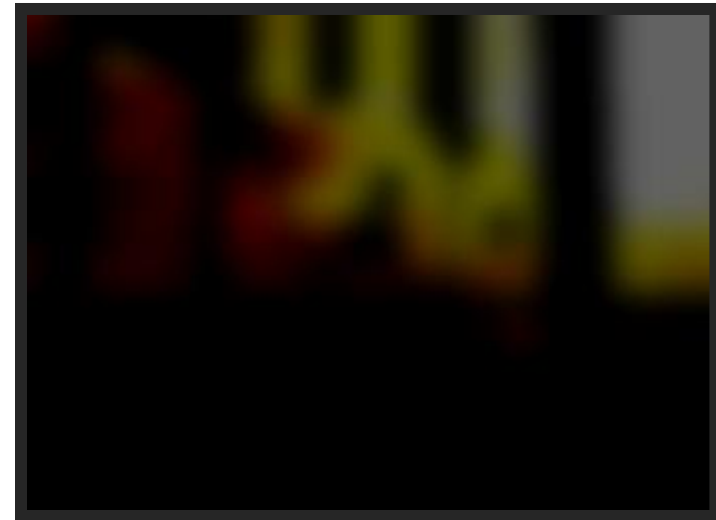
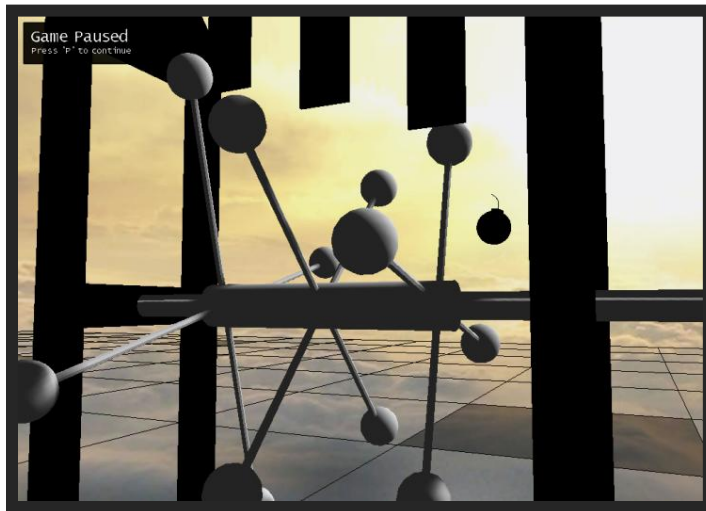
B'

G'

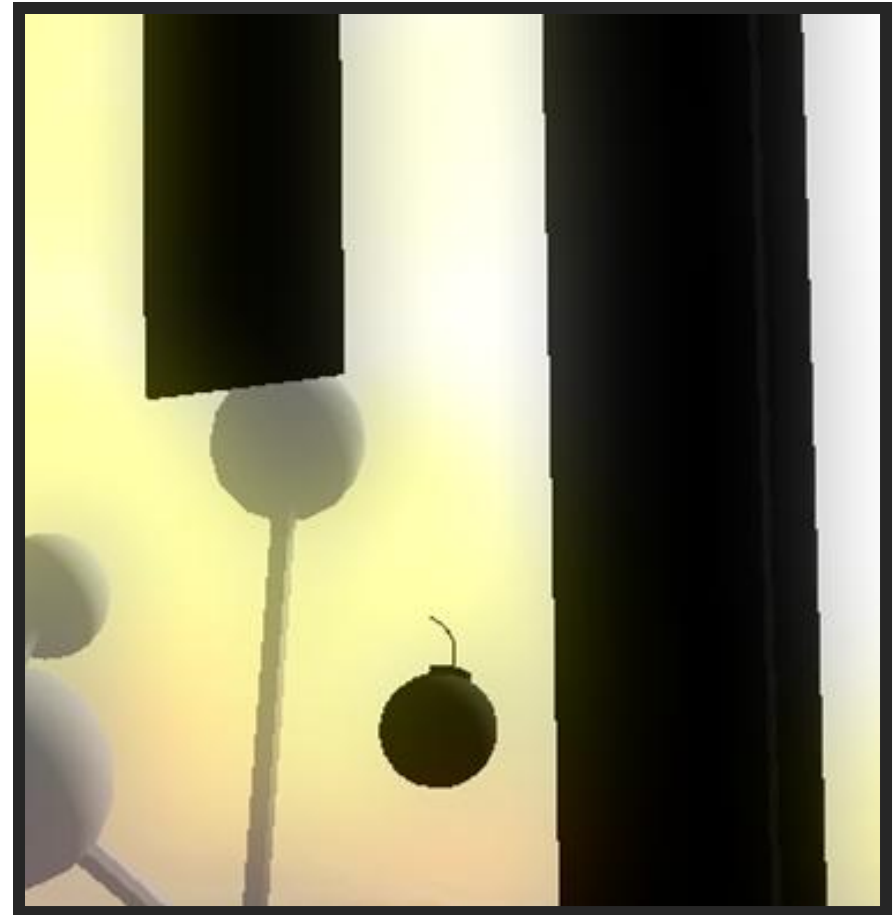
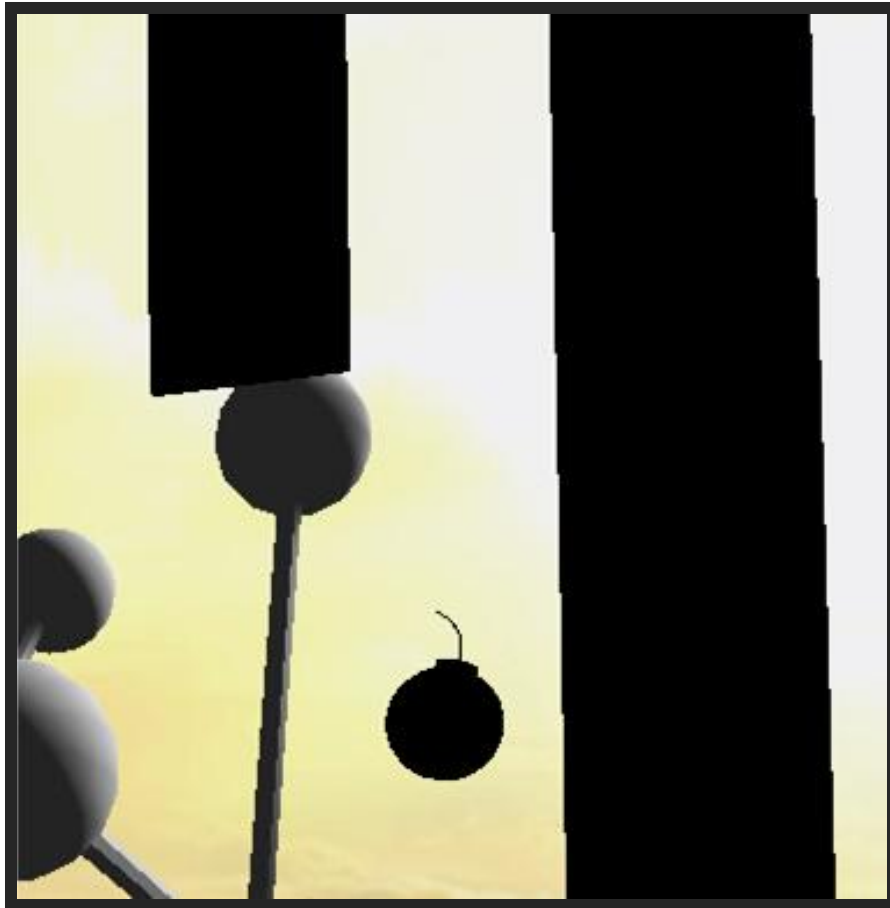
- Blur: down-sampled texture sufficient!



