

Texturing

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Why Texturing?

- Idea: enhance visual appearance of plain surfaces by applying fine structured details



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1

Why Texturing?

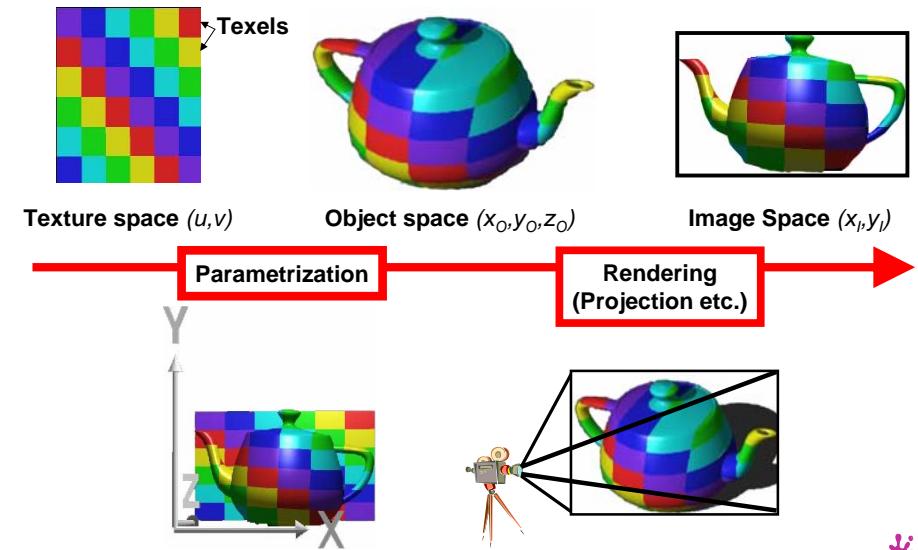
- Also possible: model very complex objects just by using simple textured geometry



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2

Texturing: General Approach



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3

- A texture is a **function**:
 - ◆ *Algebraic*: fast to evaluate but limited variety
 - ◆ *Sampled*: most common method
 - Raster images that are taken with a digital camera, scanned or synthesized
- Textures can be defined:
 - ◆ In 3D object space: "*solid texturing*"
 - ◆ On the 2D object surface: "*texture mapping*"

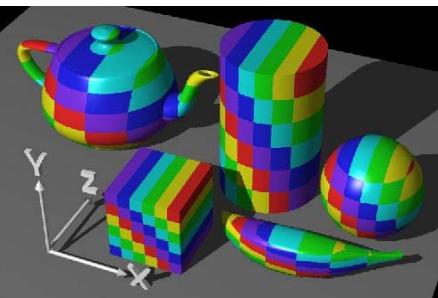
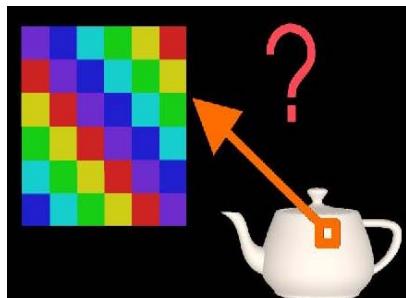
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4



Solid Texturing: Parametrization

- **2D** texture
 - ◆ Projection of 2D data
 - ◆ Many possibilities for definition



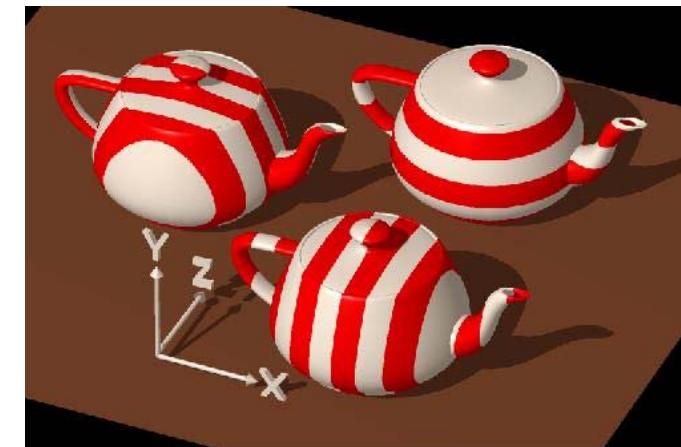
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6



Solid Texturing: Parametrization

- **1D** texture: parameter can have arbitrary domain (along one axis, incident angle, etc.)