Final (Weighted) Blending



With and without Bloom



- Don't exaggerate it!
- Play with parameters
- Colored bloom vs. white bloom

- HDR Bloom
 - Bloom on HDR values ($rgb > 0$)
 - Threshold connected with iris effect and tonemapping possible
 - Non-linear bright-pass segmentation models



- [GL: prideout.net/archive/bloom/index.php](http://prideout.net/archive/bloom/index.php)
- HDR-Bloom: DirectX10 HDRLighting sample



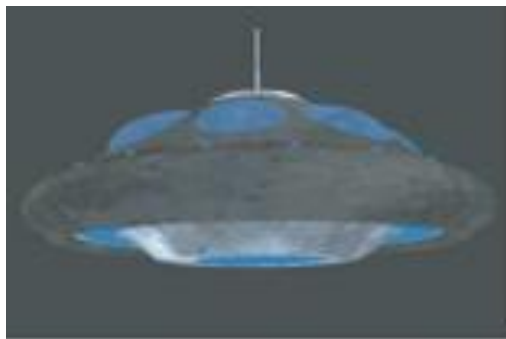
- Screen-space post effect
- Simulates glowing parts of objects (halos)
- Implementation similar to Bloom
- Surface texture based



Image: Tron (GPU Gems 1)



- Each object provides 4 channel textures:
 - ◆ RGB: diffuse color
 - ◆ Alpha: glow intensity (0 ... no glow, 1 ... full glow)
 - ◆ If alpha used for transparency \rightarrow 2 textures