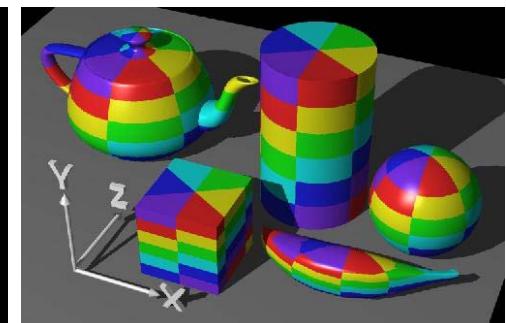
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5



Solid Texturing: Parametrization

- Other 2D texture: *cylindrical parametrization*
 - ◆ Depending on cylindrical coordinates of each point



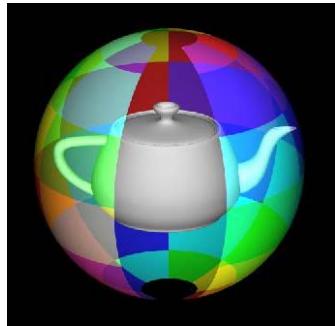
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7

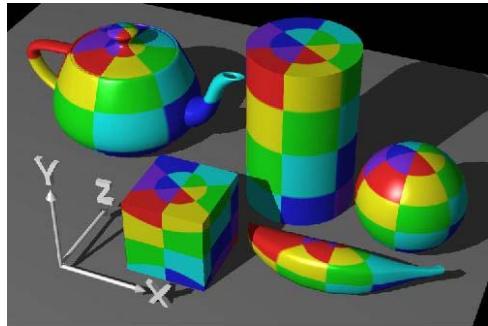


- Other 2D texture: spherical parametrization

- ◆ Depending on spherical coordinates of each point



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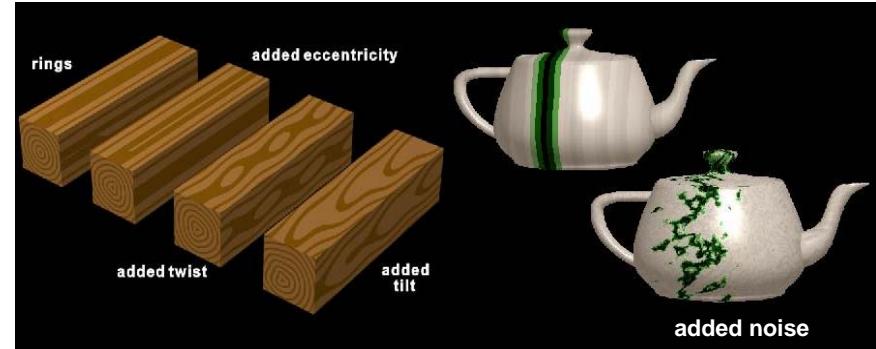


8



- 3D texture: $T(u,v,w)$

- ◆ $0 \leq x^2+y^2 < 1 \Rightarrow$ light brown
- $1 \leq x^2+y^2 < 2 \Rightarrow$ dark brown
- $2 \leq x^2+y^2 < 3 \Rightarrow$ yellow etc.



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9



Peachey, SIGGRAPH85

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10

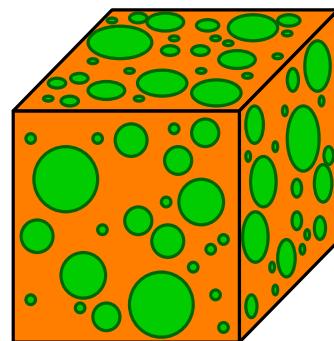


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11



- "Bombing": special solid texture function
 - ◆ Random sized spheres define areas of different material (like cheese holes)
 - ◆ Precalculation of position and radius of all spheres
 - ◆ Fast rendering



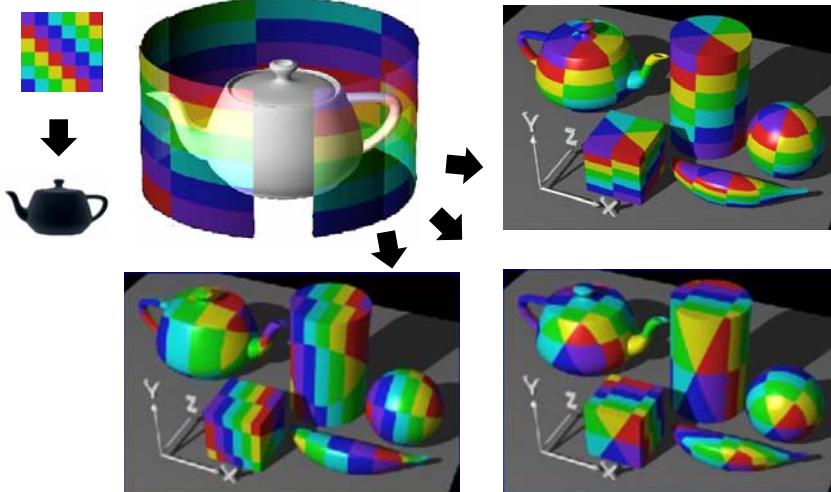
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12



Texture Mapping: Parametrization

- Difficulty: how to minimize texture distortions?