(a) Texture RGB



(b) Texture Alpha



(c) Glow Sources = $RGB * A$

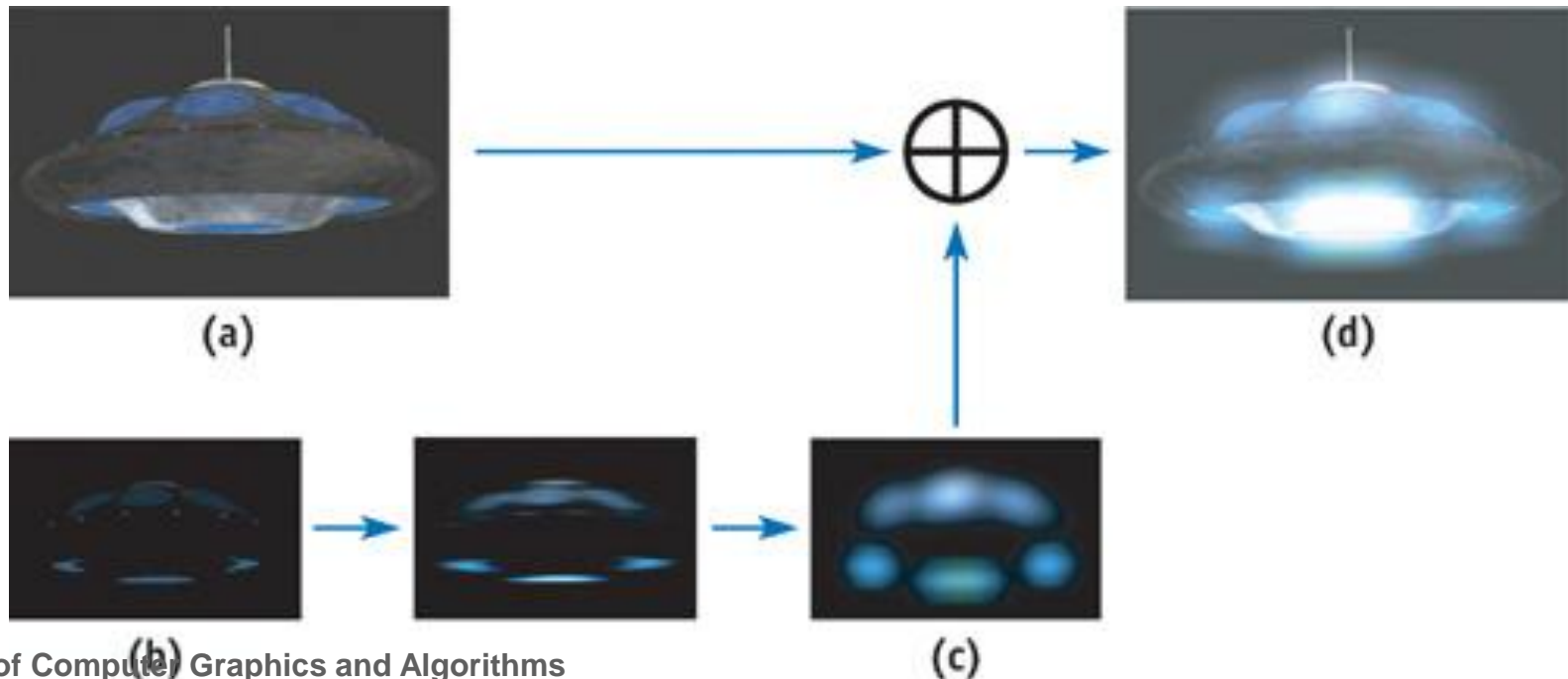
Image: GPU Gems 1

- (a) Render scene to texture (FBOs)
- (b) Create glow source texture from (a)

$$\text{GlowSource} = \text{RGB} * A$$

- (c) Blur glow source texture
- (d) Blend (c) with (a)

Image: GPU Gems 1



- Also blend the glow texture from the previous frame over the current one.
- Creates an afterglow when moving object or camera over several frames.



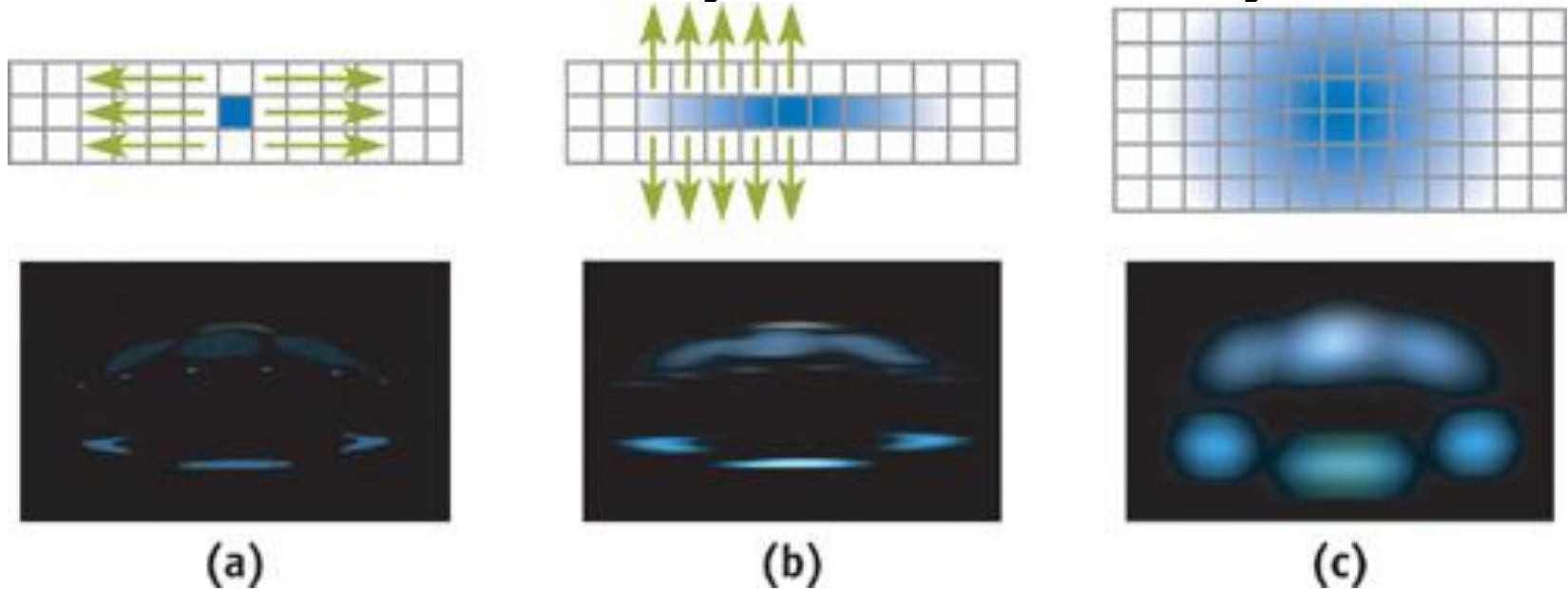
- RTF GPU Gems!
- Brief and good description on GPU Gems 1, Chapter 21.
- http://developer.nvidia.com/GPUGems/gpugems_ch21.html



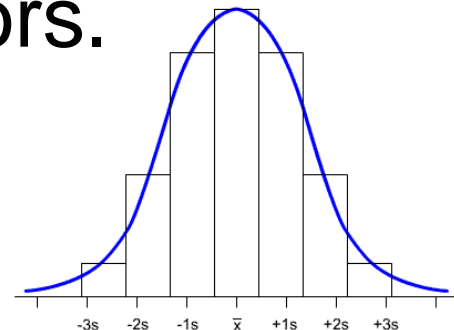
- FBOs
- Draw a fullscreen quad (4 vertices + texcoords):
 - ◆ $[(0,0), (1,0), (1,1), (0,1)]$
- Vertex shader: pass vertices to NDC
 - ◆ $\text{outPos} = \text{inPos} * 2 - 1$
- Normally no Depth Buffering
- Fragment shader: implement the pixel color transformation



- First blur horizontally, then vertically



- Per pixel: weighted sum of neighbors.
- 5x5-kernel weights:
(0.061, 0.242, 0.383, 0.242, 0.061)



- Blur → Local Averaging of neighbor values

- → Idea:

Blur with big kernel on big framebuffer

=

Blur with small kernel on small framebuffer

- Performance!



Character Animation Basics

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- Key frame
 - ◆ “snapshot” of the character at some moment
- Key frame based animation
 - ◆ Which parameter is interpolated ?
 - Vertex animation
 - ◆ All vertices are keyed (~“stored”), i.e. each key frame consist of all the vertices in the model
 - Skeletal animation
 - ◆ Only bones are keyed

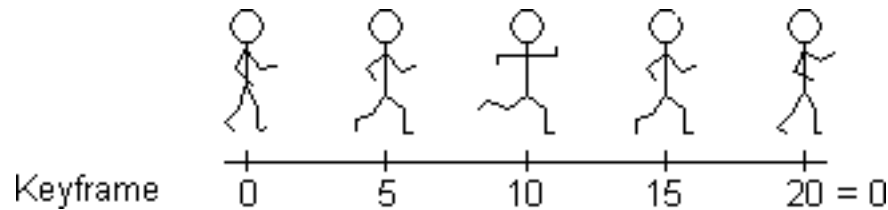


- 3D artist models “key” (important) frames only
 - ◆ **Key frames** are important **poses**
 - Character may be in particular state
 - ◆ standing, running, firing, dying etc.
 - Store several key frames for each state
 - usually up to 15 key frames / sec
 - if more are needed
 - ◆ use non-linear interpolation to reduce their number
 - ◆ consider another animation technique



■ Example:

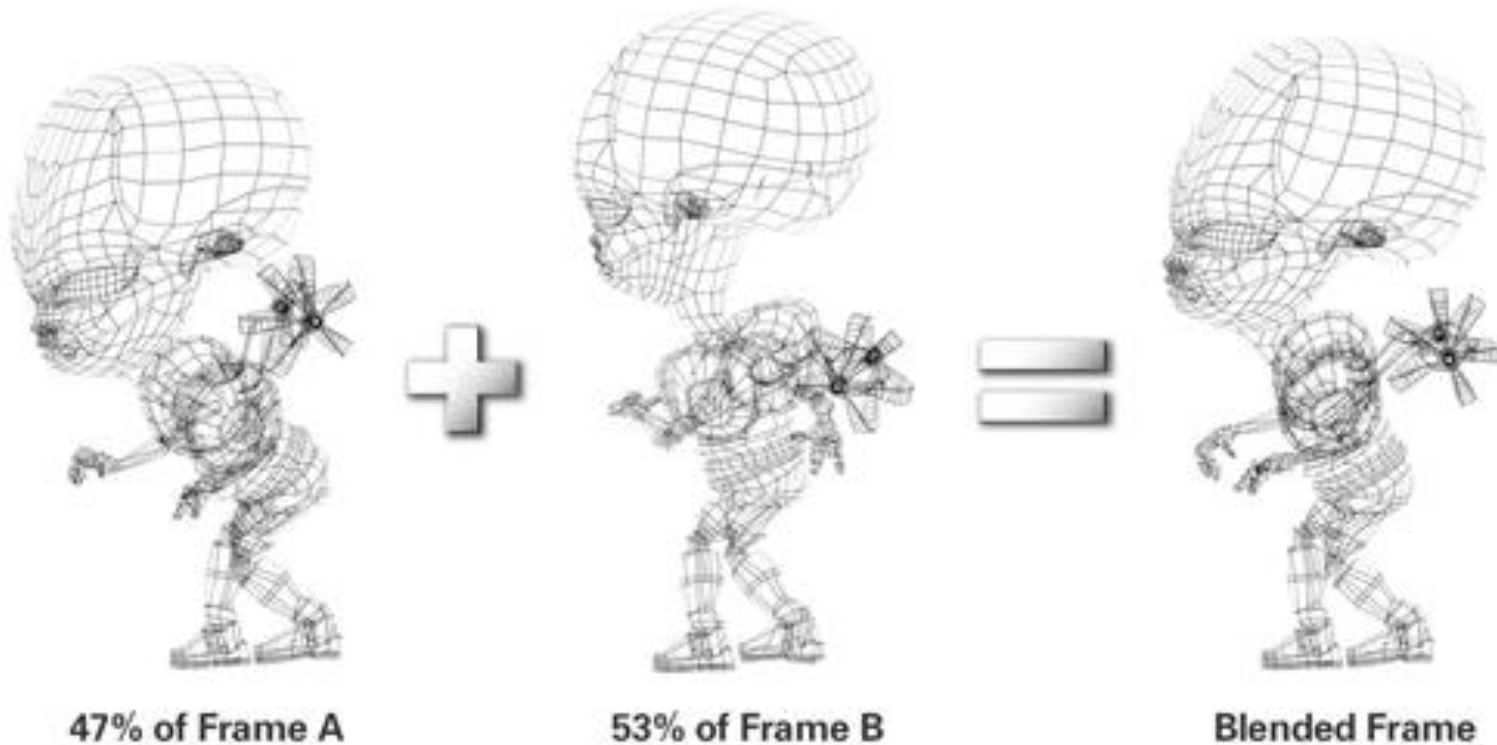
- ◆ Key frames for character in “Running” state