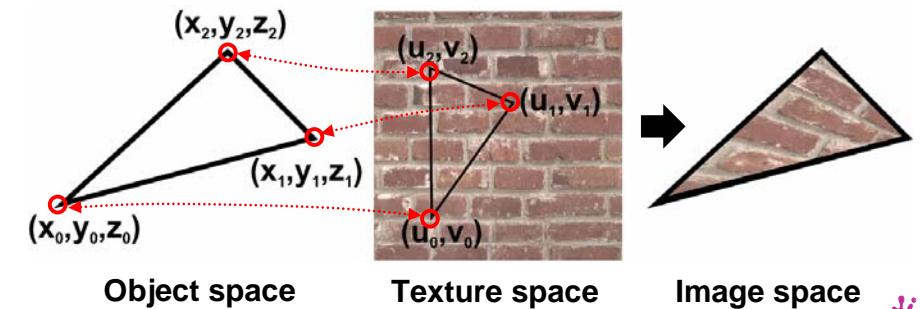
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14



Texture Mapping

- Parametrization per vertex
 - ◆ Apply (u, v) texture coordinates to every vertex
- At runtime, ***(bi)linearly interpolate*** between these coordinates during rasterization



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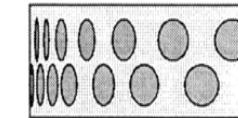
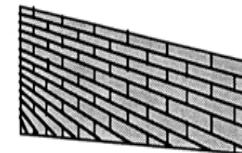
Image space



Texture Mapping: Parametrization

- ***Texture gradient***

- ◆ Defines the amount of texture pattern distortion due to the spatial position in 3D-space
 - Size / Shape / Density



- ***Angular*** and ***area distortions*** can not be minimized at the same time! (except for some special cases)

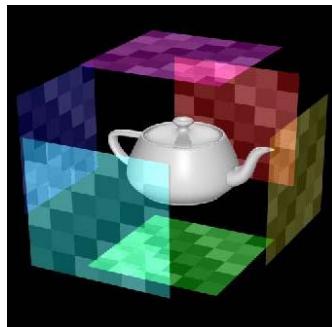
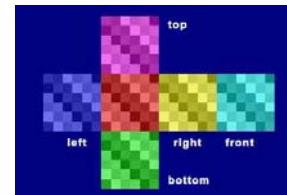
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15

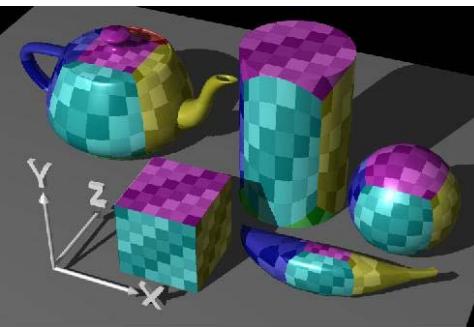


Texture Mapping: Parametrization

- Example: box parametrization



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16



Texture Mapping vs. Solid Texturing



Solid texturing



Texture mapping

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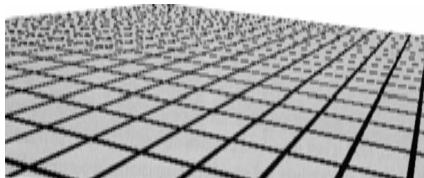
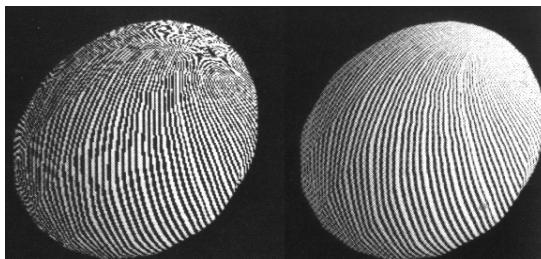
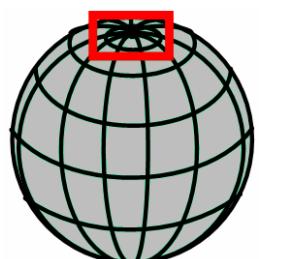
17



Texturing: Rendering

- Problem: aliasing

- ◆ One pixel in image space covers many texels

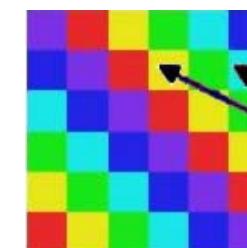


18



Aliasing

- Caused by *undersampling*: texture information is lost



Texture space

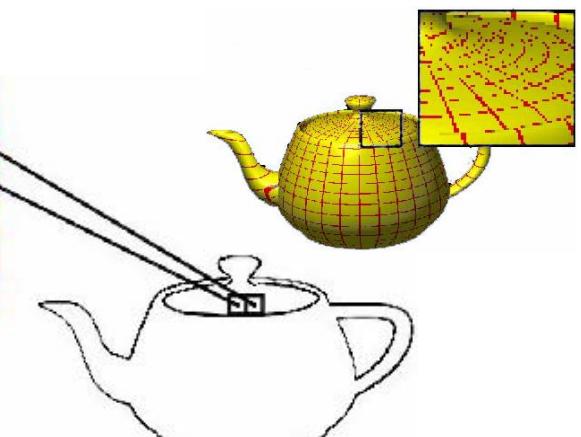


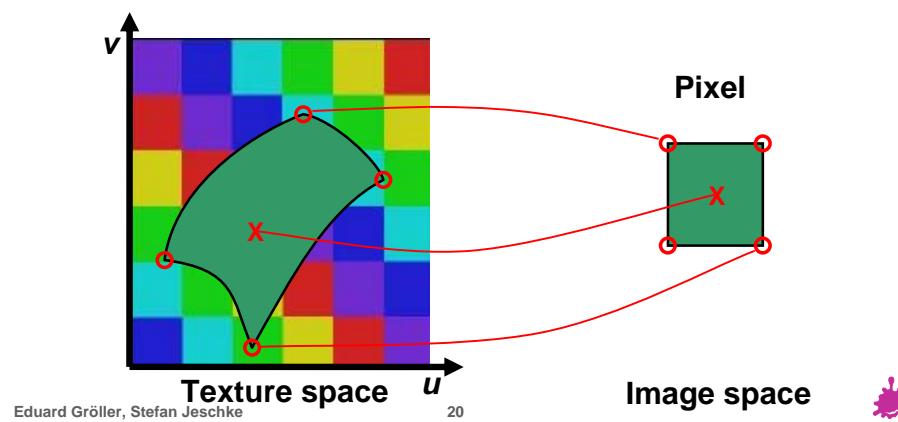
Image space

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19



- A good pixel value is the weighted mean of the pixel area projected into texture space
 - Calculation at *runtime* or in a *preprocess*

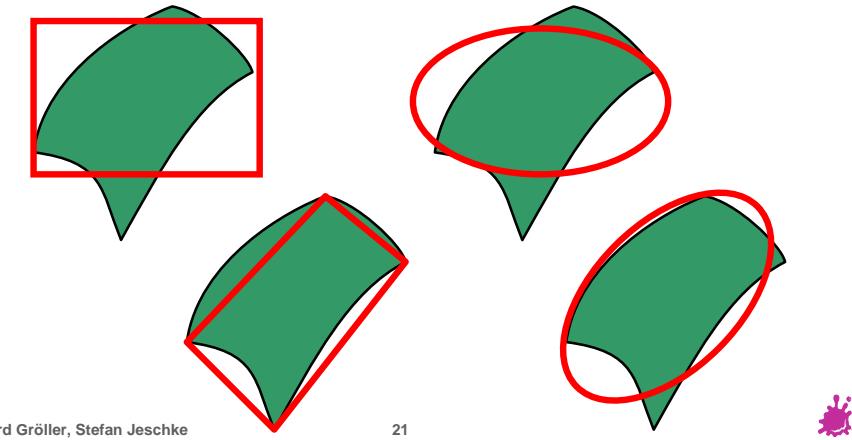


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20



- Calculation of the weighted mean at runtime (called "*direct convolution*")
 - Often used approximations



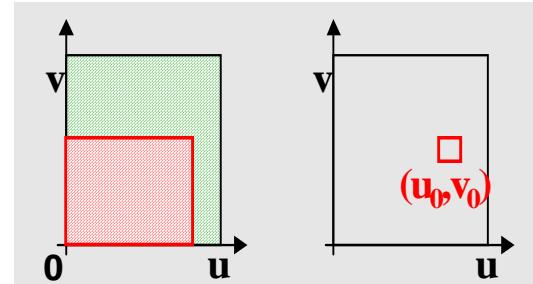
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21



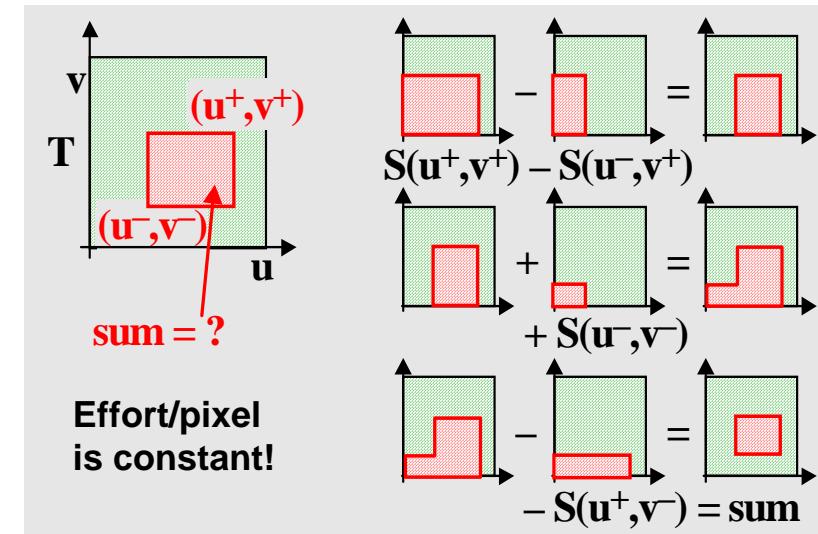
- Calculation of the weighted mean in a *preprocess* (called "*prefiltering*")
 - Summed area table*
 - Mip Mapping* (+ optional *anisotropic filtering*)
- Summed area table S
 - precalculation of rectangle sums for each pixel

$$S(u_0, v_0) = \sum_{\substack{u \leq u_0 \\ v \leq v_0}} T(u, v)$$



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22



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23



Anti-Aliasing: Example (Summed Area T.)