- Interpolate poses in between
 - ◆ Always 2 key frames involved
 - ◆ Several types of interpolation
 - linear, quadratic, ...
 - ◆ Linear interpolation fast, usually good enough
 - Blending factor w
 - blendedPos =
 $(1-w)*keyFrameA - w*keyFrameB$



- Linearly interpolated key frames:



- All key frames must have
 - ◆ Same number of vertices
 - ◆ Same vertex connectivity



- Basic steps:
 - ◆ Determine two “current” key frames A and B
 - ◆ Determine weighting factor $w \in [0,1]$
 - Whenever not $w \in [0,1]$ or character state transition (e.g., running=>dying)
 - ◆ determine new “start key frame”
 - ◆ determine new “end key frame”
 - ◆ map w back to $[0,1]$
 - ◆ Blend the corresponding key frames
 - Per-vertex
 - Don't forget the normal vectors!



■ Vertex Shader:

```
uniform float weightingFact;

void main()
{
    // use built-in “vertex attribute-slots” to pass
    // necessary data
    // alternatively, pass user-defined vertex attributes
    vec4 keyFrameA_vert = gl_Vertex;
    vec3 keyFrameA_norm = gl_Normal;

    vec4 keyFrameB_vert = gl_MultiTexCoord6;
    vec3 keyFrameB_norm = gl_MultiTexCoord7.xyz;

    ...
}
```



■ Vertex Shader:

...

```
// linear interpolation:  
// blendedPos_vert =  
//     (1.0 - weightingFact) * keyFrameA_vert +  
//     weightingFact * keyFrameB_vert
```

```
vec4 blendedPos_vert = mix(keyFrameA_vert,  
                           keyFrameB_vert,  
                           weightingFact);
```

```
vec3 blendedPos_norm = mix(keyFrameA_norm,  
                           keyFrameB_norm,  
                           weightingFact);
```

...



■ Vertex Shader:

...

```
// normalize blended normal and maybe  
// perform some light computation with the  
// normal (here, the normal is still in object  
// space!)
```

```
vec3 normal = normalize(blendedPos_norm);
```

```
// pass texture coordinates as always  
gl_TexCoord[0] = gl_MultiTexCoord0;
```

```
// transform blended vertex to homogeneous clip space  
gl_Position =  
    gl_ModelViewProjectionMatrix*blendedPos_vert;
```

```
}
```



- Advantages
 - ◆ Simple to implement
- Disadvantages
 - ◆ High storage requirements
 - ◆ No dynamic “arbitrary” poses



- Character model consists of
 - ◆ Single default pose
 - A polygonal mesh (made of **vertices**)
 - ...the “**skin**“
 - ◆ Several “**bones**“
 - Matrices that **translate** and **rotate** default pose’s vertices
 - Define coarse character structure
 - ◆ Like a stick-figure 😊



- Real life analogy:
 - ◆ As bones move, skin moves appropriately
 - ◆ But: influence of bones locally bounded
 - E.g., moving left arm does not affect right leg