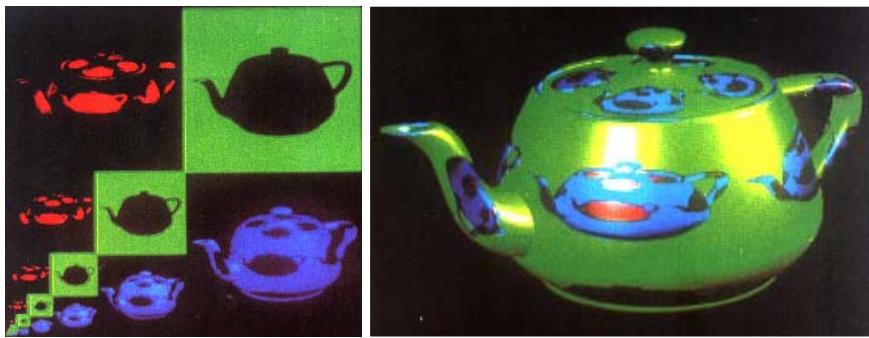


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24



Anti-Aliasing: Example (Mip Mapping)



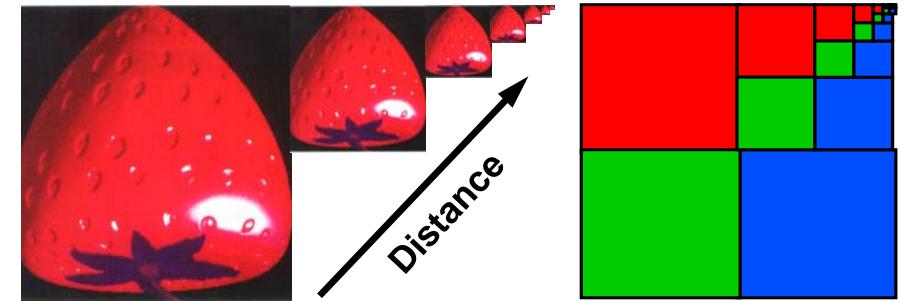
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26



Anti-Aliasing: MIP Mapping

- MIP Mapping ("Multum In Parvo")
 - ◆ Texture size is reduced by factors of 2 (*downsampling* = "much info on a small area")
 - ◆ Simple (4 pixel average) and memory efficient
 - ◆ Last image is only ONE texel

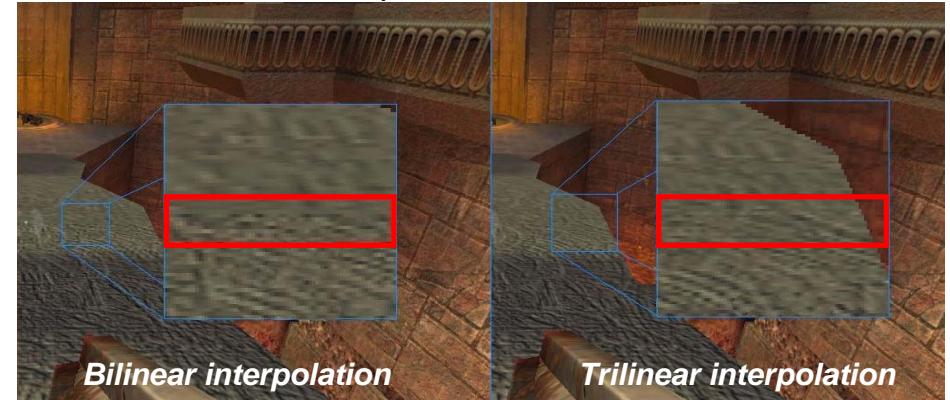
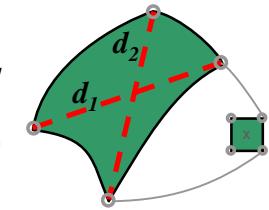


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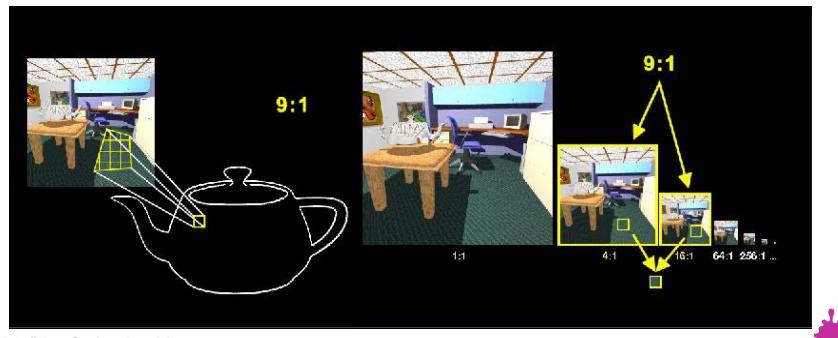
Anti-Aliasing: MIP Mapping