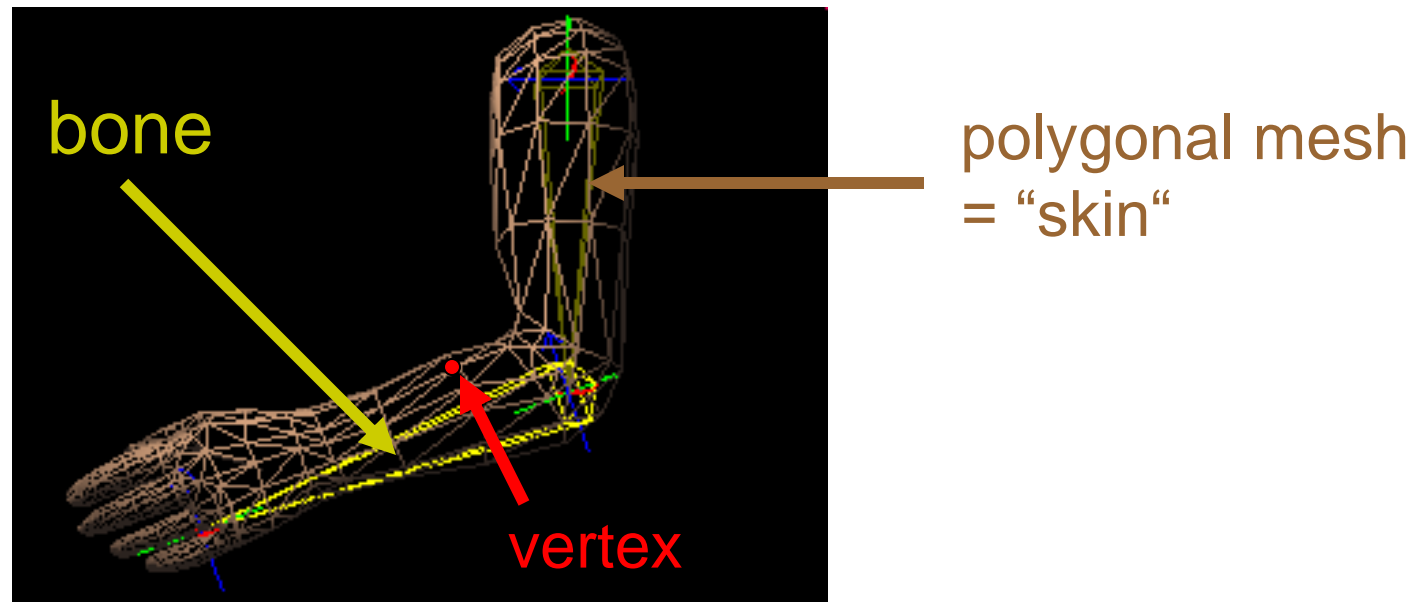
■ Bone set

- ◆ Matrices that actually influence a vertex
- ◆ Typically contains ≤ 4 matrices
- ◆ Each matrix M_i has associated weight w_i

$$w_i \geq 0, \quad \sum_{w_i \in boneSet} w_i = 1$$



- Matrix-weight determines how much it influences a vertex's position



At this vertex, 3 matrices in bone set with corresponding weights:

- 60% forearm matrix
- 30% elbow matrix
- 10% upper arm matrix

- Basic steps during rendering:
 - ◆ Transform each vertex by every matrix in its bone set
 - ◆ Scale each transformed vertex by the associated matrix weighting factor
 - ◆ Sum results => **skinned vertex position**
- Special case:
 - ◆ For default pose all the bone set's matrices are identity matrices



- How to treat normals?
 - ◆ Basically the same steps as for vertices
 - ◆ **But:** transform normals by the inverse transpose matrix ${}^t\mathbf{M}^{-1}$ rather than the matrix \mathbf{M} itself (see [2] for details)
 - If matrices contain rotations and translations only, $\mathbf{M} = {}^t\mathbf{M}^{-1}$
 - ◆ Normalize the blended normal



■ Advantages

- ◆ Storage quite efficient
 - Only **one** mesh (+ several matrices)
 - Huge savings for high-poly models
 - ◆ Most probably still “only a few” bones
- ◆ Create novel poses dynamically!
 - Supports blending several “animation-states”
 - ◆ Running + Firing + Look upwards + ...
 - Rag doll physics when killed by a shot etc.
- ◆ Inverse Kinematics and Constraints can produce quite realistic results



■ Disadvantages

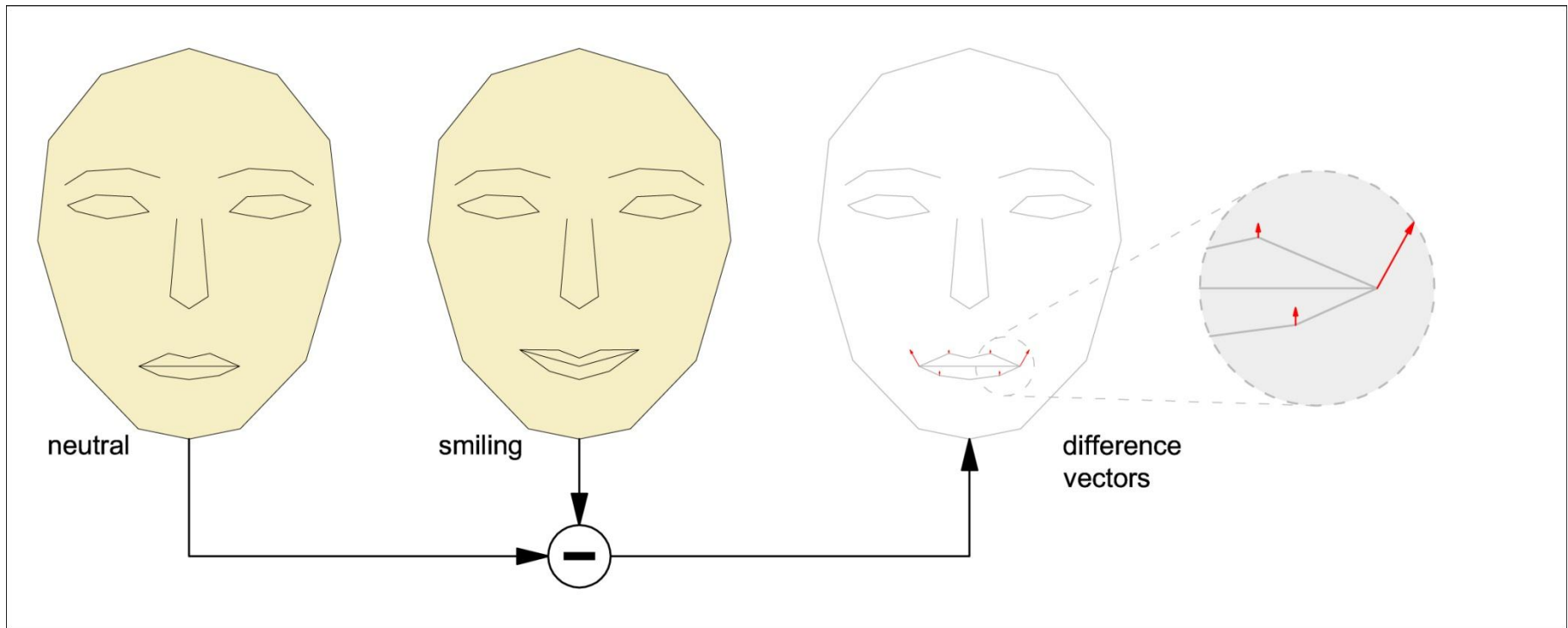
- ◆ Matrices hierarchically linked!
- ◆ each matrix needs to be multiplied by its predecessors in the correct order before applying it to the vertex
- ◆ for each bone (matrix) in the bone set the vertex has to be transformed into the bone space before applying the influence of said bone on the vertex
- ◆ vertex blending occurs in object space, so the reverse transformation is also necessary
- ◆ animation needs to be developed in a 3D-modeling software (Maya, 3ds Max, Blender, etc.)



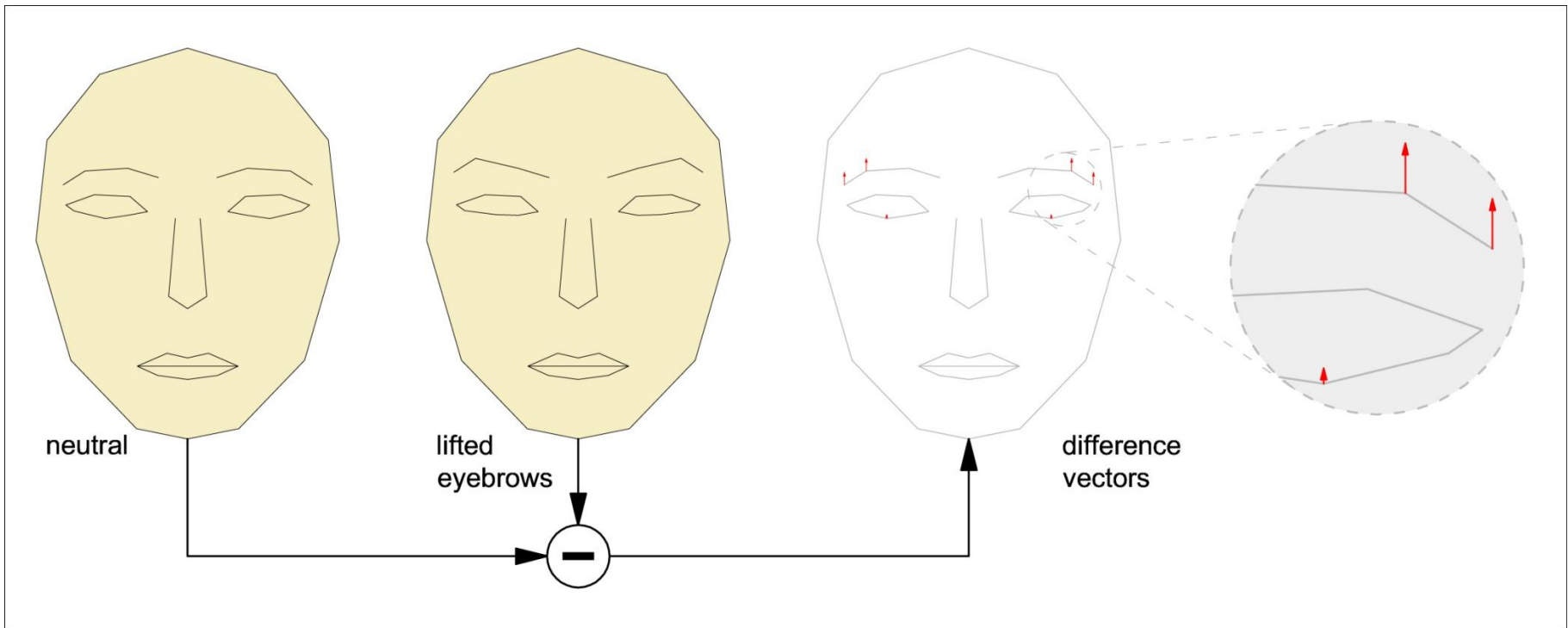
- Morph Target
 - ◆ a „snapshot“ of a character **not at a particular time** but at **a particular pose**
 - ◆ applied when
 - dynamic „arbitrary“ poses are needed
 - animation is too fine-grained for the bone + skin approach (i.e. facial expressions)
- Animation with Morph Targets
 - ◆ Which parameters are interpolated?
 - Vertex animation: for each morph target the **difference vector per vertex** is stored



- a neutral model N and $k \geq 1$ different poses $P_1 \dots P_k$
- in the preprocessing stage the difference models are computed:
 - ◆ $D_i = P_i - N, i = 1 \dots k.$