- MIP Mapping Algorithm
- $D := \text{ld}(\max(d_1, d_2))$
- $T_0 := \text{value from texture } D_0 = \text{trunc}(D)$
 - ◆ Use bilinear interpolation



- Trilinear interpolation:

- ◆ $T_1 :=$ value from texture $D_1 = D_0 + 1$ (bilin.interpolation)
- ◆ Pixel value := $(D_1 - D) \cdot T_0 + (D - D_0) \cdot T_1$
 - Linear interpolation between successive MIP Maps
- ◆ Avoids "Mip banding" (but doubles texture lookups)



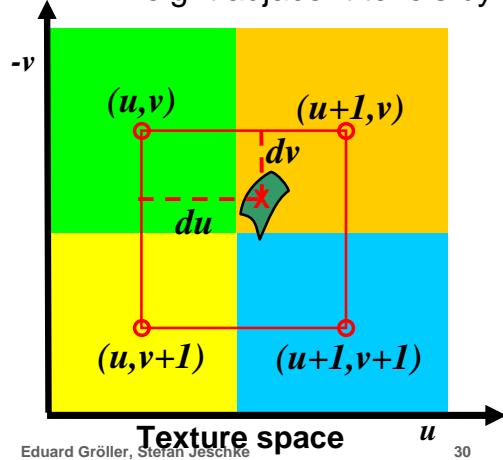
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28



- Bilinear reconstruction for texture magnification ($D < 0$) ("upsampling")

- ◆ Weight adjacent texels by distance to pixel position



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$$\begin{aligned}
 T(u+du, v+dv) \\
 &= du \cdot dv \cdot T(u+1, v+1) \\
 &+ du \cdot (1-dv) \cdot T(u+1, v) \\
 &+ (1-du) \cdot dv \cdot T(u, v+1) \\
 &+ (1-du) \cdot (1-dv) \cdot T(u, v)
 \end{aligned}$$



30

- Other example for bilinear vs. trilinear filtering



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29



Original image



Nearest neighbor

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Bilinear filtering



31



No mip-mapping

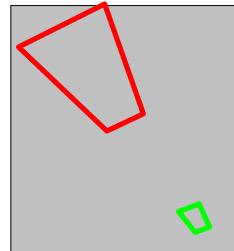
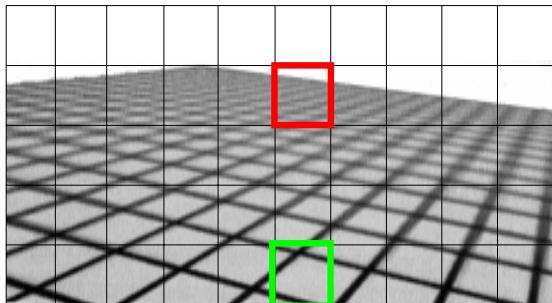
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32



Anti-Aliasing: Anisotropic Filtering

- Anisotropic Filtering
 - ◆ View dependent filter kernel
 - ◆ Implementation: *summed area table* (see above), "*RIP Mapping*", "*footprint assembly*"



Texture space



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34



simple
mip-mapping

ray
differentials

+ anisotropic
filtering

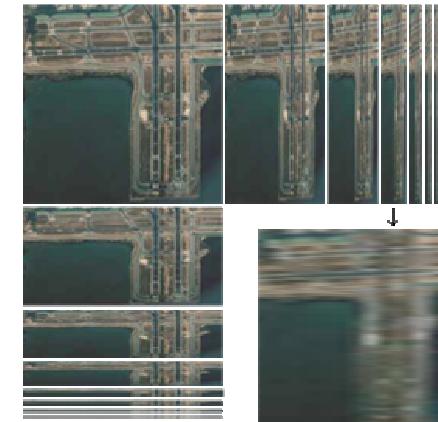
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33



Anti-Aliasing: Anisotropic Filtering

- "*RIP Mapping*": like MIP Maps but half resolution in x and y direction *separately*
 - ◆ Fast, but needs more memory than MIP Mapping



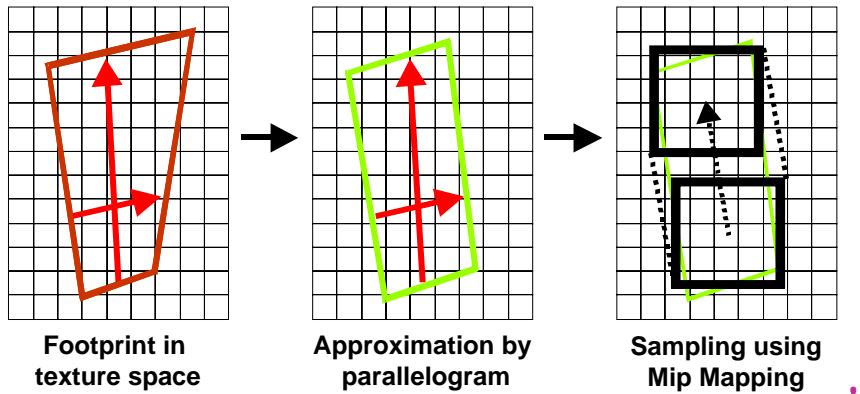
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35



- "Footprint assembly"

- ◆ Approximate pixel footprint by parallelogram
- ◆ Sample along the parallelogram using MIP mapping

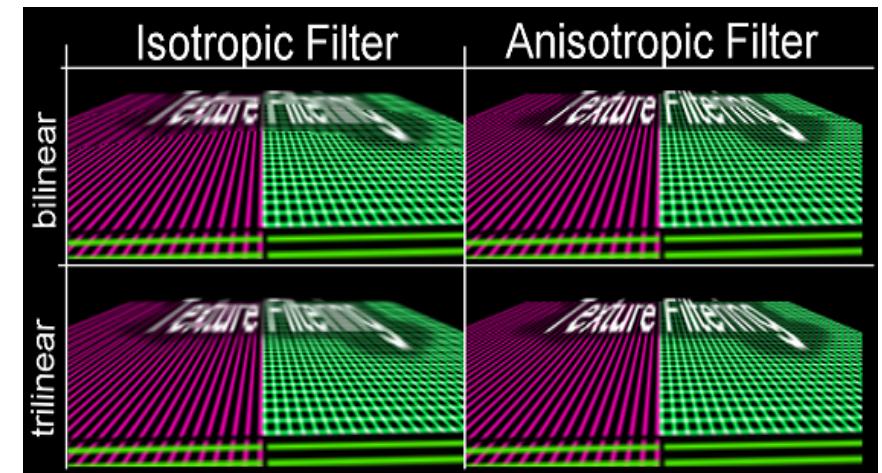


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36



- Example

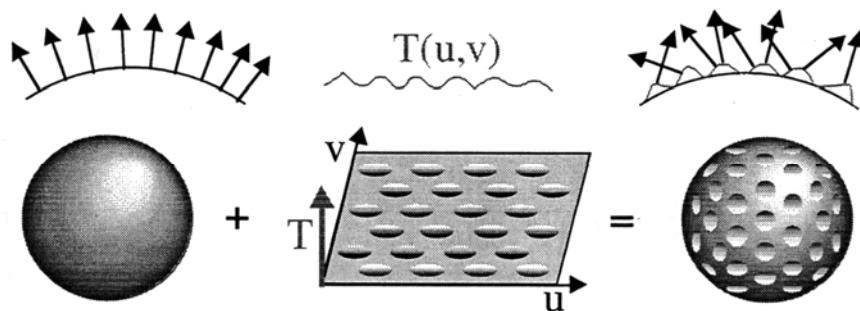


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37

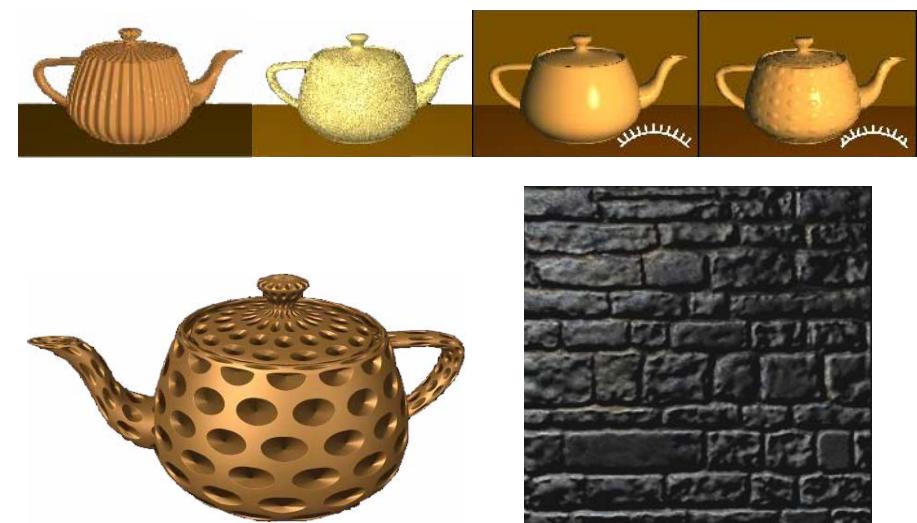


- Preprocess: compute normal vectors from height field
- Runtime: use computed normals for illumination