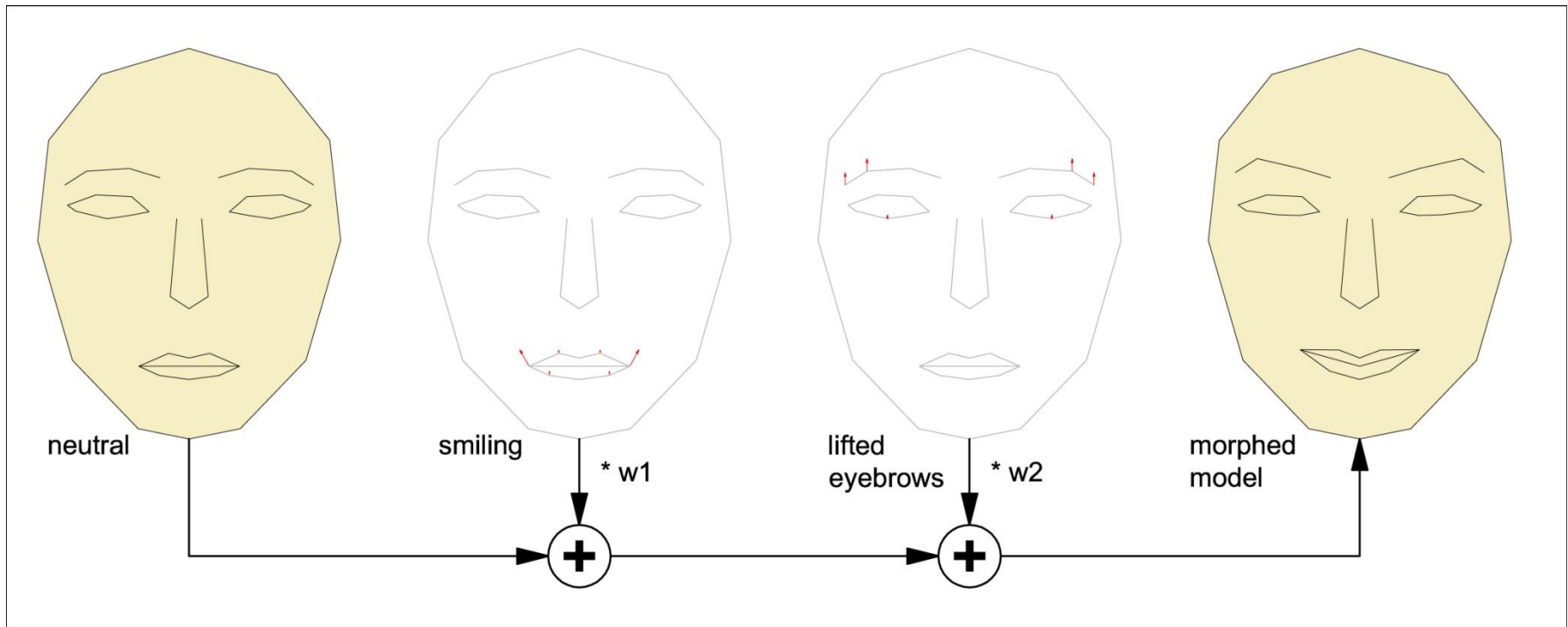


- a neutral model N and $k \geq 1$ different poses $P_1 \dots P_k$
- in the preprocessing stage the difference models are computed:
 - ◆ $D_i = P_i - N, i = 1 \dots k.$



- a neutral model N and $k \geq 1$ different poses $D_1 \dots D_k$
- to obtain a morphed model compute:

$$\blacklozenge M = N + \sum_{i=1}^k w_i D_i.$$



■ Advantages

- ◆ fine-grained animation does not result in complex implementation
- ◆ the weights w_i can be:
 - ≤ 0 (inverted pose) or
 - ≥ 1 (exaggerated pose)

■ Disadvantages

- ◆ the neutral model N and the different poses $P_1 \dots P_k$ need :
 - the same number of vertices
 - the same vertex connectivity



- Example (see [7]):



Pose Space Deformation



Skeleton Space Deformation



- Combines Skeletal Animation and Morph Targets (each is a dimension in the Pose Space)
- Basic steps:
 - ◆ apply skeletal animation in **skeleton space**
 - ◆ for each affected vertex compute deviation from relevant poses in **pose space** (a falloff ensures that only the most „relevant“ poses are considered)
 - ◆ interpolate deviation and apply to vertex
- For more information see [7].



- [1] The CG Tutorial: The Definitive Guide to Programmable Real-Time Graphics
http://http.developer.nvidia.com/CgTutorial/cg_tutorial_chapter06.html
- [2] <http://www.glprogramming.com/red/appendixf.html>
- [3] <http://www.darwin3d.com/conf/igdn0398/index.htm>
- [4] <http://tfc.duke.free.fr/old/models/md2.htm>
- [5] OpenGL Shading Language, Randi J. Rost, 3rd Edition, Chapter 16 Animation
- [6] http://http.developer.nvidia.com/GPUGems/gpugems_ch04.html
- [7] Lewis, J.P., Matt Cordner, Nickson Fong, „Pose Space Deformation: A Unified Approach to Shape Interpolation and Skeleton-Driven Deformation“, Computer Graphics (SIGGRAPH 2000 Proceedings), pp. 165-172, July 2000.



- Peter Houska
- Martin Knecht