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38

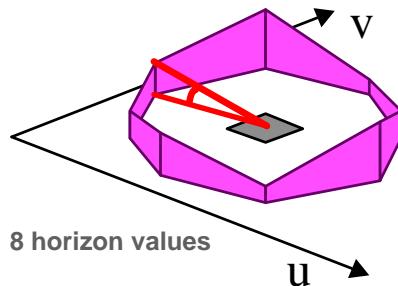


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39



- Improve bump mapping with (local) shadows
- Preprocess: compute n horizon values per texel
- Runtime:
 - ◆ Interpolate horizon values
 - ◆ Shadow accordingly

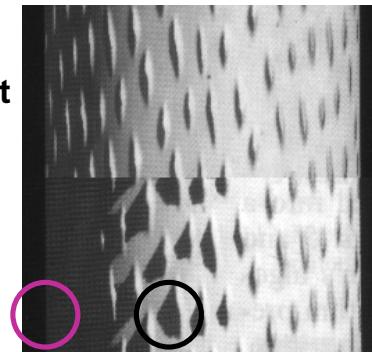


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40

without



with



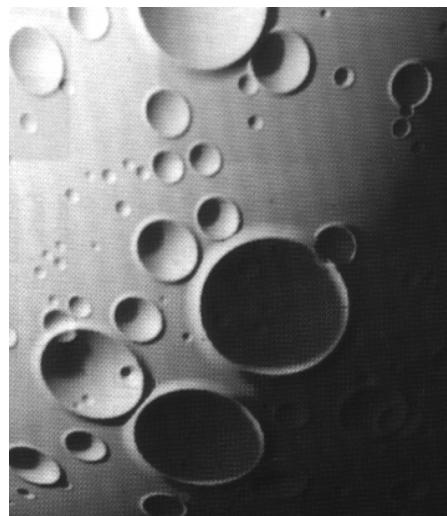
Shadows from bumps

No light on rear side of the object

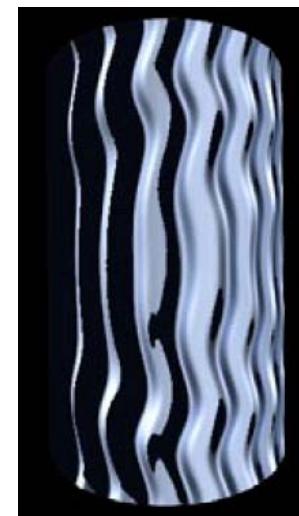


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41



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42

- Parallax: apparent movement of close objects in front of further objects
 - ◆ Preprocess: calculate "texture coordinate shifts"
 - ◆ Runtime: "crd. shifts" alter the texture lookup position
 - Problem: occlusions cannot be modelled



Bump mapping

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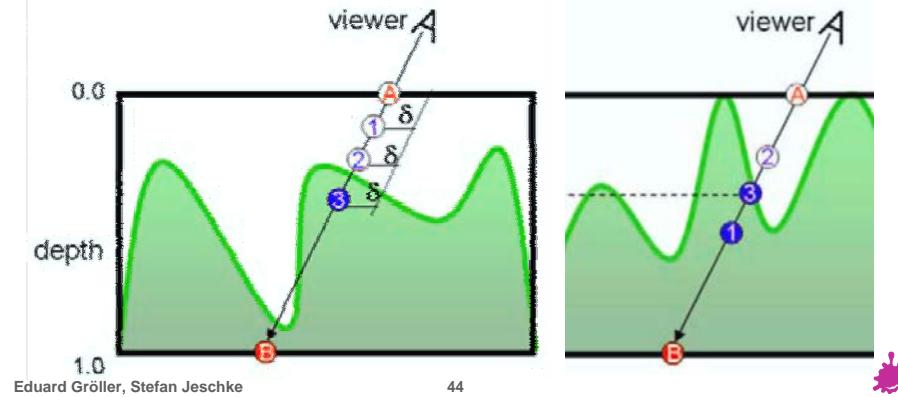


Parallax + Bump mapping



43

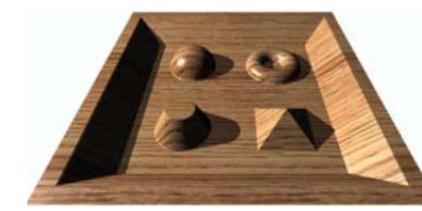
- At runtime: perform ray casting in the pixel shader
 - ◆ Calculate entry (A) and exit point (B)
 - ◆ March along ray until intersection with height field is found
 - ◆ Binary search to refine the intersection position



Texture mapping



Parallax mapping



Relief mapping



45



- [http://www.siggraph.org/education/materials/
HyperGraph/mapping/r_wolfe/r_wolfe_mapping_2.htm](http://www.siggraph.org/education/materials/HyperGraph/mapping/r_wolfe/r_wolfe_mapping_2.htm)
- <http://www.3dcenter.org/artikel/grafikfilter/index3.php>